4-Day Hands-on Workshop on:

Python for Scientific Computing and TensorFlow for Artificial Intelligence

By Dr Stephen Lynch NATIONAL TEACHING FELLOW FIMA SFHEA

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Day 4	•		
Neural Networks & Neurodynamics	10am-11am	Convolutional Neural Networks	2pm-3pm
KERAS and TensorFlow	11am-12pm	Chat GPT-4 & the Future of AI	3pm-4pm
Recurrent Neural Networks	12pm-1pm		

Download all files from GitHub:

https://github.com/proflynch/CRC-Press/

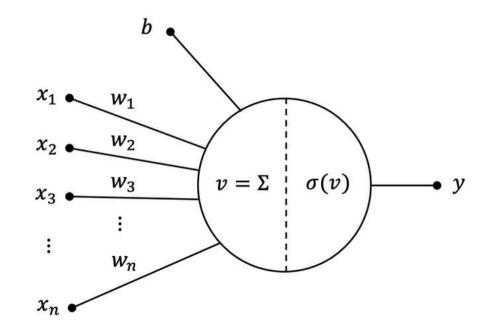
Solutions to the Exercises in Section 3:

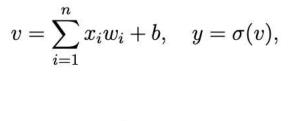
https://drstephenlynch.github.io/webpages/Solutions_Section_3.html





Neural Networks: Start Session 1





$$\sigma(v) = \frac{1}{1 + e^{-v}},$$

 $\phi(v) = \tanh(v) = \frac{e^v - e^{-v}}{e^v + e^{-v}}$

Figure 17.1 Schematic of a mathematical model of a neuron. Notice the similarity to Figure 16.1. The inputs x_i , and the bias b, are connected to the cell body via dendrites of synaptic weights w_i , v is the activation potential of the neuron, σ is a transfer function, and y is the output.



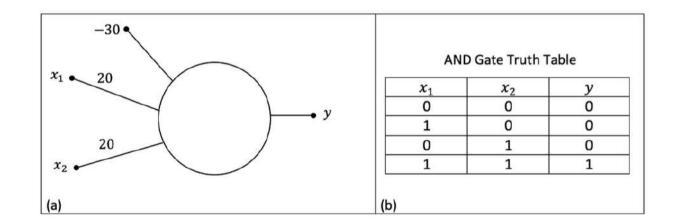


Figure 17.2 (a) ANN for an AND gate. (b) Truth table for an AND gate.

Program_17a.py: ANN for an AND Gate. import numpy as np w1 , w2 , b = 20 , 20 , -30 def sigmoid(v): return 1 / (1 + np.exp(- v)) def AND(x1, x2): return sigmoid(x1 * w1 + x2 * w2 + b) print("AND(0,0)=", AND(0,0)) print("AND(1,0)=", AND(1,0)) print("AND(1,1)=", AND(0,1))



ANN of an XOR Gate

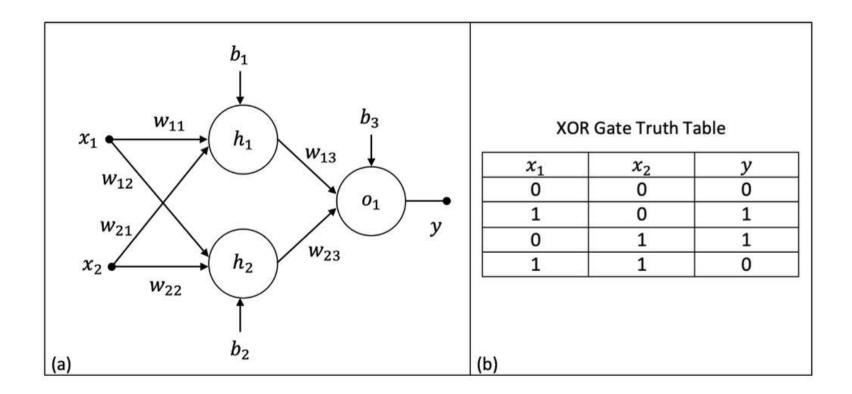
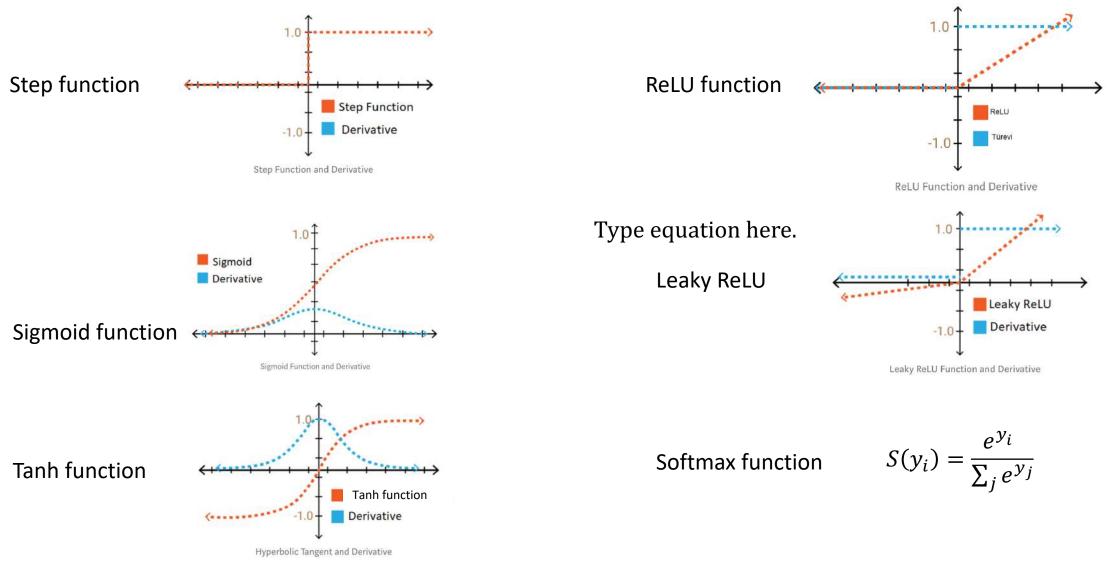


Figure 17.4 (a) ANN for an XOR gate, the synaptic weights are given in the text. There is one hidden layer consisting of two neurons, labelled h_1 and h_2 , and there is one output neuron, o_1 . Here, h_1, h_2, o_1 , are activation potentials. (b) The truth table for an XOR gate. The problem is not linearly separable when only one neuron is used.

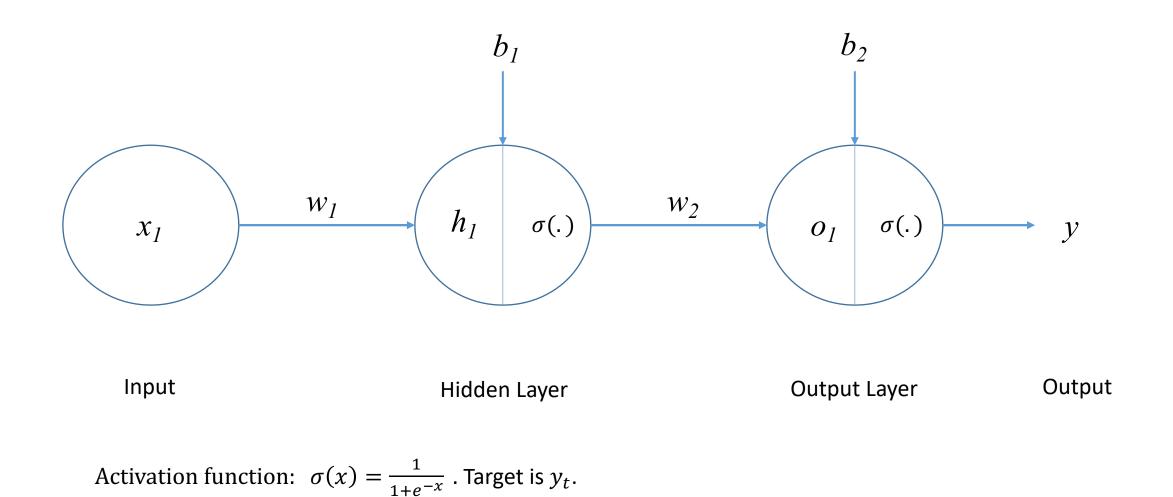


Activation Functions: $\phi(x)$ or $\sigma(x)$



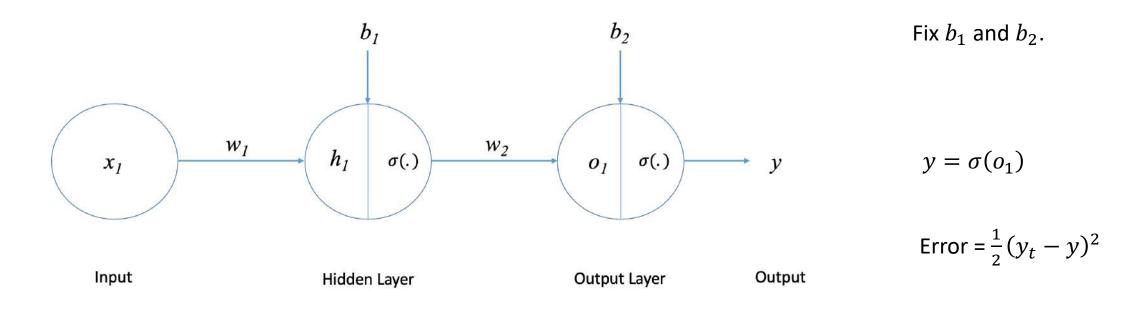


Backpropagation Algorithm



Hanchester Metropolitan University

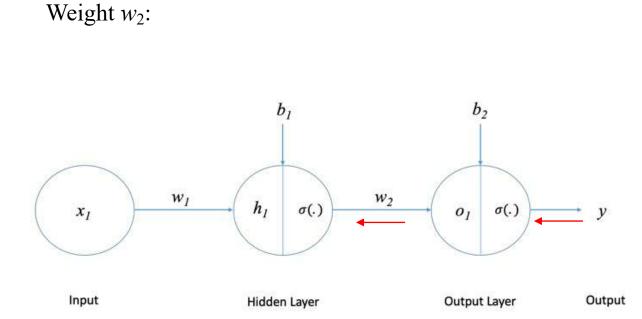
Backpropagation Algorithm: Simple Example Feedforward



 $h_1 = x_1 w_1 + b_1$ $o_1 = w_2 \times \sigma(h_1) + b_2$



Backpropagation Algorithm: Simple Example Backpropagate



$$h_{1} = x_{1}w_{1} + b_{1}$$

$$\sigma(h_{1}) = \frac{1}{1 + e^{-h_{1}}}$$

$$o_{1} = w_{2} \times \sigma(h_{1}) + b_{2}$$

$$y = \sigma(o_{1})$$
Error = $\frac{1}{2}(y_{t} - y)^{2}$

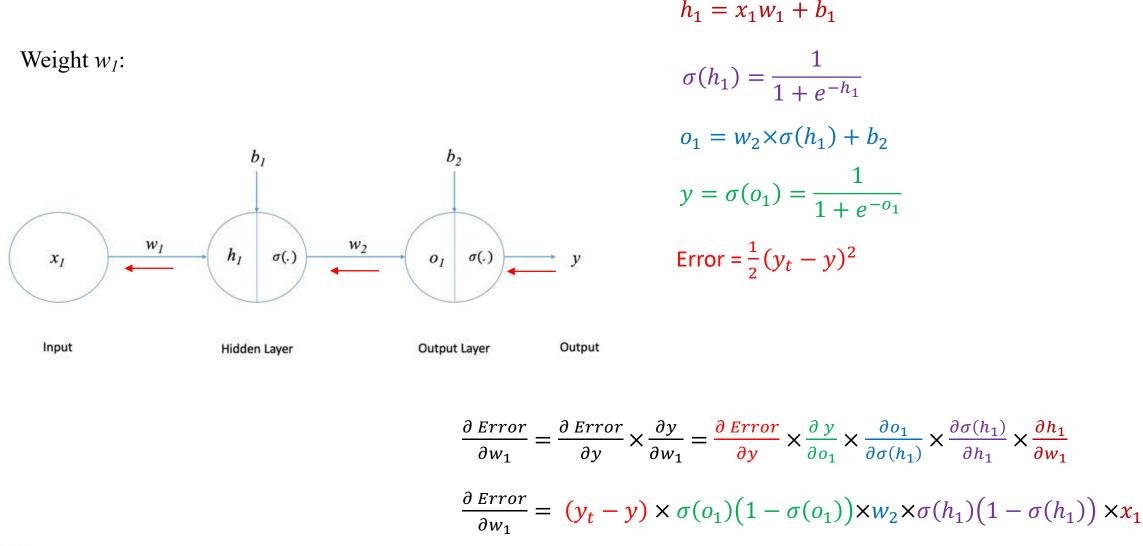
<u> d Error</u>	∂ Error	∂y	$-\frac{\partial Error}{\sqrt{\partial y}} \times \frac{\partial y}{\sqrt{\partial o_1}}$
∂w_2	- dy		$-\frac{\partial y}{\partial v_1} \wedge \frac{\partial v_2}{\partial w_2}$

$$\frac{\partial \ Error}{\partial w_2} = (y_t - y) \times \sigma'(o_1) \times \sigma(h_1)$$

$$\frac{\partial \, Error}{\partial w_2} = (y_t - y) \times \sigma(o_1) (1 - \sigma(o_1)) \times \sigma(h_1)$$



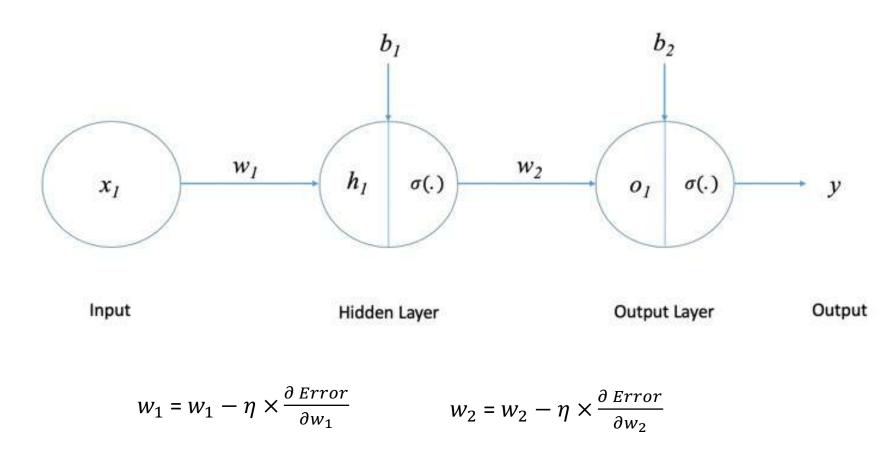
Backpropagation Algorithm: Simple Example Backpropagate





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Simple Backpropagation: Update Weights



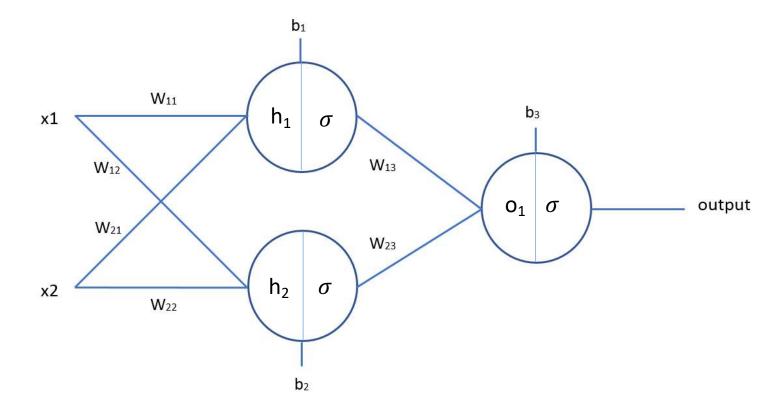
η is the learning rate.



Backpropagation Algorithm: Python Exercise

Given $w_{11}=0.11$, $w_{12}=0.12$, $w_{21}=0.21$, $w_{22}=0.08$, $w_{13}=0.14$, $w_{23}=0.15$, $b_1=b_2=b_3=-1$, $x_1=0$, $x_2=1$, and $y_t=1$,

Use backpropagation to update the weights after one forward and one reverse pass.





Example 17.3.1. Write a Python program to create an ANN for the Boston Housing data for three attributes: column six (average number of rooms), nine (index of accessibility to radial highways), and 13 (percentage lower status of population), using the target data presented in column 14 (median value of owner-occupied homes in thousands of dollars). Use the activation function $\phi(v)$, asynchronous updating, and show how the weights are adjusted as the number of iterations increases.

Solution. By experimentation, it was found that the weights converged after 100 epochs, 50600 iterations, and a learning rate of $\eta = 0.0005$, was sufficient for this problem. Program_17d.py gives Figure 17.6, showing how the weights converge.



```
# Program 17d.py: Boston Housing Data.
import matplotlib.pyplot as plt
import numpy as np
data = np.loadtxt("housing.txt")
rows, columns = data.shape
columns = 4 # Using 4 columns from the dataset in this case.
X , t = data[:, [5, 8, 12]] , data[:, 13]
ws1, ws2, ws3, ws4 = [], [], [], []
# Normalize the data.
xmean , xstd = X.mean(axis=0) , X.std(axis=0)
ones = np.array([np.ones(rows)])
X = (X - xmean * ones.T) / (xstd * ones.T)
X = np.c [np.ones(rows), X]
tmean , tstd = (max(t) + min(t)) / 2 , (max(t) - min(t)) / 2
t = (t - tmean) / tstd
# Set random weights.
w = 0.1 * np.random.random(columns)
y1 = np.tanh(X.dot(w))
e1 = t - y1
mse = np.var(e1)
num epochs , eta = 100 , 0.0005
```

```
k = 1
for m in range(num_epochs):
    for n in range(rows):
        yk = np.tanh(X[n, :].dot(w))
        err = vk - t[n]
        g = X[n, :].T * ((1 - yk**2) * err) # Gradient vector.
        w = w - eta*g
                                            # Update weights.
        k += 1
        ws1.append([k, np.array(w[0]).tolist()])
        ws2.append([k, np.array(w[1]).tolist()])
        ws3.append([k, np.array(w[2]).tolist()])
        ws4.append([k, np.array(w[3]).tolist()])
ws1,ws2,ws3,ws4=np.array(ws1),np.array(ws2),np.array(ws3),np.array(ws4)
plt.plot(ws1[:, 0],ws1[:, 1],"k",markersize=0.1,label="b")
plt.plot(ws2[:, 0],ws2[:, 1],"g",markersize=0.1,label="w1")
plt.plot(ws3[:, 0],ws3[:, 1],"b",markersize=0.1,label="w2")
plt.plot(ws4[:, 0],ws4[:, 1],"r",markersize=0.1,label="w3")
plt.xlabel("Number of iterations", fontsize=15)
plt.ylabel("Weights", fontsize=15)
plt.tick_params(labelsize=15)
plt.legend()
plt.show()
```



Boston Housing Data

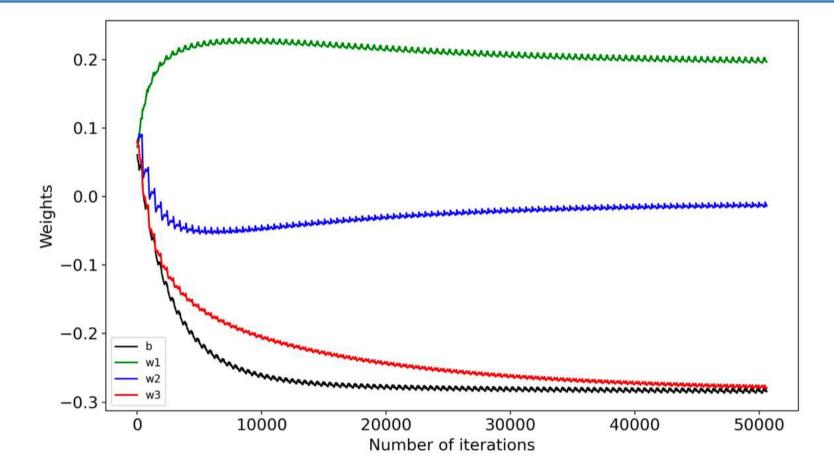


Figure 17.6 See Figure 17.1 for the ANN. Graph of weights versus number of iterations. In this case, 100 epochs were used (50600 iterations) and the learning rate was set at $\eta = 0.0005$. There is clear convergence.



Neurodynamics

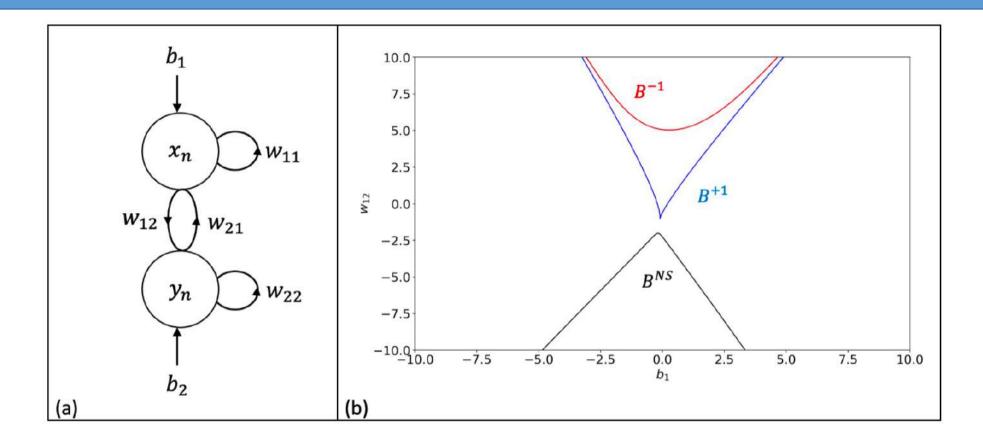


Figure 17.7 (a) Two-neuron module. (b) Stability diagram in the (b_1, w_{12}) plane when $b_2 = -1$, $w_{11} = 1.5$, $w_{21} = 5$, $\alpha = 1$, and $\beta = 0.1$. B^{+1} is the bistable boundary curve, where the system displays hysteresis, B^{-1} is the unstable boundary curve, where the system is not in steady state, and B^{NS} is the Neimark-Sacker boundary curve, where the system can show quasiperiodic behaviour.



Two-Neuron Module

$$x_{n+1} = b_1 + w_{11}\phi_1(x_n) + w_{12}\phi_2(y_n), \quad y_{n+1} = b_2 + w_{21}\phi_1(x_n) + w_{22}\phi_2(y_n), \quad (17.4)$$

where b_1, b_2 are biases, w_{ij} are weights, x_n, y_n are activation potentials, and the transfer functions are $\phi_1(x) = \tanh(\alpha x), \phi_2(y) = \tanh(\beta y)$.

Period one: $x_{n+1} = x_n = x, y_{n+1} = y_n = y$

So, from (17.4)
$$b_1 = x - w_{11} \tanh(\alpha x) - w_{12} \tanh(\beta y), y = b_2 + w_{21} \tanh(\alpha x)$$

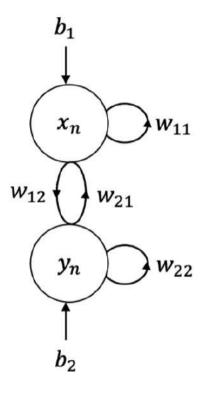
Jacobian
 $J = \begin{pmatrix} \frac{\partial P}{\partial x} & \frac{\partial P}{\partial y} \\ \frac{\partial Q}{\partial x} & \frac{\partial Q}{\partial y} \end{pmatrix} = \begin{pmatrix} \alpha w_{11} sech^2(\alpha x) & \beta w_{12} sech^2(\beta y) \\ \alpha w_{21} sech^2(\alpha x) & 0 \end{pmatrix}$

Characteristic Equation:

$$\chi(\lambda) = |J - \lambda I| = 0$$

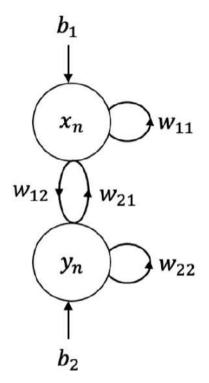
$$\lambda^{2} - \alpha w_{11} sech^{2}(\alpha x)\lambda - \alpha \beta w_{12} w_{21} sech^{2}(\beta y) sech^{2}(\alpha x) = 0$$

Boundary conditions given by $\lambda = +1$, $\lambda = -1$, and det(J) = 1, |trace(J)| < 2.





Neurodynamics: Linear Stability Analysis

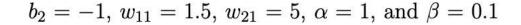


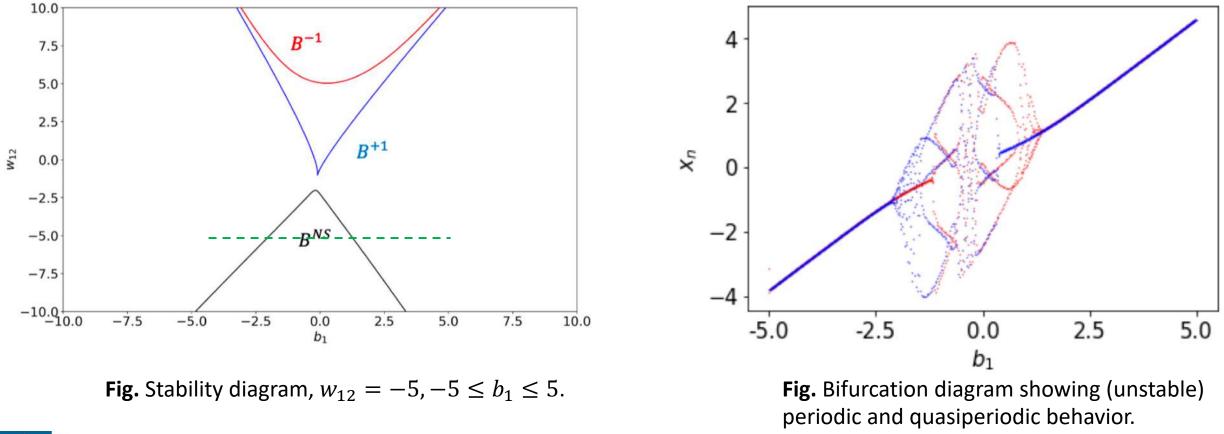
 $x_{n+1} = b_1 + w_{11}\phi_1(x_n) + w_{12}\phi_2(y_n), \quad y_{n+1} = b_2 + w_{21}\phi_1(x_n) + w_{22}\phi_2(y_n), \quad (17.4)$

where b_1, b_2 are biases, w_{ij} are weights, x_n, y_n are activation potentials, and the transfer functions are $\phi_1(x) = \tanh(\alpha x), \phi_2(y) = \tanh(\beta y)$.

Program_17e.py: Stability Diagram of a Neuromodule. import numpy as np import matplotlib.pyplot as plt # Set parameters. b2, w11, w21, alpha, beta = -1, 1.5, 5, 1, 0.1 xmin=5 x=np.linspace(-xmin,xmin,1000) y=b2 + w21 * np.tanh(x)def sech(x): return 1 / np.cosh(x) w12=(1-alpha*w11*(sech(alpha*x))**2) / \ (alpha*beta*w21*(sech(alpha*x))**2*(sech(beta*y))**2) b1=x-w11*np.tanh(alpha*x)-w12*np.tanh(beta*y) plt.plot(b1, w12, "b") # Bistable boundary. w12=(1+alpha*w11*(sech(alpha*x))**2) / \ (alpha*beta*w21*(sech(alpha*x))**2*(sech(beta*y))**2) b1=x-w11*np.tanh(alpha*x)-w12*np.tanh(beta*y) plt.plot(b1, w12, "r") # Unstable boundary. w12=(−1) / \ (alpha*beta*w21*(sech(alpha*x))**2*(sech(beta*y))**2) b1=x-w11*np.tanh(alpha*x)-w12*np.tanh(beta*y) plt.plot(b1, w12, "k") # Neimark-Sacker boundary. plt.rcParams["font.size"] = "20" plt.xlim(-10,10) plt.ylim(-10,10) plt.xlabel("\$b 1\$") plt.ylabel("\$w_{12}\$") plt.show()



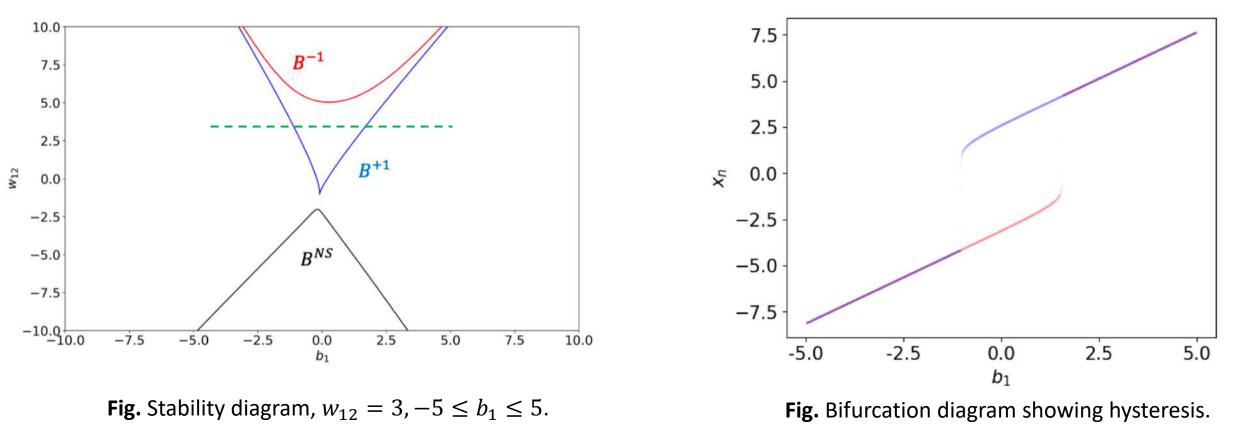






Neurodynamics: End Session 1

$$b_2 = -1, w_{11} = 1.5, w_{21} = 5, \alpha = 1, \text{ and } \beta = 0.1$$



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Artificial Intelligence: Start Session 2



Talos: A giant automaton made from bronze.

Novel: First published in 1818. Mary Shelley.

A TO Z CLASSIES

Frankenstein Mary Shelley

Play: First published in 1920. Karel Čapek.



Movie: First screened in 1968. Stanley Kubrick.



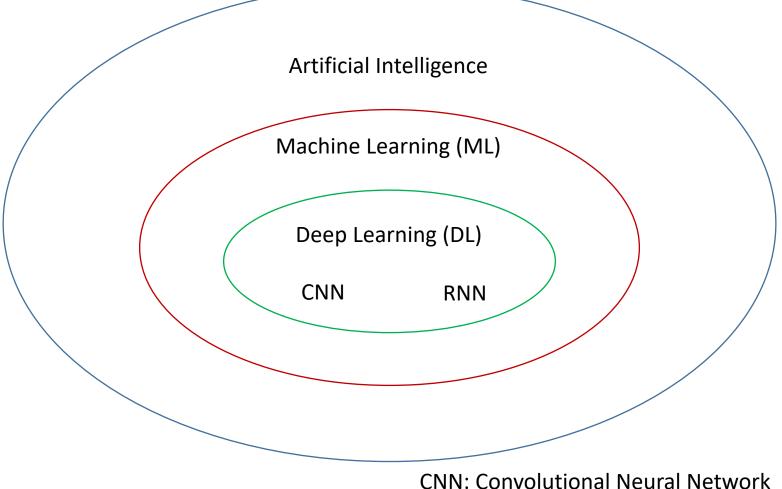


Artificial Intelligence (AI)

Al: The science and engineering of making intelligent machines.

ML: A subset of AI involved with the creation of algorithms which can modify itself without human intervention to produce desired output - by feeding itself through structured data.

DL: A subset of ML where algorithms are created and function similar to those in ML, but there are numerous layers of these algorithms - each providing a different interpretation to the data it feeds on.



RNN: Recurrent Neural Network

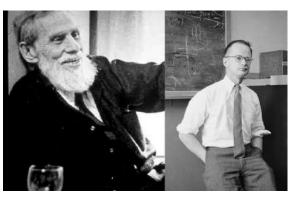


History of Al



Alan Turing (1930s):

The father of theoretical Computer Science and AI. The development of modern Computer Science. A.M. Turing (1950) Computing Machinery and Intelligence. *Mind 49:* 433-460.



Warren McCullough and Walter Pitts (1943):

A logical calculus and the ideas immanent in *nervous activity*. The development of modern neural networks.



Frank Rosenblatt (1957):

The perceptron – a perceiving and recognizing automaton. The perceptron learning rule.



Marvin Minsky & Seymour Papert (1969):

Limitations of the perceptron learning algorithm and the XOR gate.



History of Al



D.E. Rumelhart, G.E. Hinton & R.J. Williams (1986): *Learning representation by back-propagating*.

The backpropagation algorithm.

1997: IBMs Deep Blue v Gary Kasparov. First computer program to defeat a world champion in a *match* under tournament regulations. The Man vs. The Machine: Documentary film.

1990s: Work on Machine learning shifts from a knowledge-driven approach to a data-driven approach. Support Vector Machines and Recurrent Neural Networks.

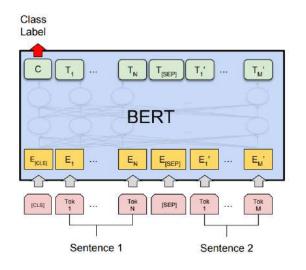
2012: Geoff Hinton: Deep Learning, Microsoft Research, Google, Toronto. DNN translated his English talk into Chinese. Image Net Competition: An error rate of just 16%.

2014: Google-Backed DeepMind Technologies learnt and successfully played 49 classic Atari games by itself using Deep Reinforcement Leaning.

2016: AlphaGo beat Lee Sedol, the first computer Go program to beat a 9-dan professional introducing the Monte Carlo Tree Search (MCTS) algorithm.



History of Al





Amazon Alexa (2014): Natural Language Processing (NLP).

BERT (2018): The best NLP model ever.

The BERT model's architecture is a bidirectional transformer encoder.

TensorFlow 2.0 (2019): An easy-to-use framework.

TensorFlow 2.0 provides a comprehensive ecosystem of tools for developers, enterprises, and researchers who want to push the state-of-the-art machine learning and build scalable ML-powered applications.

Discovery of new exoplanets (2021)

Self-replicating robots - Xenobots (2021)

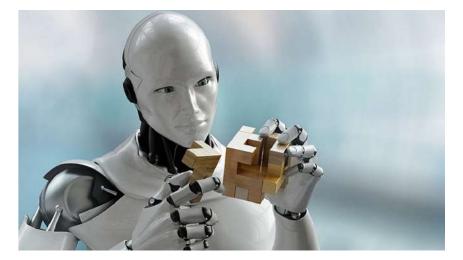
OpenAl: Chat GPT-4



Driverless Cars (???): Autonomous vehicles.

The Internet of Things (IoT)

Muthana MSA, Muthana A, Rafiq A,Khakimov A, Albelaly S, Elgendy, Hammoudeh M, **Lynch S** and Elboseny M (2022) Deep reinforcement learning based transmission policy enforcement and multi-hop routing in Quality-of-Service aware Long Range IoT networks. *Computer Communications* 183(1), 33-50.



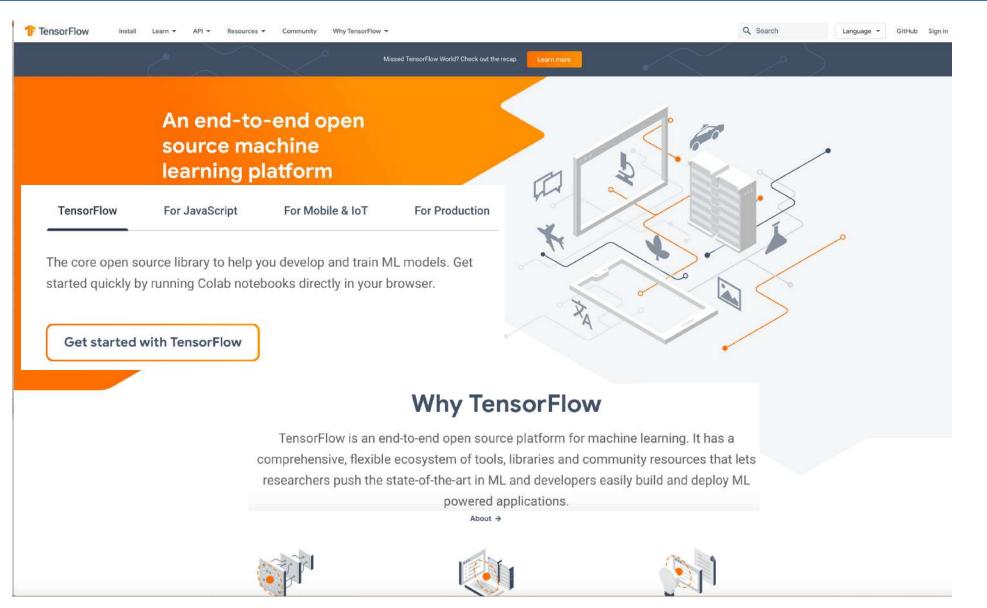
Humanoid Robots(????): Androids are humanoid robots built to aesthetically resemble humans.

Avatars and AI (????). Frankenstein!

Art, music, poetry, books and mathematical proof!

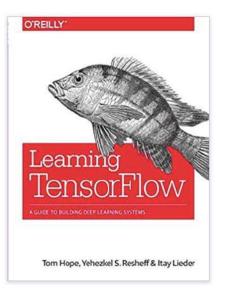


TensorFlow



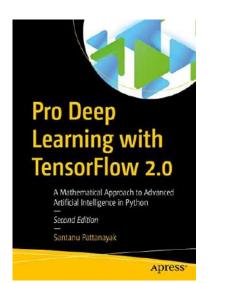


TensorFlow and KERAS



What's New in TensorFlow 2.0





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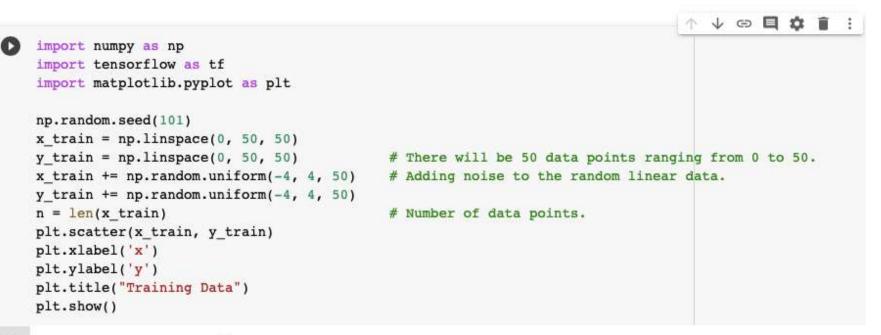


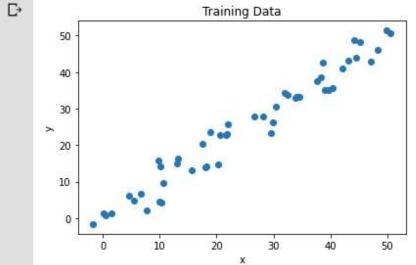
Application Programming Interface (API)

https://keras.io/api/applications/

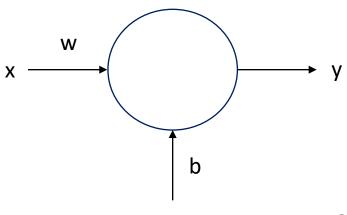


Linear Regression in TensorFlow 2





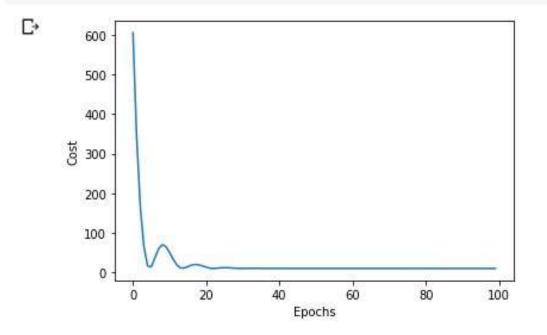






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Linear Regression in TensorFlow 2





Linear Regression in TensorFlow 2

E>

```
[8] weights = layer0.get_weights()
weight = weights[0][0]
bias = weights[1]
print('weight: {} bias: {}'.format(weight, bias))
y_learned = x_train * weight + bias
plt.scatter(x_train, y_train, label='Training Data')
plt.plot(x_train, y_learned, color='red', label='Fit Line')
plt.legend()
plt.xlabel('x')
plt.ylabel('y')
plt.show()
```

50 Fit Line Training Data 40 30 20 10 0 10 20 30 40 50 x

weight: [0.9789486] bias: [0.23586343]

Equation of Line of Best Fit

$$y = w * x + b$$



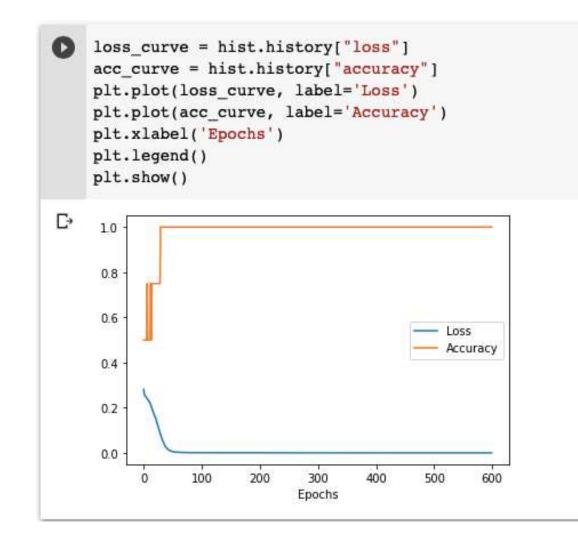
XOR Implementation in TensorFlow 2

7.115719927242026e-05 1.0

```
[6] import numpy as np
    import matplotlib.pyplot as plt
    import pandas as pd
    import tensorflow as tf
    from tensorflow import keras
    import sys
    training data = np.array([[0,0],[0, 1], [1, 0], [1, 1], 'float32')
    target data = np.array([[0], [1], [1], [0]], 'float32')
    model = tf.keras.models.Sequential()
    model.add(tf.keras.layers.Dense(4, input dim = 2, activation = 'relu'))
    model.add(tf.keras.layers.Dense(1, activation = 'sigmoid'))
    model.compile(loss='mean squared error', optimizer=tf.keras.optimizers.Adam(0.1), metrics=['accuracy'])
    hist = model.fit(training data, target data, epochs = 600, verbose = 0)
    print(model.predict(training data).round())
    val loss, val acc = model.evaluate(training data, target data)
    print(val loss, val acc)
□→ [[0.]
     [1.]
     [1.]
     [0.1]
    1/1 [================================] - 0s lms/step - loss: 7.1157e-05 - accuracy: 1.0000
```



XOR Implementation in TensorFlow 2





	Keras K	TensorFlow	PyTorch
Level of API	high-level API ¹	Both high & low level APIs	Lower-level API ²
Speed	Slow	High	High
Architecture	Simple, more readable and concise	Not very easy to use	Complex ³
Debugging	No need to debug	Difficult to debugging	Good debugging capabilities
Dataset Compatibility	Slow & Small	Fast speed & large	Fast speed & large datasets
Popularity Rank	1	2	3
Uniqueness	Multiple back-end support	Object Detection Functionality	Flexibility & Short Training Duration
Created By	Not a library on its own	Created by Google	Created by Facebook ⁴
Ease of use	User-friendly	Incomprehensive API	Integrated with Python language
Computational graphs used	Static graphs	Static graphs	Dynamic computation graphs ⁵



Boston Housing Data in TensorFlow: Keras

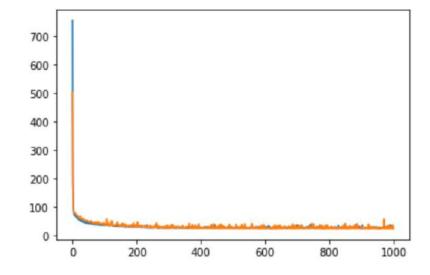
[1] import tensorflow as tf
 from tensorflow import keras
 import numpy as np
 import matplotlib.pyplot as plt

[2] from keras.datasets import boston_housing (x_train, y_train), (x_test, y_test) = boston_housing.load_data(path='boston_housing.npz',test_split=0,seed=113)

[3] model = keras.Sequential([keras.layers.Dense(1, input_dim=13, kernel_initializer='normal'),])

[4] model.compile(loss='mean_squared_error', optimizer=tf.keras.optimizers.Adam(0.01)) hist=model.fit(x_train, y_train, epochs=1000, validation_split=0.2, verbose=0)

[5] plt.plot(range(1000), hist.history['loss'], range(1000), hist.history['val_loss'])





Boston Housing Data in TensorFlow: Hidden Layers and Overfitting

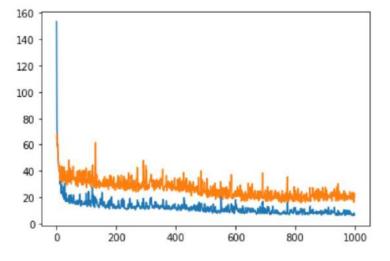
[1] import tensorflow as tf
from tensorflow import keras
import numpy as np
import matplotlib.pyplot as plt

[2] from keras.datasets import boston_housing (x_train, y_train), (x_test, y_test) = boston_housing.load_data(path='boston_housing.npz',test_split=0,seed=113)

[3] model = keras.Sequential([
 keras.layers.Dense(100, input_dim=13, kernel_initializer='normal', activation='relu'),
 keras.layers.Dense(100, kernel_initializer='normal', activation='relu'),
 keras.layers.Dense(1, kernel_initializer='normal'),
])

[4] model.compile(loss='mean_squared_error', optimizer=tf.keras.optimizers.Adam(0.01))
hist=model.fit(x_train, y_train, epochs=1000, validation_split=0.2, verbose=0)

[5] plt.plot(range(1000), hist.history['loss'], range(1000), hist.history['val_loss'])





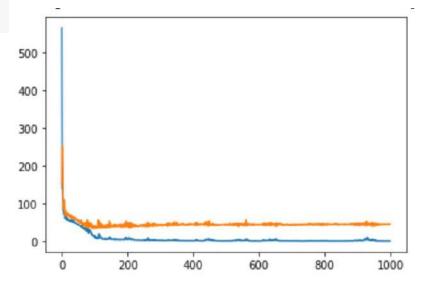
Boston Housing Data in TensorFlow: Overfitting: End Session 2

[1] import tensorflow as tf
from tensorflow import keras
import numpy as np
import matplotlib.pyplot as plt

[2] from keras.datasets import boston_housing (x_train, y_train), (x_test, y_test) = boston_housing.load_data(path='boston_housing.npz',test_split=0,seed=113)

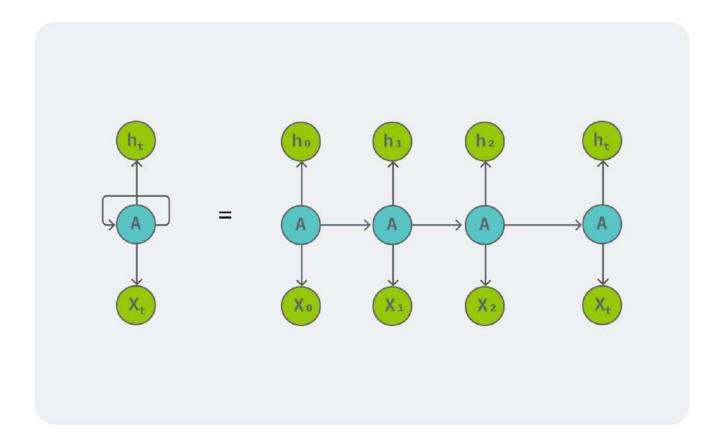
[3] model = keras.Sequential([
 keras.layers.Dense(100, input_dim=13, kernel_initializer='normal', activation='relu'),
 keras.layers.Dense(100, kernel_initializer='normal', activation='relu'),
 keras.layers.Dense(1, kernel_initializer='normal'),
])

- [4] model.compile(loss='mean_squared_error', optimizer=tf.keras.optimizers.Adam(0.01))
 hist=model.fit(x_train, y_train, epochs=1000, validation_split=0.9, verbose=0)
- [5] plt.plot(range(1000), hist.history['loss'], range(1000), hist.history['val_loss'])



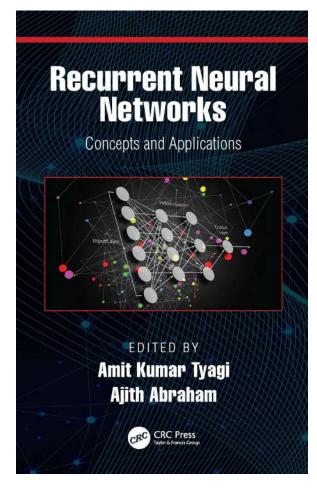


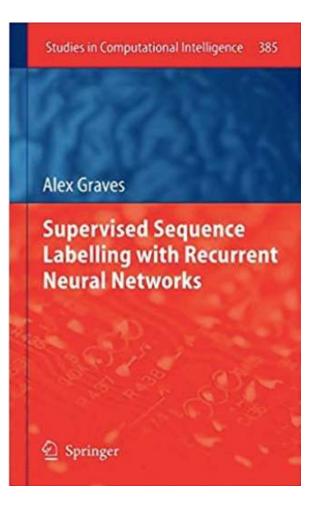
Recurrent Neural Network (RNN): Start Session 3



A **Recurrent Neural Network** (**RNN**) is a class of artificial neural networks where connections between nodes form a directed graph along a temporal sequence. This allows it to exhibit temporal dynamic behaviour.







SPRINGER BRIEFS IN COMPUTER SCIENCE

Filippo Maria Bianchi Enrico Maiorino Michael C. Kampfimeyer Antonello Rizzi Robert Jenssen

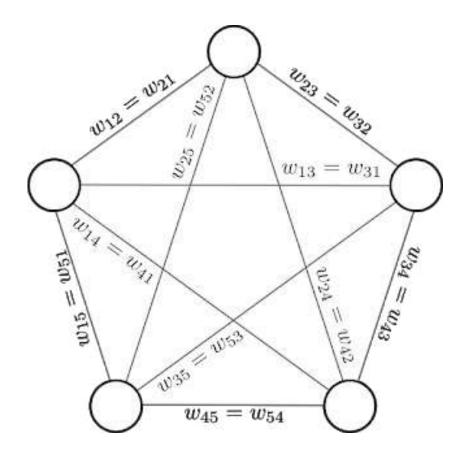
Recurrent Neural Networks for Short-Term Load Forecasting An Overview and Comparative Analysis

Manchester Metropolitan University Springer

Recurrent Neural Network: The Hopfield Neural Network



John J Hopfield





1. Hebb's Postulate of Learning. Let $\mathbf{x}_1, \mathbf{x}_2, \ldots, \mathbf{x}_M$ denote a set of N-dimensional fundamental memories. The synaptic weights of the network are determined using the formula

$$\mathbf{W} = \frac{1}{N} \sum_{r=1}^{M} \mathbf{x}_{r} \mathbf{x}_{r}^{T} - \frac{M}{N} \mathbf{I}_{n}$$

where \mathbf{I}_n is the $N \times N$ identity matrix. Once computed, the synaptic weights remain fixed.

2. Initialization. Let \mathbf{x}_p denote the unknown probe vector to be tested. The algorithm is initialized by setting

$$x_i(0) = x_{ip}, \quad i = 1, 2, \dots, N,$$

where $x_i(0)$ is the state of neuron *i* at time n = 0, x_{ip} is the *i*th element of vector \mathbf{x}_p , and N is the number of neurons.



RNN: The Discrete Hopfield Model

 Iteration. The elements are updated asynchronously (i.e., one at a time in a random order) according to the rule

$$x_i(n+1) = \operatorname{hsgn}\left(\sum_{j=1}^N w_{ij}x_j(n)\right), i = 1, 2, \dots, N,$$

where

hsgn
$$(v_i(n+1)) = \begin{cases} 1, & v_i(n+1) > 0\\ x_i(n), & v_i(n+1) = 0\\ -1, & v_i(n+1) < 0 \end{cases}$$

and $v_i(n+1) = \sum_{j=1}^{N} w_{ij} x_j(n)$. The iterations are repeated until the vector converges to a stable value. Note that at least N iterations are carried out to guarantee convergence.

4. **Result.** The stable vector, say, $\mathbf{x}_{\text{fixed}}$, is the result.



Example 5. A five-neuron discrete Hopfield network is required to store the following fundamental memories:

$$\mathbf{x}_1 = (1, 1, 1, 1, 1)^T$$
, $\mathbf{x}_2 = (1, -1, -1, 1, -1)^T$, $\mathbf{x}_3 = (-1, 1, -1, 1, 1)^T$.

(a) Compute the synaptic weight matrix W.

(b) Use asynchronous updating to show that the three fundamental memories are stable.

(c) Test the following vectors on the Hopfield network (the random orders affect the outcome):

$$\mathbf{x}_4 = (1, -1, 1, 1, 1)^T$$
, $\mathbf{x}_5 = (0, 1, -1, 1, 1)^T$, $\mathbf{x}_6 = (-1, 1, 1, 1, -1)^T$.



RNN: The Discrete Hopfield Model

Solution. (a) The synaptic weight matrix is given by

$$\mathbf{W} = \frac{1}{5} \left(\mathbf{x}_1 \mathbf{x}_1^T + \mathbf{x}_2 \mathbf{x}_2^T + \mathbf{x}_3 \mathbf{x}_3^T \right) - \frac{3}{5} \mathbf{I}_5,$$

 \mathbf{SO}

0	0	-1	1	1	$^{-1}$	1
1	$^{-1}$	0	1	1	3	
$W = \frac{1}{5}$	1	1	0	-1	1	
Б	1	1	-1	0	1	
2	(-1)	3	1	1	0)

(b) Step 1. First input vector, $\mathbf{x}_1 = \mathbf{x}(0) = (1, 1, 1, 1, 1)^T$.

Step 2. Initialize $x_1(0) = 1, x_2(0) = 1, x_3(0) = 1, x_4(0) = 1, x_5(0) = 1.$

Step 3. Update in random order $x_3(1), x_4(1), x_1(1), x_5(1), x_2(1)$, one at a time.

$$x_{3}(1) = hsgn(0.4) = 1,$$

$$x_{4}(1) = hsgn(0.4) = 1,$$

$$x_{1}(1) = hsgn(0) = x_{1}(0) = 1,$$

$$x_{5}(1) = hsgn(0.8) = 1,$$

$$x_{2}(1) = hsgn(0.8) = 1.$$

Thus $\mathbf{x}(1) = \mathbf{x}(0)$ and the net has converged.

Step 4. The net has converged to the steady state \mathbf{x}_1 .



RNN: The Discrete Hopfield Model

Step 1. Sixth input vector, $\mathbf{x}_6 = \mathbf{x}(0) = (-1, 1, 1, 1, -1)^T$.

Step 2. Initialize
$$x_1(0) = -1, x_2(0) = 1, x_3(0) = 1, x_4(0) = 1, x_5(0) = -1$$

Step 3. Update in random order $x_3(1), x_2(1), x_5(1), x_4(1), x_1(1)$, one at a time.

$$x_{3}(1) = \operatorname{hsgn}(-0.4) = -1,$$

$$x_{2}(1) = \operatorname{hsgn}(-0.4) = -1,$$

$$x_{5}(1) = \operatorname{hsgn}(-0.4) = -1,$$

$$x_{4}(1) = \operatorname{hsgn}(-0.4) = -1,$$

$$x_{1}(1) = \operatorname{hsgn}(0) = x_{1}(0) = -1$$

Step 3 (again). Update in random order $x_2(1), x_1(1), x_5(1), x_4(1), x_3(1)$, one at a time.

$$x_2(2) = \operatorname{hsgn}(-0.8) = -1,$$

$$x_1(2) = \operatorname{hsgn}(0) = x_1(1) = -1,$$

$$x_5(2) = \operatorname{hsgn}(-0.8) = -1,$$

$$x_4(2) = \operatorname{hsgn}(-0.4) = -1,$$

$$x_3(2) = \operatorname{hsgn}(-0.4) = -1.$$

Thus $\mathbf{x}(2) = \mathbf{x}(1)$ and the net has converged.

Step 4. The net has converged to the spurious steady state $-\mathbf{x}_1$.



EXERCISES

19.1 Write a Python program that illustrates the behavior of the discrete Hopfield network as a content-addressable memory using N = 81 neurons and the set of handcrafted patterns displayed in Figure 19.12. Display the images of the fundamental memories and the outputted images.

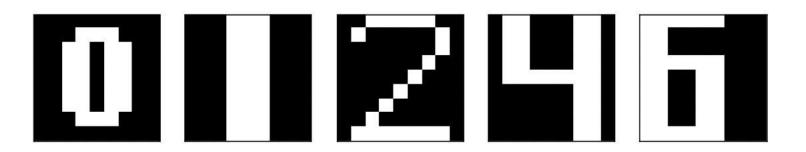


Figure 19.12: Five handcrafted patterns.



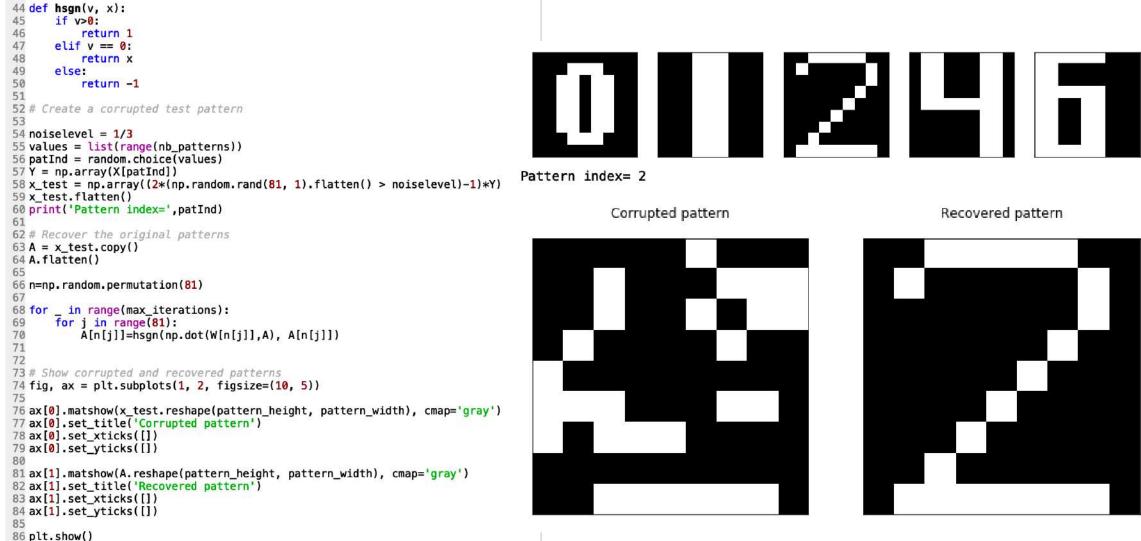
RNN: The Discrete Hopfield Model

```
1 # Hopfield Model
3 import matplotlib.pvplot as plt
4 import numpy as np
5 import random
8 \text{ nb patterns} = 5
9 pattern width = 9
10 pattern height = 9
11 max iterations = 81
12
13 # Initialize the patterns
14 X = np.zeros((nb patterns, pattern width * pattern height))
15
24 -1, -1, 1, -1, -1, -1, -1, -1, -1, 1, 1, 1, 1, 1, 1, 1, 1, -1]
27 -1, 1, 1, -1, -1, -1, -1, -1, -1, -1, 1, 1, -1]
30 -1, -1, 1, 1, 1, 1, 1, 1, -1, -1, -1
31
32 # Show the patterns
33 fig, ax = plt.subplots(1, nb patterns, figsize=(10, 5))
34
35 for i in range(nb patterns):
  ax[i].matshow(X[i].reshape((pattern_height, pattern_width)), cmap='gray')
36
37
  ax[i].set xticks([])
38
  ax[i].set yticks([])
39
40 plt.show()
```



RNN: The Discrete Hopfield Model

42 W = ((np.outer(X[0],X[0])+np.outer(X[1],X[1])+np.outer(X[2],X[2])+np.outer(X[3],X[3])+np.outer(X[4],X[4]))-5*np.identity(81))/81 43





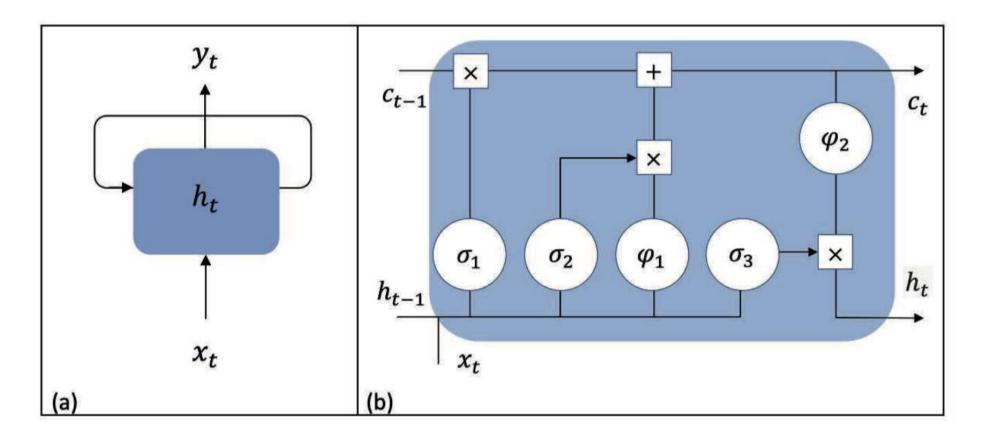


Figure: (a) RNN unit; (b) A forget layer, update the state, new cell state and decide on output.



```
] import tensorflow as tf
from tensorflow import keras
import pandas as pd
import numpy as np
import seaborn as sns
from pylab import rcParams
import matplotlib.pyplot as plt
from matplotlib import rc
```

```
%matplotlib inline
%config InlineBackend.figure_format='retina'
sns.set(style='whitegrid', palette='muted', font_scale=1.5)
rcParams['figure.figsize'] = 16, 10
RANDOM_SEED = 42
np.random.seed(RANDOM_SEED)
```



```
[2] x = 0.1
     chaos = []
     for t in range(1000):
                                                                             1.0
       x = 4 * x * (1 - x)
       chaos = np.append(chaos,x)
                                                                            0.8
    time = np.arange(0, 100, 0.1)
     plt.plot(chaos, label='logistic map chaos')
     plt.legend();
                                                                            0.6
                                                                                                                                       logistic map chaos
[3] df = pd.DataFrame(dict(chaos=chaos), index=time, columns=['chaos'])
     df.head()
                                                                            0.4
C,
            chaos
                                                                            0.2
     0.0 0.360000
     0.1 0.921600
                                                                            0.0
     0.2 0.289014
                                                                                              200
                                                                                                          400
                                                                                                                       600
                                                                                                                                   800
                                                                                                                                               1000
                                                                                  0
     0.3 0.821939
```

Manchester Metropolitan University

0.4 0.585421

```
[4] train_size = int(len(df) * 0.8)
test_size = len(df) - train_size
train, test = df.iloc[0:train_size], df.iloc[train_size:len(df)]
print(len(train), len(test))
```

[→ 800 200

```
[5] def create_dataset(X, y, time_steps=1):
    Xs, ys = [], []
    for i in range(len(X) - time_steps):
        v = X.iloc[i:(i + time_steps)].values
        Xs.append(v)
        ys.append(y.iloc[i + time_steps])
    return np.array(Xs), np.array(ys)
```



```
[6] time_steps = 10

# reshape to [samples, time_steps, n_features]
X_train, y_train = create_dataset(train, train.chaos, time_steps)
X_test, y_test = create_dataset(test, test.chaos, time_steps)
print(X train.shape, y train.shape)
```

```
C→ (790, 10, 1) (790,)
```

```
[7] model = keras.Sequential()
model.add(keras.layers.LSTM(128, input_shape=(X_train.shape[1], X_train.shape[2])))
model.add(keras.layers.Dense(1))
model.compile(loss='mean_squared_error', optimizer=keras.optimizers.Adam(0.001))
```

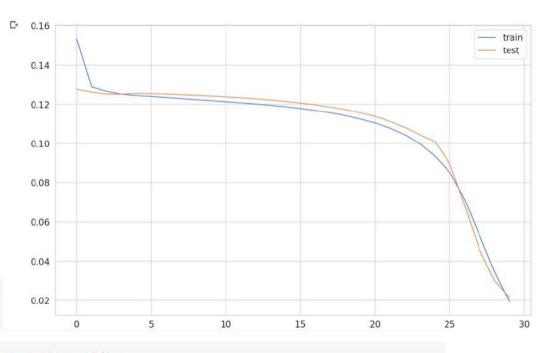


[8] history = model.fit(X_train, y_train, epochs=30, batch_size=16, validation_split=0.1, verbose=1, shuffle=False)

C+	Epoch 1/30									
L.	711/711 [===============================]		1s	2ms/sample	-	loss:	0.1535	\overline{a}	val_loss:	0.1277
	Epoch 2/30									
	711/711 [==========]	\approx	1s	lms/sample	-	loss:	0.1288	-	val_loss:	0.1261
	Epoch 3/30									
	711/711 [===============================]	\overline{a}	ls	1ms/sample	-	loss:	0.1266	\overline{a}	val_loss:	0.1252
	Epoch 4/30									
	711/711 [======================]	=	1s	lms/sample	-	loss:	0.1251	-	val_loss:	0.1251
	Epoch 5/30									
	711/711 [==============================]		1s	1ms/sample	-	loss:	0.1244	\overline{a}	val_loss:	0.1255
	Epoch 6/30									
	711/711 [=======================]	=	1s	lms/sample	-	loss:	0.1240	-	val_loss:	0.1254
	Epoch 7/30									
	711/711 [==============================]	\overline{a}	ls	1ms/sample	-	loss:	0.1234	\overline{a}	val_loss:	0.1252
	Epoch 8/30									
	711/711 [=========]	-	1s	lms/sample	-	loss:	0.1229	-	val_loss:	0.1249



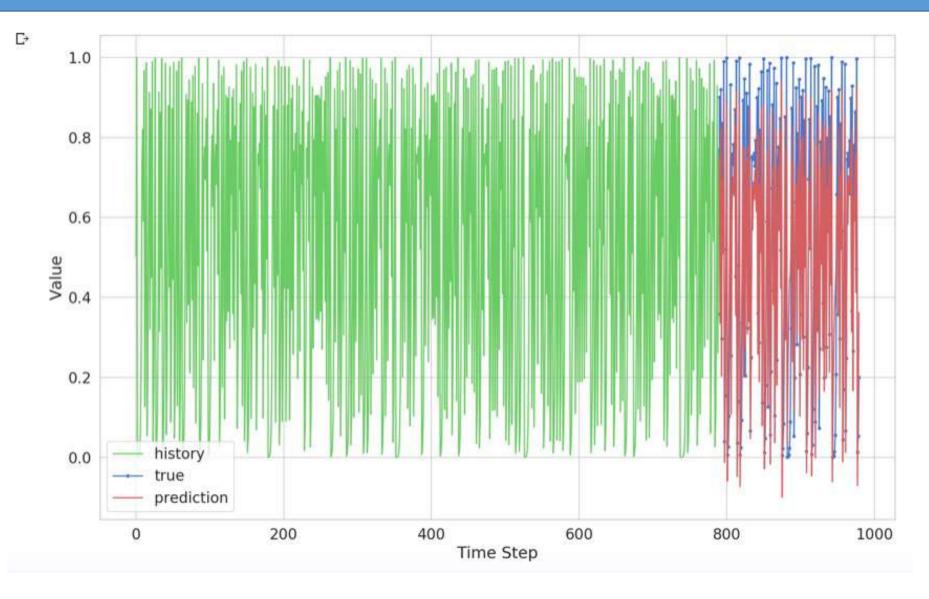
[9] plt.plot(history.history['loss'], label='train')
 plt.plot(history.history['val_loss'], label='test')
 plt.legend();



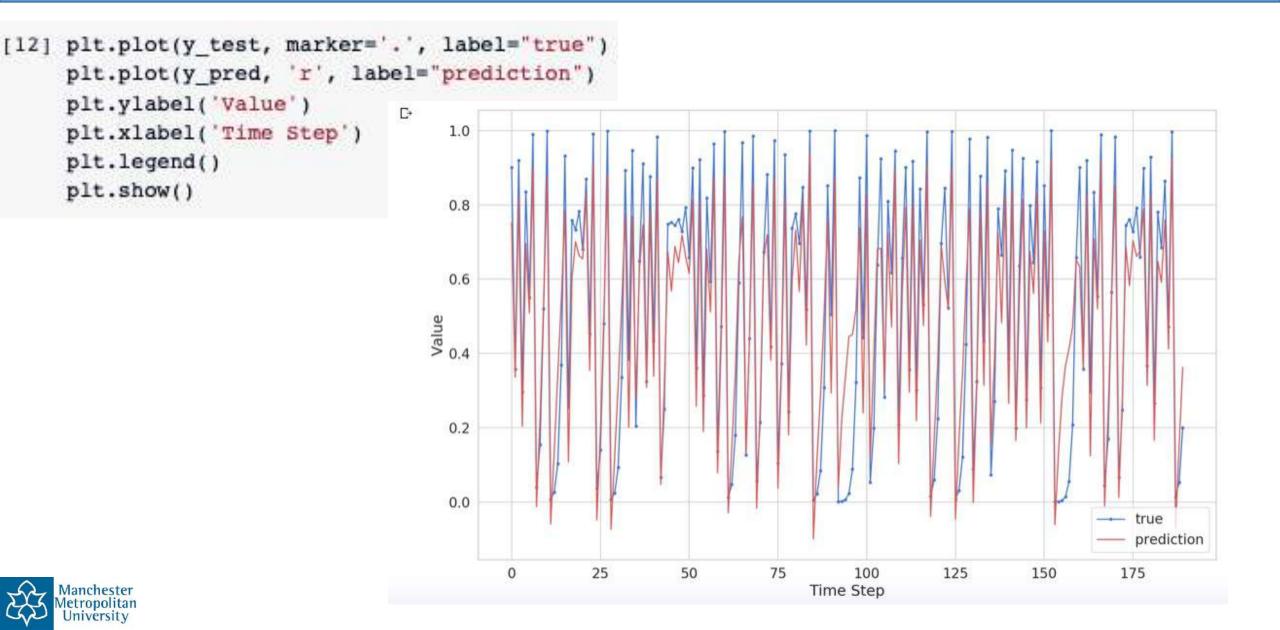
```
[10] y_pred = model.predict(X_test)
```

```
[11] plt.plot(np.arange(0, len(y_train)), y_train, 'g', label="history")
    plt.plot(np.arange(len(y_train), len(y_train) + len(y_test)), y_test, marker='.', label="true")
    plt.plot(np.arange(len(y_train), len(y_train) + len(y_test)), y_pred, 'r', label="prediction")
    plt.ylabel('Value')
    plt.xlabel('Time Step')
    plt.legend()
    plt.show();
```









Run the Python notebook LSTM_TS_Forecast_US_EUR_Exchange_Rate.ipynb through GitHub.

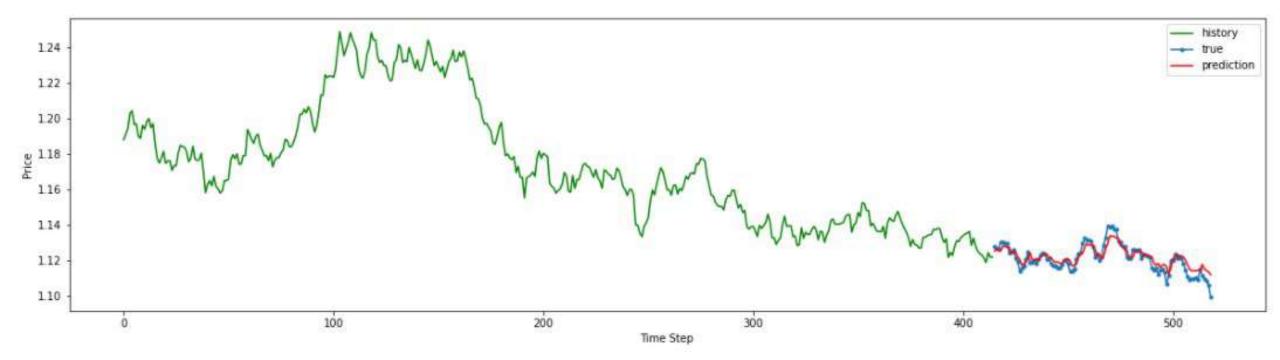


Figure: Using LSTM to predict the US/EUR exchange rate.



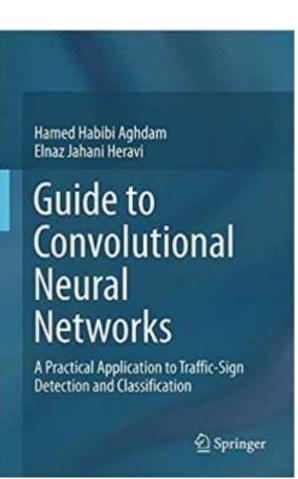
MORGAN & CLAYPOOL PUBLISHERS A Guide to

Convolutional Neural Networks for Computer Vision

Salman Khan Hossein Rahmani Syed Afaq Ali Shah Mohammed Bennamoun

SINTHERE LECTURES ON COMPLETER VISION

Genaal Musicary & Sone Disitionen, Sone Pattern





Convolutional Neural Network (CNN): MNIST Data Set

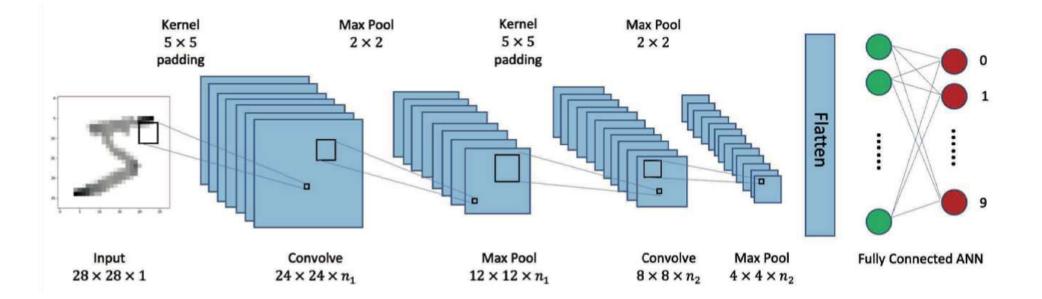
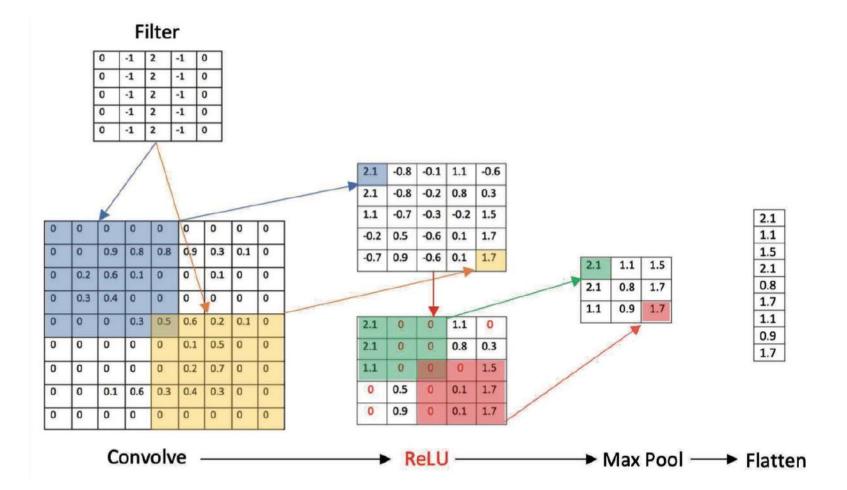


Figure 20.1 A CNN for the MNIST data set of handwritten digits. Reading from left to right, one convolves, then pools, convolves, then pools and finally flattens the data to feed through an ANN in the usual way.

https://www.youtube.com/watch?v=2-OI7ZB0MmU



Convolutional Neural Network (CNN): Explained





Convolutional Neural Network: Convolving

```
# Program 20a.py: Convolve A with K.
import numpy as np
# Input padded array.
A = np.array([[0,0,0,0,0,0,0,0]],
              [0,0,0.9,0.8,0.8,0.9,0.3,0.1,0],
              [0, 0.2, 0.6, 0.1, 0, 0, 0.1, 0.2, 0],
              [0, 0.3, 0.4, 0, 0, 0, 0, 0, 0],
              [0,0,0,0.3,0.5,0.6,0.2,0,0],
              [0,0,0,0,0,0.1,0.5,0,0],
              [0,0,0,0,0,0.2,0.7,0.4,0],
              [0.0, 0.1, 0.6, 0.3, 0.4, 0.3, 0, 0],
              [0,0,0,0,0,0,0,0,0]])
# The filter (kernel), used to find vertical lines.
K = np.array([[0, -1, 2, -1, 0]])
              [0, -1, 2, -1, 0],
              [0, -1, 2, -1, 0],
              [0, -1, 2, -1, 0],
              [0, -1, 2, -1, 0]])
C = np.zeros([5,5])
for i in range(5):
    for j in range(5):
        C[j,i] = np.sum(A[j:5+j,i:5+i] * K)
print(C)
```

MNIST database of handwritten digits

Dataset of 60,000 28x28 grayscale images of the 10 digits, along with a test set of 10,000 images.

Usage:

from keras.datasets import mnist

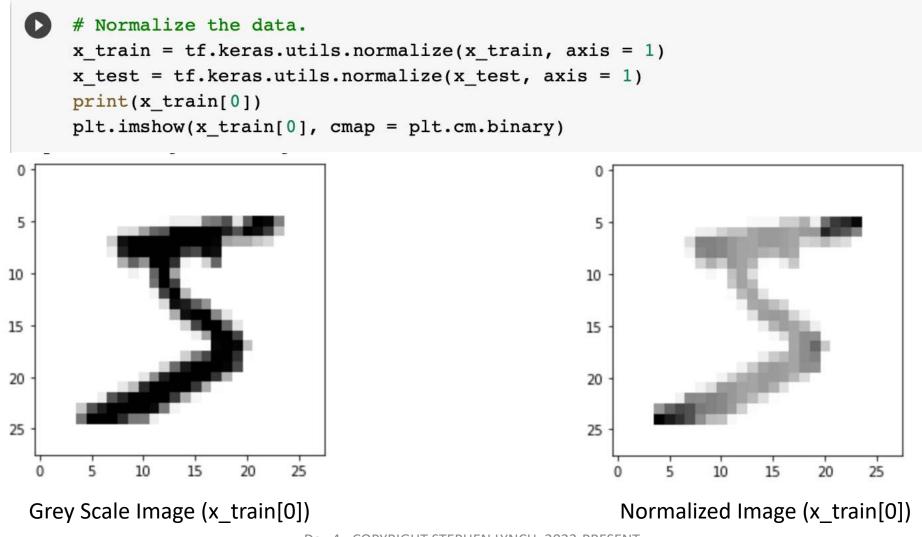
```
(x_train, y_train), (x_test, y_test) = mnist.load_data()
```

- Returns:
 - 2 tuples:
 - x_train, x_test: uint8 array of grayscale image data with shape (num_samples, 28, 28).
 - y_train, y_test: uint8 array of digit labels (integers in range 0-9) with shape (num_samples,).
- Arguments:
 - path: if you do not have the index file locally (at '~/.keras/datasets/' + path), it will be downloaded to this location.



```
layers.ipynb 🖄
       File Edit View Insert Runtime Tools Help
 + Code + Text
>
          import tensorflow as tf
          import matplotlib.pyplot as plt
          mnist = tf.keras.datasets.mnist # Digits 0-9, 28x28= pixels
          (x train, y train), (x test, y test) = mnist.load data()
          print('Dimensions of first image=', x train[0].shape)
          print(x train[0])
          #plt.imshow(x train[0])
                                                      # Plots the colour image.
          plt.imshow(x train[0], cmap = plt.cm.binary) # Plots a grey scale image.
```



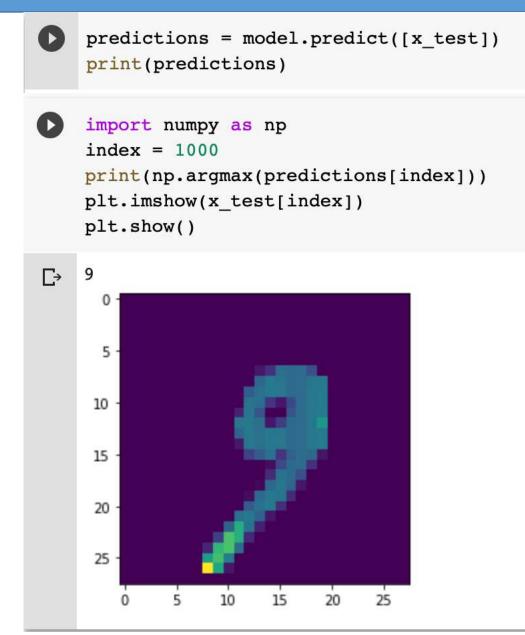


Google Colab (MNIST Dataset)

```
model = tf.keras.models.Sequential()
   model.add(tf.keras.layers.Flatten()) # The input layer.
   model.add(tf.keras.layers.Dense(128, activation = tf.nn.relu)) # The 1st hidden layer with RELU activation.
   model.add(tf.keras.layers.Dense(128, activation = tf.nn.relu)) # The 2nd hidden layer with RELU activation.
   model.add(tf.keras.layers.Dense(10, activation = tf.nn.softmax)) # The number of classifications with softmax activation.
   model.compile(optimizer='adam',
           loss='sparse categorical crossentropy',
           metrics=['accuracy'])
  model.fit(x train, y train, epochs=3)
Train on 60000 samples
Epoch 1/3
Epoch 2/3
Epoch 3/3
<tensorflow.python.keras.callbacks.History at 0x7f70142ad860>
   val loss, val acc = model.evaluate(x test, y test)
   print(val loss, val acc)
   C→
   0.1104153299085796 0.9657
```

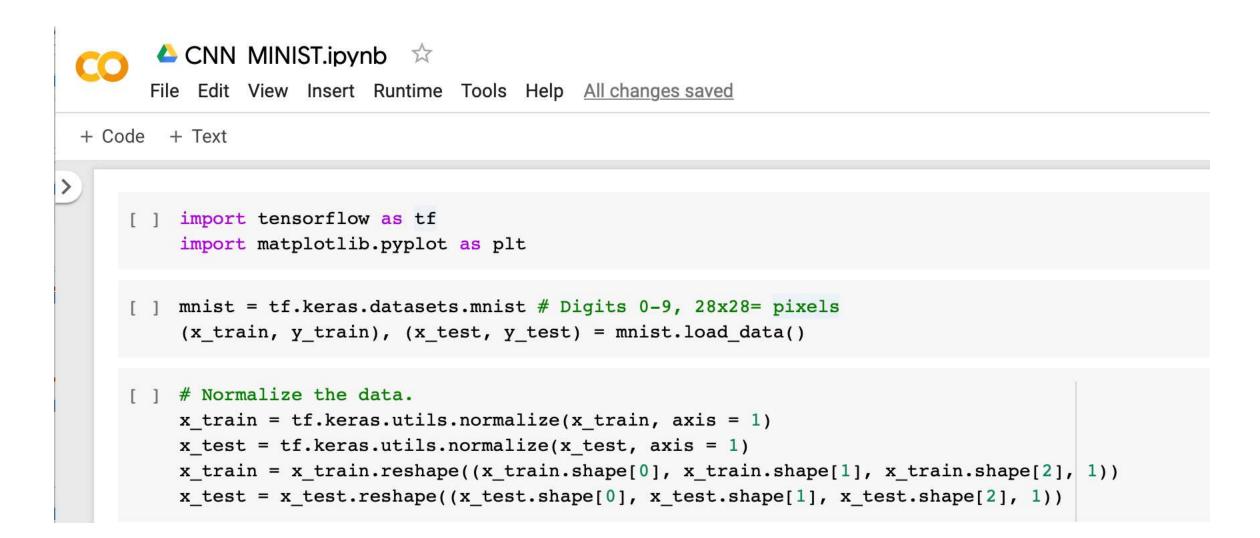


Google Colab (MNIST Dataset)





Google Colab (CNN MNIST Dataset)





Google Colab (CNN MNIST Dataset)

```
[ ] # Add convolution layers
input_shape=(28,28,1)
inputs = tf.keras.layers.Input(shape=input_shape) # The input layer.
layer = tf.keras.layers.Conv2D(filters=64, kernel_size=(5,5), strides=(2,2), activation=tf.nn.relu)(inputs)
layer = tf.keras.layers.Conv2D(filters=64, kernel_size=(5,5), strides=(2,2), activation=tf.nn.relu)(layer)
layer = tf.keras.layers.Flatten()(layer)
layer = tf.keras.layers.Dense(128, activation = tf.nn.relu)(layer) # The 1st hidden layer with RELU activation.
layer = tf.keras.layers.Dense(128, activation = tf.nn.relu)(layer) # The 2nd hidden layer with RELU activation.
outputs = tf.keras.layers.Dense(10, activation = tf.nn.softmax)(layer) # The number of classifications with softmax activation.
```



Google Colab (CNN MNIST Dataset)

[→ Model: "model_1"

Layer (type)	Output Shape	Param #				
input_2 (InputLayer)	[(None, 28, 28, 1)]	0				
conv2d_2 (Conv2D)	(None, 12, 12, 64)	1664				
conv2d_3 (Conv2D)	(None, 4, 4, 64)	102464				
flatten_1 (Flatten)	(None, 1024)	0				
dense_3 (Dense)	(None, 128)	131200				
dense_4 (Dense)	(None, 128)	16512				
dense_5 (Dense)	(None, 10)	1290				
Total params: 253,130 Trainable params: 253,130 Non-trainable params: 0						
Train on 60000 samples Epoch 1/3 60000/60000 [=================================	======] - 33s	558us/sample -	loss:	0.1717 - a	acc: 0.9	465
Epoch 2/3 60000/60000 [=================================						
60000/60000 [=================================		and the second of the	loss:	0.0412 - a	.cc: 0.9	872



Google Colab (CNN MNIST Dataset) : End Session 4

```
x = x_test.reshape((x_test.shape[0], x_test.shape[1], x_test.shape[2], 1))
D
    predictions = model.predict([x test])
    print(predictions)
    import numpy as np
    index = 1000
    print(np.argmax(predictions[index]))
    plt.imshow(x test[index].reshape((28,28)))
    plt.show()
□ [[3.91767618e-10 3.75979825e-09 4.56916780e-08 ... 9.99998450e-01
      4.04364231e-09 1.31759430e-06]
     [7.06394231e-12 1.56008383e-07 9.99999881e-01 ... 5.07569098e-10
     4.52388370e-11 3.62123864e-14]
     [1.08492145e-07 9.99971986e-01 7.53841096e-06 ... 5.89023466e-06
      8.70545534e-07 8.48745231e-07]
     ...
     [4.42824692e-08 3.24178254e-05 1.39420010e-07 ... 8.49580756e-05
     4.52493041e-05 6.18437247e-04]
     [4.69727501e-09 1.78956447e-10 3.33151770e-11 ... 1.50632440e-09
     3.29844079e-05 2.30408276e-10]
     [3.05831890e-07 4.55387106e-09 1.44481149e-07 ... 1.76121354e-10
      8.38539762e-08 5.32932765e-09]]
    9
     5
     10
    15
     20
     25
                10
                    15
                         20
                             25
       0
           5
```



An Introduction to TensorBoard: MNIST Dataset: Start Session 5

```
(1) try:
      %tensorflow version 2.x
    except Exception:
      pass
    # Load the TensorBoard notebook extension
    %load ext tensorboard
    TensorFlow 2.x selected.
 E÷.
[2] import tensorflow as tf
    import datetime
[3] # Clear any logs from previous runs
    Irm -rf ./logs/
[4] mnist = tf.keras.datasets.mnist
    (x_train, y_train),(x_test, y_test) = mnist.load_data()
    x train, x test = x train / 255.0, x test / 255.0
    def create model():
      return tf.keras.models.Sequential([
        tf.keras.layers.Flatten(input shape=(28, 28)),
        tf.keras.layers.Dense(512, activation='relu'),
        tf.keras.layers.Dropout(0.2),
        tf.keras.layers.Dense(10, activation='softmax')
      1)
```



An Introduction to TensorBoard

```
log_dir="logs/fit/" + datetime.datetime.now().strftime("%Y%m%d-%H%M%S")
tensorboard_callback = tf.keras.callbacks.TensorBoard(log_dir=log_dir, histogram_freq=1)
```

model.fit(x=x_train, y=y_train, epochs=16, validation_data=(x_test, y_test), callbacks=[tensorboard_callback])

```
Train on 60000 samples, validate on 10000 samples
Epoch 1/16
60000/60000 [============] - 11s 180us/sample - loss: 0.2224 - accuracy: 0.9337 - val_loss: 0.1046 - val_accuracy: 0.9683
Epoch 2/16
60000/60000 [============] - 11s 177us/sample - loss: 0.0969 - accuracy: 0.9704 - val_loss: 0.0742 - val_accuracy: 0.9771
Epoch 3/16
60000/60000 [==================] - 11s 182us/sample - loss: 0.0665 - accuracy: 0.9787 - val_loss: 0.0708 - val_accuracy: 0.9771
```

```
Epoch 14/16
60000/60000 [=========] - 11s 176us/sample - loss: 0.0147 - accuracy: 0.9951 - val_loss: 0.0919 - val_accuracy: 0.9816
Epoch 15/16
60000/60000 [==========] - 10s 175us/sample - loss: 0.0177 - accuracy: 0.9940 - val_loss: 0.0815 - val_accuracy: 0.9817
Epoch 16/16
60000/60000 [==========] - 11s 176us/sample - loss: 0.0124 - accuracy: 0.9957 - val_loss: 0.0867 - val_accuracy: 0.9820
<tensorflow.python.keras.callbacks.History at 0x7fa77ac7a5f8>
```



An Introduction to TensorBoard

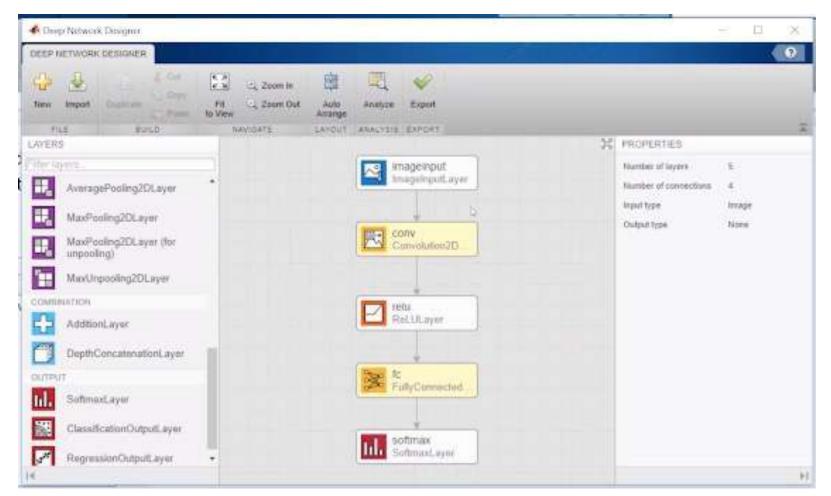
C) %tensorb	oardlogdir=	logs		
G	Tenso	orBoard	SCALARS GRAPHS DIST	RIBUTIONS HISTOGRAMS PROFILE	
			 Show data download links Ignore outliers in chart scaling Tooltip sorting method: default 	Q Filter tags (regular expressions supported) epoch_accuracy	
Run this command	to get bot	h curves!	Smoothing Horizontal Axis STEP RELATIVE WALL	epoch_accuracy 0.995 0.975 0.965	
[7] 1kill 4696			Runs Write a regex to filter runs O fit/20200102-172828/train C fit/20200102 172828/train	0 2 4 6 8 10 12 14 C3 epoch_loss	
[/] IXIII 4030			TOGGLE ALL RUNS	epoch_loss	
Manchester Metropolitan University			Di	0 2 4 6 8 10 12 14	74

TensorBoard Graphs

TensorBoard	SCALARS GRA	PHS DISTRIBUTIONS HIS	TOGRAMS PROFILE		
Search nodes. Regex	es supported.				
Fit to Screen					
🛓 Download PNG				(
Run (1) <u>fit/2020010</u>	2-172828/train -	metrics	loss	dropout_er	LEbox
Tag (3) Default		dense_1	5	dropout, an	nd t
Upload Cho	iose File	Ŧ			
Graph					
O Conceptual Graph	h	dropout			
O Profile		$\langle \rangle$			
🔵 Trace inputs		keras_le. dense			
Show health pil	ls	dense 1			
 Close legend. 					
Graph (* = expandab	nle)	flatten			
Namespace*	2				
OpNode ? Unconnected	series*?	flatter 1			
Connected se Constant ?	ries* <u>?</u>				
Summary ?					
> Dataflow edg	e <u>?</u>				
Control deper	idency edge ?				



MATLAB[®] Deep Learning Toolbox

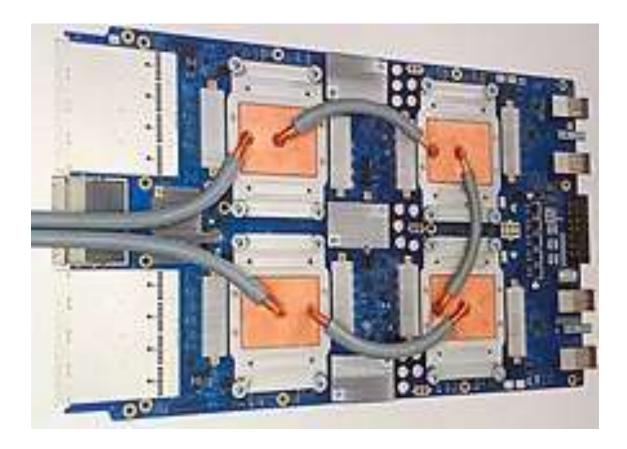


https://uk.mathworks.com/videos/what-is-deep-learning-toolbox--1535667599631.html



A Tensor Processing Unit (TPU) is an AI Accelerator application-Specific Integrated Circuit (ASIC) developed By Google for Deep Learning using TensorFlow.







Google Colab and the Tensor Processing Unit

TPUs in Colab 闼



In this example, we'll work through training a model to classify images of flowers on Google's lightning-fast Cloud TPUs. Our model will take as input a photo of a flower and return whether it is a daisy, dandelion, rose, sunflower, or tulip.

We use the Keras framework, new to TPUs in TF 2.1.0. Adapted from this notebook by Martin Gorner.









Using AI to write Shakespeare!

QUEENE:

I had thought thou hadst a Roman; for the oracle, Thus by All bids the man against the word, Which are so weak of care, by old care done; Your children were in your holy love, And the precipitation through the bleeding throne.

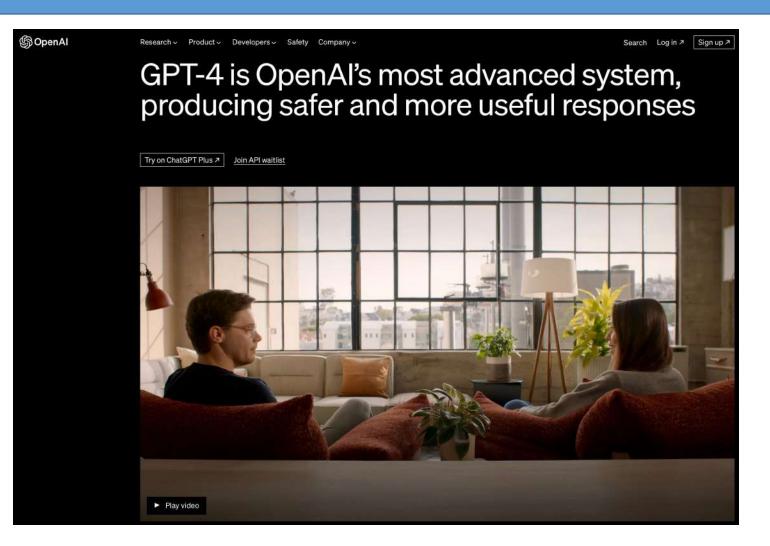
BISHOP OF ELY: Marry, and will, my lord, to weep in such a one were prettiest; Yet now I was adopted heir Of the world's lamentable day, To watch the next way with his father with his face?

ESCALUS: The cause why then we are all resolved more sons.





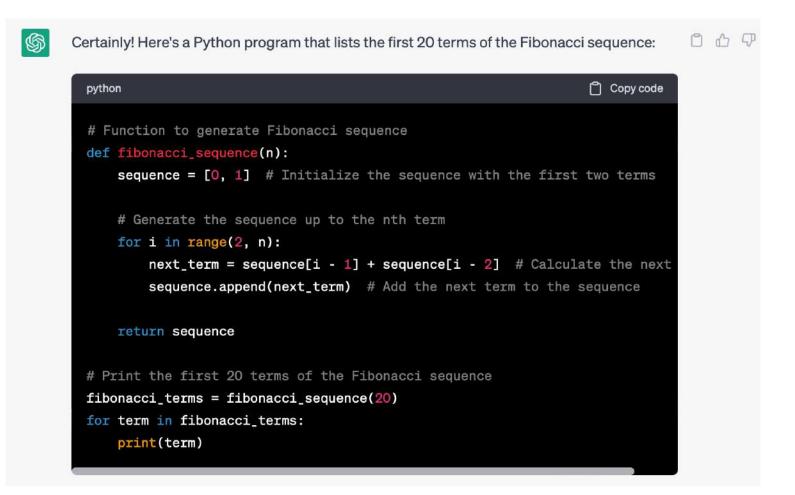
OpenAI: ChatGPT-4 and Python



https://openai.com/product/gpt-4



Write a Python program to list the first 20 terms of the Fibonacci sequence and comment the code.





Write a Python program to list the first 20 terms of the Fibonacci sequence and comment the code.

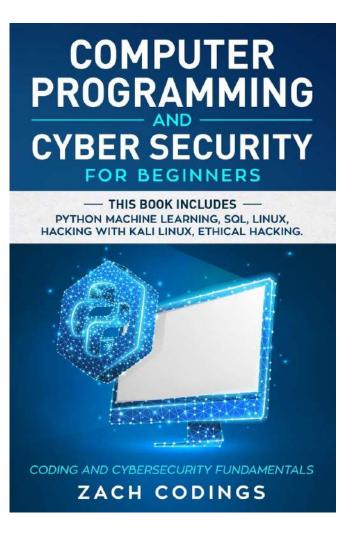
Let's go through the code step by step:

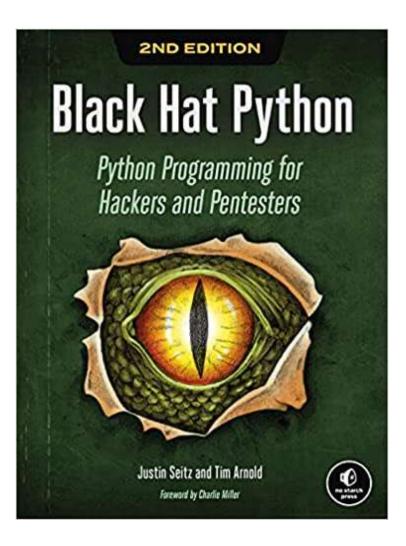
- 1. We define a function called `fibonacci_sequence` that takes an integer `n` as a parameter. This function will generate the Fibonacci sequence up to the nth term.
- 2. Inside the function, we initialize the 'sequence' list with the first two terms: 0 and 1.
- 3. We use a for loop starting from the third term (index 2) up to the desired `n`th term. In each iteration, we calculate the next term by summing up the previous two terms.
- 4. The calculated next term is then appended to the 'sequence' list.
- 5. Finally, the function returns the generated Fibonacci sequence.
- 6. Outside the function, we call `fibonacci_sequence(20)` to generate the Fibonacci sequence up to the 20th term and store it in the variable `fibonacci_terms`.
- 7. We use a for loop to iterate over `fibonacci_terms` and print each term on a new line.

When you run this program, it will output the first 20 terms of the Fibonacci sequence.



Further Reading: Cyber Security







Paula Boddington Towards a Code of Ethics for Artificial Intelligence

D Springer

bonomit tr. Dr. Sanjay Kumar Raul bonomit & bonotement



ARTIFICIAL INTELLIGENCE Ethics and International Law: An Introduction

A Techno-Social Vision of Artificial Intelligence in the International Life

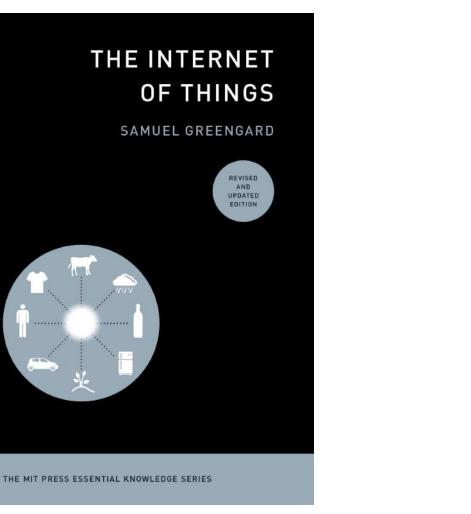
bob

ABHIVARDHAN





Further Reading: The Internet of Things (IoT)



RASPBERRY PI 4 COMPLETE MANUAL

A Step-by-Step Guide to Master the New Raspberry Pi 4 and Set Up Innovative Projects

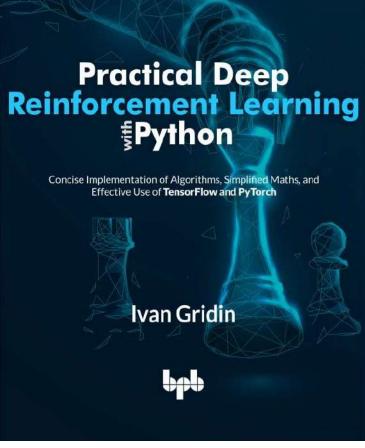
Raphael Stone





Further Reading: Reinforcement Learning

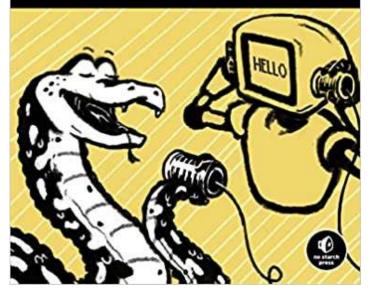






NATURAL LANGUAGE PROCESSING USING PYTHON

YULI VASILIEV





Natural Language Understanding with Python

Building Human-Like Understanding with Large Language Models

DEBORAH A. DAHL



Day 4						
Neural Networks & Neurodynamics	10am-11am	Convolutional Neural Networks	2pm-3pm			
KERAS and TensorFlow	11am-12pm	Chat GPT-4 & the Future of AI	3pm-4pm			
Recurrent Neural Networks	12pm-1pm					

Download all files from GitHub:

https://github.com/proflynch/CRC-Press/

Solutions to the Exercises in Section 3:

https://drstephenlynch.github.io/webpages/Solutions_Section_3.html

