

4-Day Hands-on Workshop on:

Python for Scientific Computing and TensorFlow for Artificial Intelligence

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Schedule (Day 2)

Day 2			
Jupyter and Colab Notebooks	10am-11am	Economics	2pm-3pm
Biology and Chemistry	11am-12pm	Engineering	3pm-4pm
Data Science	12pm-1pm		

Download all files from GitHub:

<https://github.com/proflynch/CRC-Press/>

Solutions to the Exercises in Section 2:

https://drstephenlynch.github.io/webpages/Solutions_Section_2.html



Anaconda: Launch a Jupyter Notebook: Start Session 1

The screenshot displays the Anaconda Navigator desktop application. The interface includes a left-hand sidebar with navigation options: Home, Environments, Learning, and Community. The main area shows a grid of application tiles for 'base (root)' environment. The tiles are: JupyterLab (3.0.14), Jupyter Notebook (6.3.0), Qt Console (5.0.3), Spyder (5.0.0), Glueviz (1.0.0), Orange 3 (3.26.0), and RStudio (1.1.456). Each tile contains an icon, version number, a brief description, and a button to either 'Launch' or 'Install'. A red arrow points from the text 'Click here to open a new Python 3 ipynb notebook' to the 'Launch' button of the Jupyter Notebook tile. The top right of the window has 'Upgrade Now' and 'Sign in to Anaconda.org' links. The bottom left of the sidebar shows social media icons for Twitter, YouTube, and GitHub.

ANACONDA NAVIGATOR

Upgrade Now Sign in to Anaconda.org

Home Environments Learning Community

Applications on base (root) Channels Refresh

JupyterLab 3.0.14
An extensible environment for interactive and reproducible computing, based on the Jupyter Notebook and Architecture.
Launch

Jupyter Notebook 6.3.0
Web-based, interactive computing notebook environment. Edit and run human-readable docs while describing the data analysis.
Launch

Qt Console 5.0.3
PyQt GUI that supports inline figures, proper multiline editing with syntax highlighting, graphical calltips, and more.
Launch

Spyder 5.0.0
Scientific PYTHON Development Environment. Powerful Python IDE with advanced editing, interactive testing, debugging and introspection features
Launch

Glueviz 1.0.0
Multidimensional data visualization across files. Explore relationships within and among related datasets.
Install


Orange 3 3.26.0
Component based data mining framework. Data visualization and data analysis for novice and expert. Interactive workflows with a large toolbox.
Install

RStudio 1.1.456
A set of integrated tools designed to help you be more productive with R. Includes R essentials and notebooks.
Install

Documentation Developer Blog

Twitter YouTube GitHub

Anaconda: Launch a Jupyter Notebook



QuitLogout

FilesRunningClusters

Click here to open a new Python 3 ipynb notebook

Select items to perform actions on them.

0 /

UploadNew

Notebook:
Python 3

Other:
Text File
Folder
Terminal

<input type="checkbox"/>	Desktop		
<input type="checkbox"/>	Documents		
<input type="checkbox"/>	Downloads		
<input type="checkbox"/>	Dropbox		
<input type="checkbox"/>	Movies	2 months ago	
<input type="checkbox"/>	Music	2 months ago	
<input type="checkbox"/>	Pictures	2 months ago	
<input type="checkbox"/>	Public	2 months ago	
<input type="checkbox"/>	Untitled.ipynb	a month ago	555 B
<input type="checkbox"/>	matlab_crash_dump.83074-1	a month ago	8.48 kB

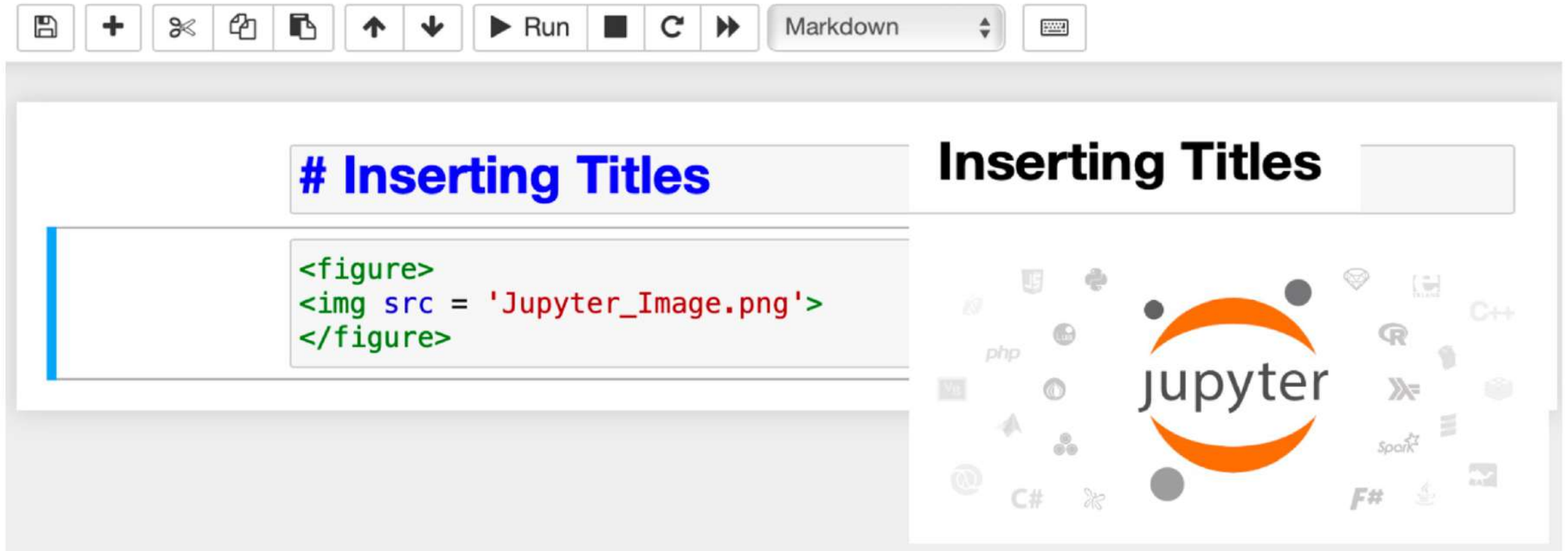
Jupyter Notebook

The image shows a Jupyter Notebook interface with the title "Untitled1 (unsaved changes)". The top bar includes the Jupyter logo, the title, a Python logo, and a "Logout" button. Below this is a menu bar with "File", "Edit", "View", "Insert", "Cell", "Kernel", "Widgets", and "Help". To the right of the menu bar are "Trusted" and "Python 3" indicators. The toolbar contains icons for saving, adding, deleting, copying, pasting, moving up/down, running, interrupting, and redoing. A dropdown menu is set to "Code". The main area contains a code cell with the prompt "In []:" and the text "A Cell".

Annotations with red arrows point to the following elements:

- Save File**: Points to the save icon (floppy disk) in the toolbar.
- Change File Name**: Points to the "Untitled1 (unsaved changes)" title.
- Run the Cell**: Points to the "Run" button (play icon) in the toolbar.
- Interrupt the Kernel**: Points to the interrupt button (black square icon) in the toolbar.
- Insert Code or Markdown (Text)**: Points to the dropdown menu in the toolbar, which is currently set to "Code".

Jupyter Notebook: Inserting Titles and Figures



The screenshot displays the Jupyter Notebook interface. At the top is a toolbar with icons for saving, adding, deleting, and running code, along with a 'Markdown' dropdown menu. Below the toolbar, the notebook is divided into two main sections. The left section contains a code cell with the following HTML code:

```
<figure>
<img src = 'Jupyter_Image.png'>
</figure>
```

The right section shows the rendered output of the code cell. It features a large, bold title 'Inserting Titles' at the top. Below the title is a large image of the Jupyter logo, which consists of an orange circle with the word 'jupyter' in lowercase. Surrounding the logo are various icons representing different programming languages and technologies, including JavaScript, Python, R, C++, C#, F#, Spark, and others.

You can **File > Download as > Notebook (.pynb)** or **Webpage (.html)** Save (ipynb) file in a folder with figure and **Open** using Jupyter.

Simple Programming with Jupyter Notebooks (Solving ODEs)

Solve the 1st order ODE:

$$\frac{dx}{dt} + x = 1$$

Solve the 2nd order ODE:

$$\frac{d^2y}{dt^2} + \frac{dy}{dt} + y = e^t$$

Solve the 1st order ODE:

$$\frac{dx}{dt} + x = 1$$

Solve the 2nd order ODE:

$$\frac{d^2y}{dt^2} + \frac{dy}{dt} + y = e^t$$

```
In [1]: # Solve the 1st order ODE.
from sympy import *
t = symbols('t')
x = symbols('x', cls = Function)
ODE1 = Eq(x(t).diff(t), 1 - x(t))    # dx/dt=1-x.
sol1 = dsolve(ODE1, x(t))
print(sol1)
```

$\text{Eq}(x(t), C1 \cdot \exp(-t) + 1)$

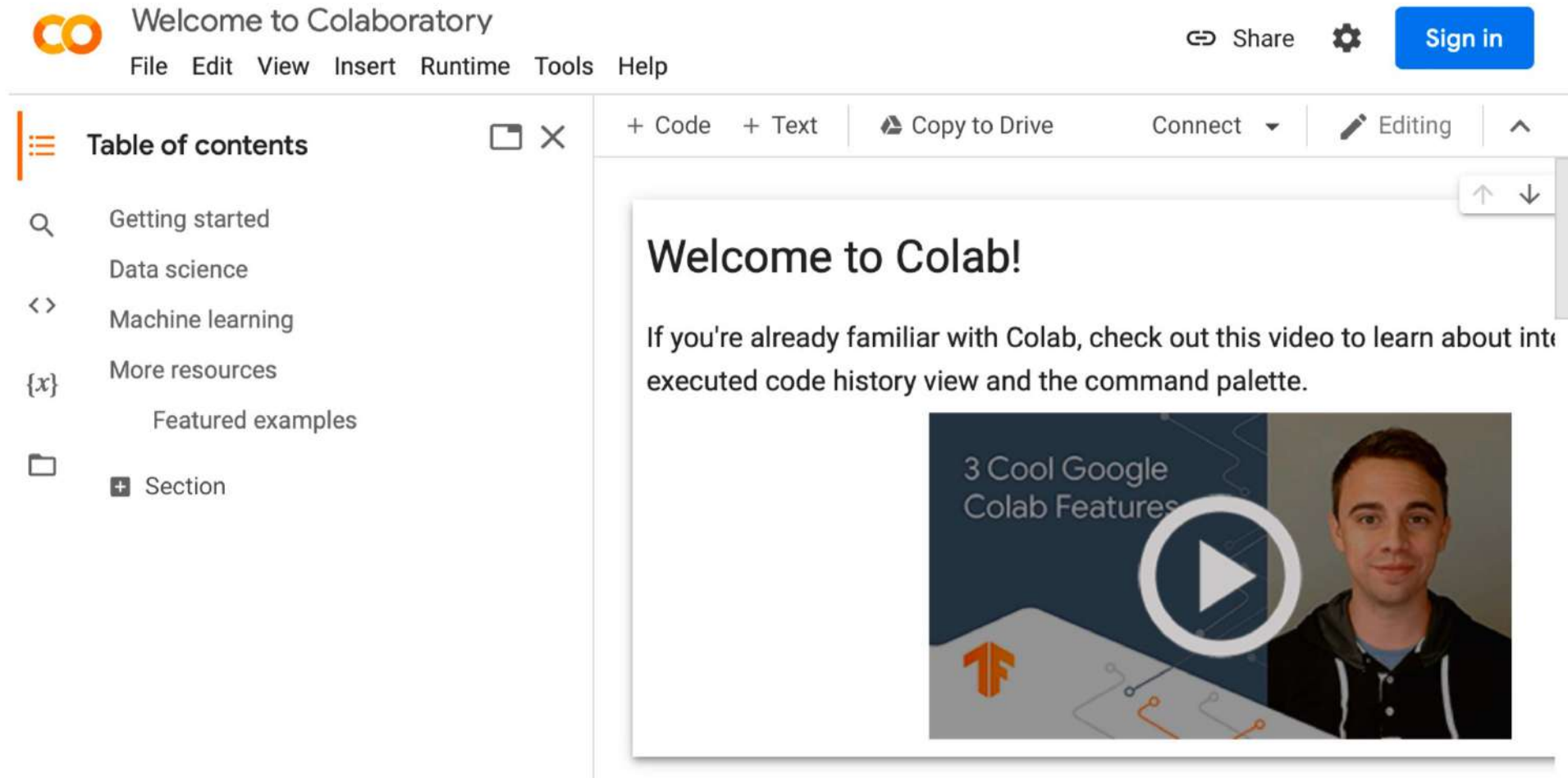
https://oeis.org/wiki/List_of_LaTeX_mathematical_symbols

Jupyter Notebooks: LaTeX Symbols

Table 3.1 Table of popular LaTeX symbols for jupyter Notebooks.

Greek Letters	LaTeX	Mathematics	LaTeX
α	<code>\alpha</code>	$\frac{dx}{dt}$	<code>\frac{dx}{dt}</code>
β	<code>\beta</code>	\dot{x}	<code>\dot{x}</code>
γ, Γ	<code>\gamma, \Gamma</code>	\ddot{x}	<code>\ddot{x}</code>
δ	<code>\delta</code>	$\sin(x)$	<code>\sin(x)</code>
ϵ	<code>\epsilon</code>	$\cos(x)$	<code>\cos(x)</code>
θ	<code>\theta</code>	\leq	<code>\leq</code>
λ, Λ	<code>\lambda, \Lambda</code>	\geq	<code>\geq</code>
μ	<code>\mu</code>	x^2	<code>x^2</code>
σ, Σ	<code>\sigma, \Sigma</code>	\in	<code>\in</code>
τ	<code>\tau</code>	\pm	<code>\pm</code>
ϕ	<code>\phi</code>	\rightarrow	<code>\rightarrow</code>
ω, Ω	<code>\omega, \Omega</code>	\int	<code>\int</code>

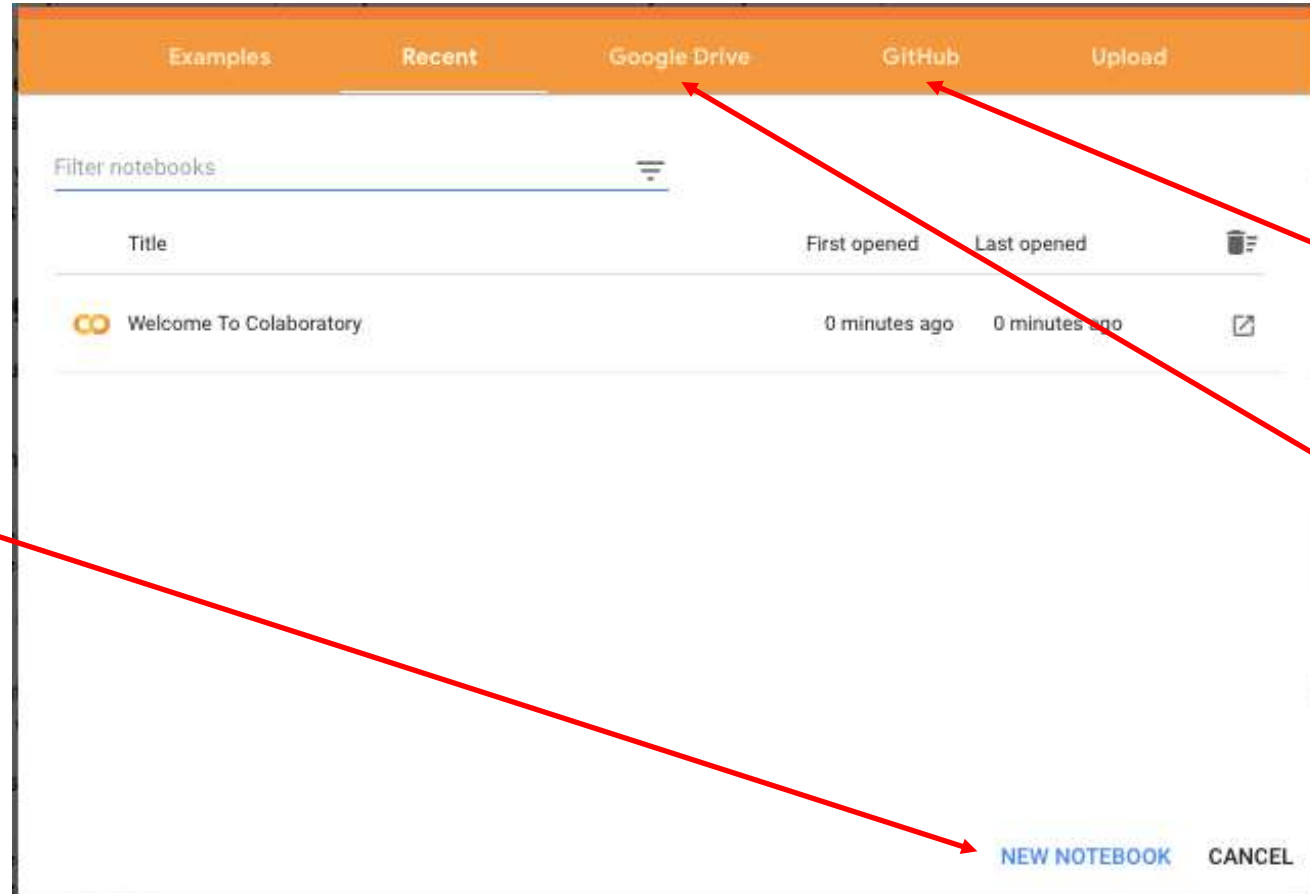
Google Colaboratory



The screenshot displays the Google Colaboratory web interface. At the top, the Google Colaboratory logo is followed by the text "Welcome to Colaboratory". Below this is a menu bar with options: File, Edit, View, Insert, Runtime, Tools, and Help. On the right side of the top bar, there are links for "Share" and "Sign in", along with a settings gear icon. A left-hand sidebar contains a "Table of contents" section with a search icon and a list of items: "Getting started", "Data science", "Machine learning", "More resources", "Featured examples", and a "Section" with a plus icon. The main content area features a large "Welcome to Colab!" heading, followed by a paragraph: "If you're already familiar with Colab, check out this video to learn about int[er] executed code history view and the command palette." Below the text is a video thumbnail titled "3 Cool Google Colab Features" showing a man's face and the TensorFlow logo. The interface also includes a top navigation bar with "+ Code", "+ Text", "Copy to Drive", "Connect", and "Editing" options.

<https://colab.research.google.com/>

Google Colaboratory



Click here to open a new Python 3 ipynb notebook

GitHub

Google Drive

<https://colab.research.google.com/>

Google Colab: Untitled0.ipynb Notebook

The screenshot shows the Google Colab interface for a notebook titled 'Untitled0.ipynb'. The top menu bar includes 'File', 'Edit', 'View', 'Insert', 'Runtime', 'Tools', and 'Help', with a status message 'All changes saved'. On the right, there are buttons for 'Comment', 'Share', a settings gear, and a Google account icon. Below the menu, a toolbar contains '+ Code' and '+ Text' buttons, a 'Connect' dropdown menu, and an 'Editing' mode selector. A code editor area is visible with a cursor. Red arrows point from callout boxes to these elements: one to the '+ Code' button, one to the '+ Text' button, one to the 'Untitled0.ipynb' title, and one to the 'Connect' dropdown. A fifth callout box is positioned below the 'Connect' dropdown.

Annotations:

- Add Code cell
- Add Text cell
- File Name
- Connect to hosted runtime. You can use a Central Processing Unit (CPU), Graphical Processing Unit (GPU) or Tensor Processing Unit (TPU).

Google Colab: Loading Images from the Web and Computer

Loading a figure from the Web:



Copy Image Address from internet



Loading a figure from your computer:

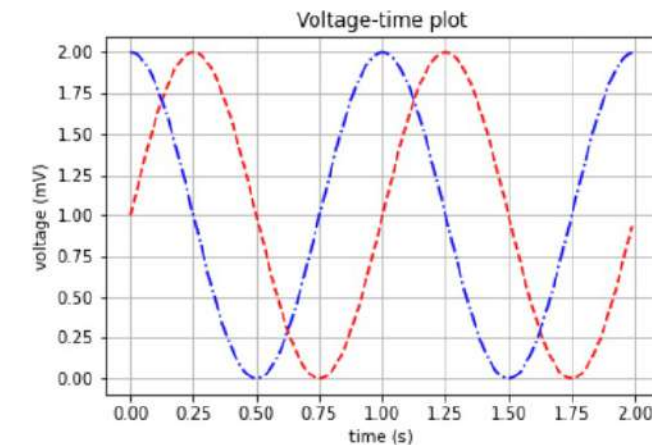
```
[1] from google.colab import files
    from IPython.display import Image
```

```
uploaded = files.upload()
```

Choose Files no files selected

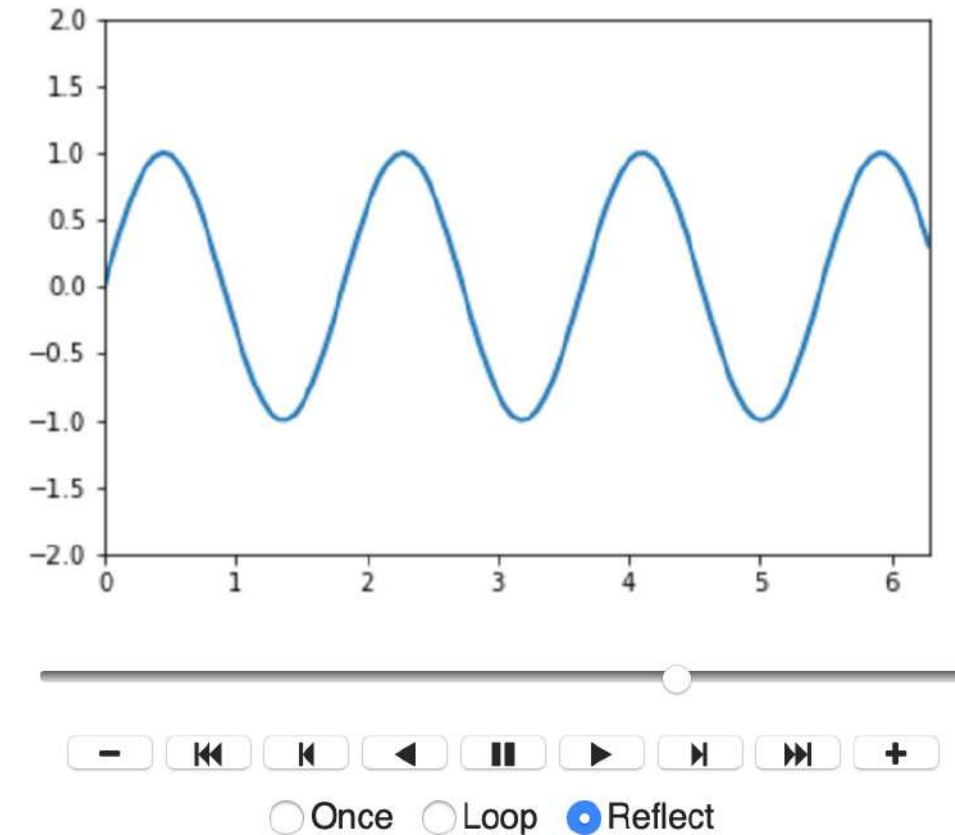
Cancel upload

```
Image('Voltage-Time Plot.png', width = 300)
```



Animation in Google Colab

```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib import animation, rc
from IPython.display import HTML
# Set up figure.
fig, ax = plt.subplots()
plt.close()
# Set domain and range.
ax.set_xlim(( 0, 2 * np.pi))
ax.set_ylim((-2, 2))
# Set line width.
line, = ax.plot([], [], lw=2)
# Draw a clear frame.
def init():
    line.set_data([], [])
    return (line,)
# Function to animate.
def animate(n):
    x = np.linspace(0, 2 * np.pi, 100)
    y = np.sin(0.05 * x * n)
    line.set_data(x, y)
    return (line,)
# Animate. The interval command changes speed of animation.
anim = animation.FuncAnimation(fig, animate, init_func=init,
                              frames=100, interval=100, blit=True)
# Note: below is the part which makes it work on Colab.
rc('animation', html='jshtml')
anim
```



Edit to animate $y = e^{-0.01at} \sin(t)$, for $0 \leq a \leq 50$?

Interactive Plots in Google Colab

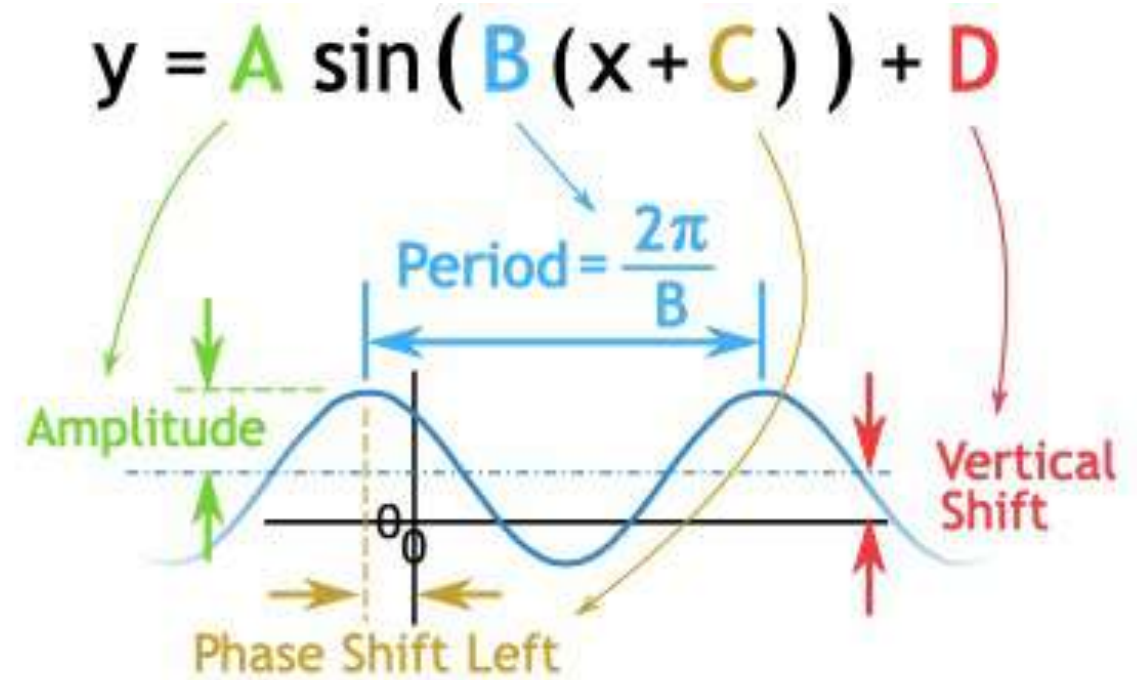
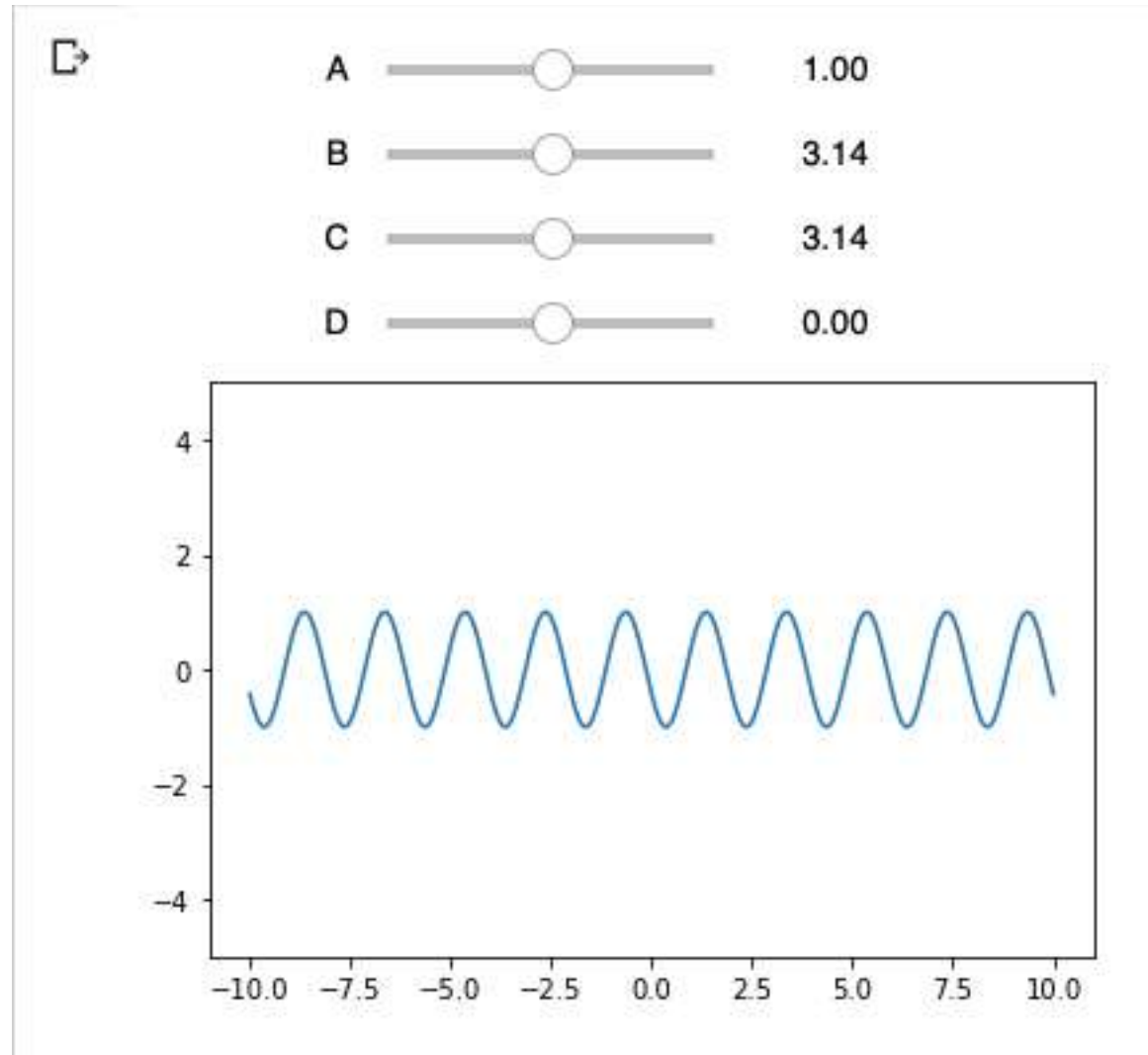
```
# Interactive plots with Python.
from __future__ import print_function
from ipywidgets import interact, interactive, fixed, interact_manual
import ipywidgets as widgets

%matplotlib inline
from ipywidgets import interactive
import matplotlib.pyplot as plt
import numpy as np

def f(A, B, C, D):
    plt.figure(2)
    x = np.linspace(-10, 10, num=1000)
    plt.plot(x, A * np.sin(B * (x + C)) + D)
    plt.ylim(-5, 5)
    plt.show()

interactive_plot = interactive(f, A=(0, 2.0), B = (0, 2 * np.pi), \
                               C = (0, 2 * np.pi), D = (-3, 3, 0.5))
output = interactive_plot.children[-1]
output.layout.height = '350px'
interactive_plot
```


Interactive Plots in Google Colab: End Session 1



Biology: Population of Blowfly: Start Session 2

$x_{n+1} = \mu x_n(1 - x_n)$, x_n is population and μ is a parameter.

```
# Program_6a.py: Iteration of the logistic map function.
import numpy as np
import matplotlib.pyplot as plt
mu , x = 4 , 0.2          # For case (iv).
xs = [0.2]                # Initially, 20% of the tank is full.
for i in range(50):
    x = mu * x * (1 - x)
    xs = np.append(xs , x)
    #print(x)             # Print the x values if you like.
plt.plot(xs)
plt.xlabel("n")
plt.ylabel("$x_n$")
plt.show()
```



Biology: The Logistic Map

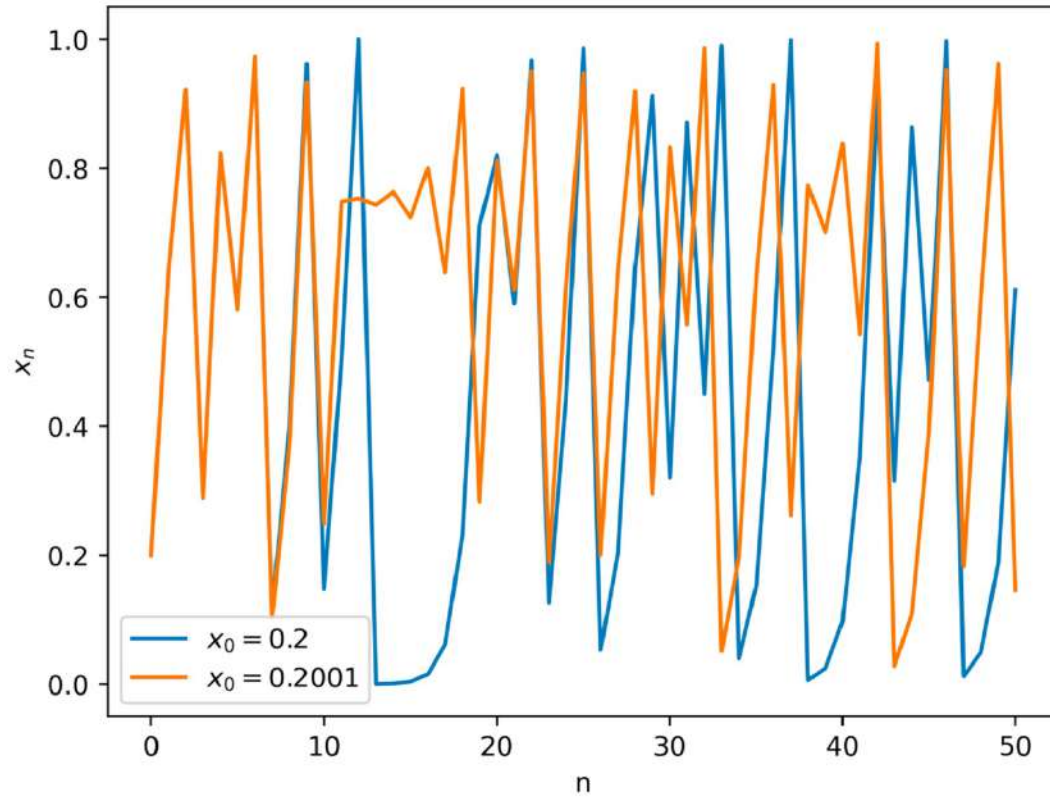


Figure: Sensitivity to initial conditions: chaos.

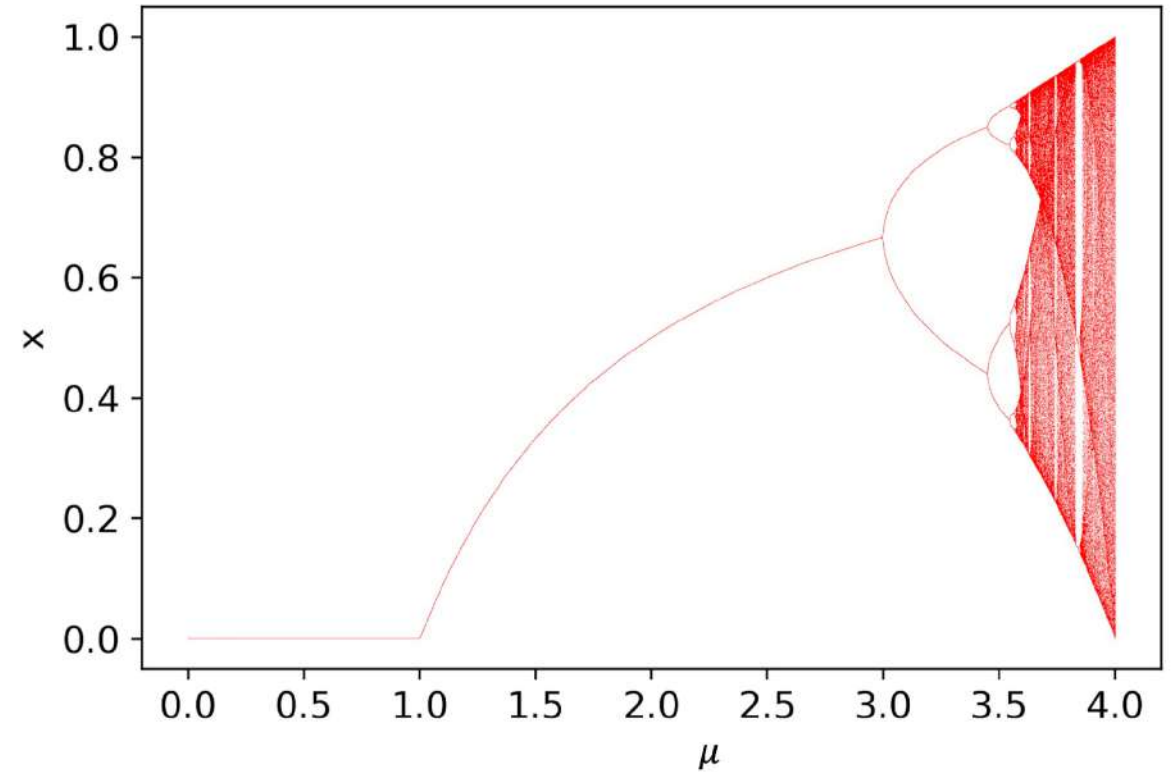
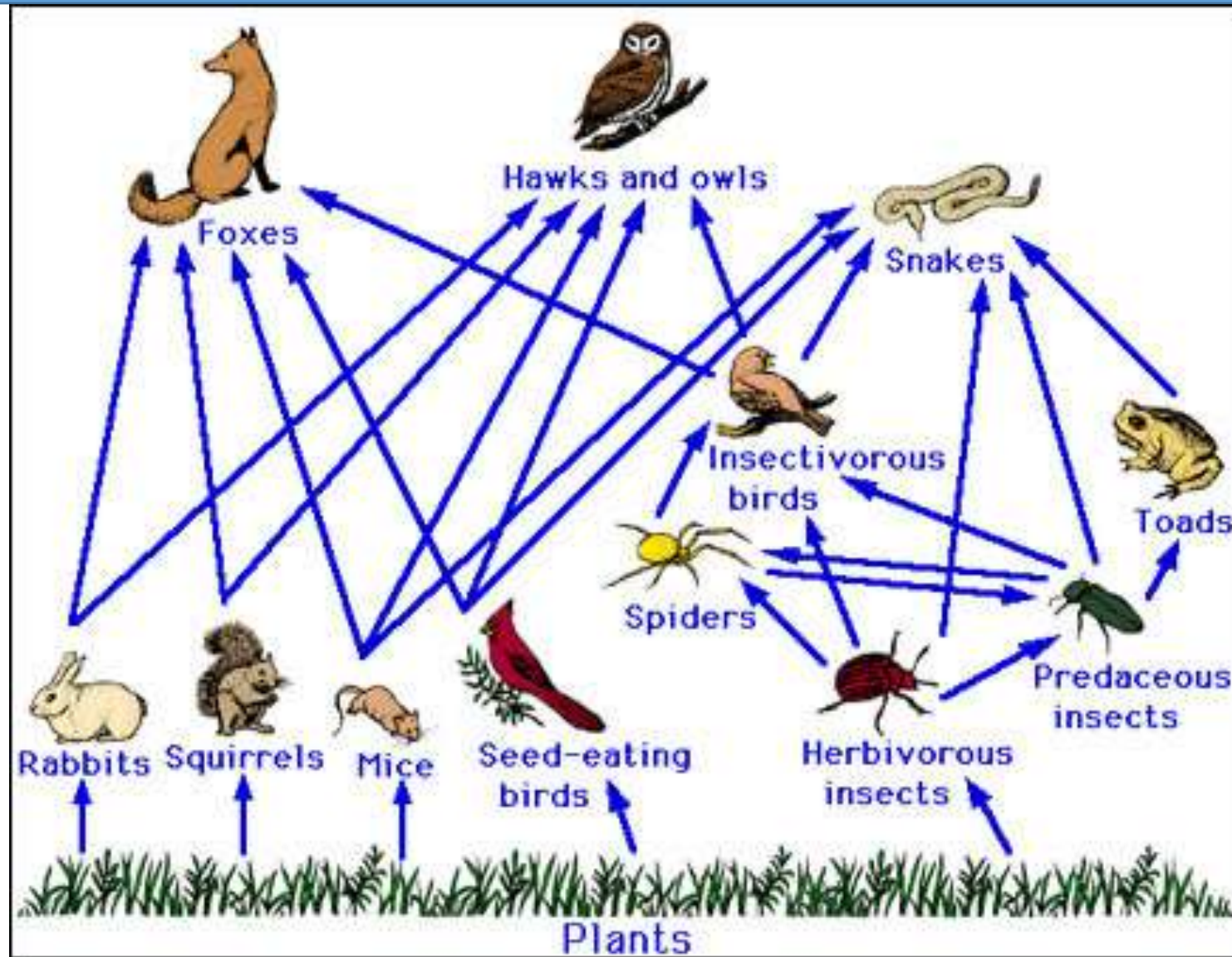


Figure: Bifurcation diagram.

Interacting Species in the UK



The Holling-Tanner Model: Predator-Prey

Consider the specific Holling–Tanner model

$$\dot{x} = x \left(1 - \frac{x}{7}\right) - \frac{6xy}{(7 + 7x)}, \quad \dot{y} = 0.2y \left(1 - \frac{Ny}{x}\right)$$



Fig. Predator-Prey: Lynx and snowshoe hare.

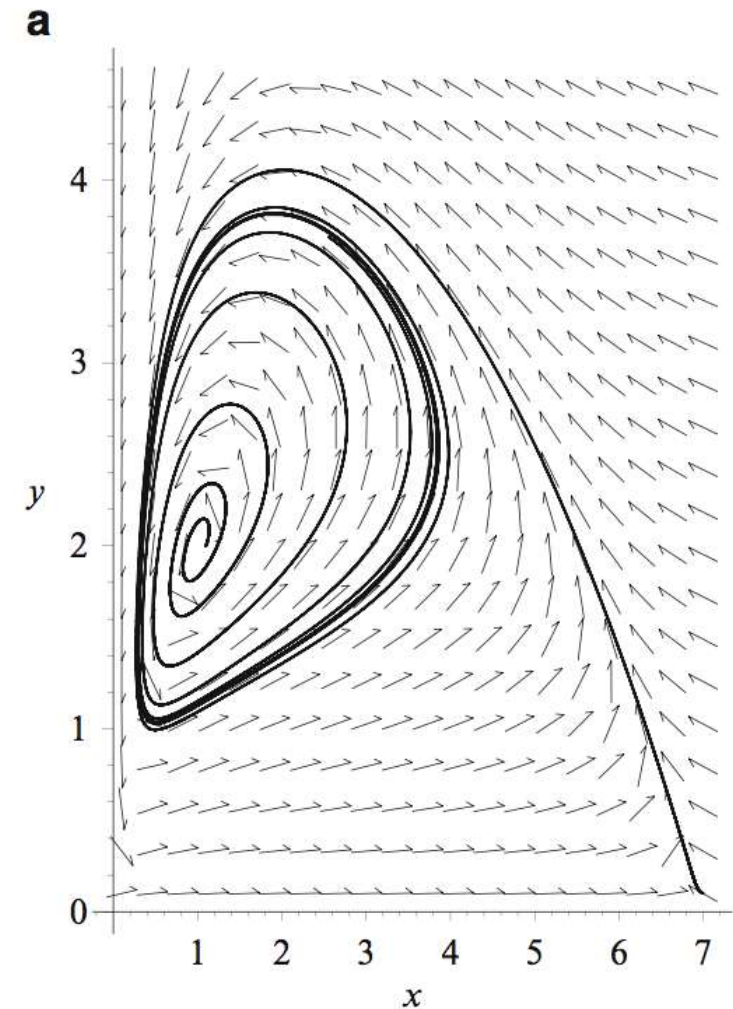
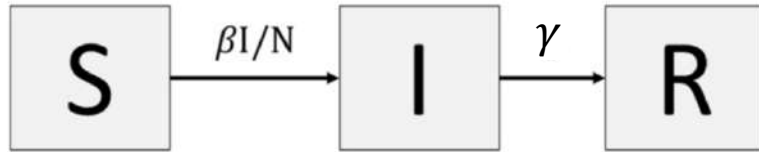


Fig. A limit cycle of the Holling-Tanner Model

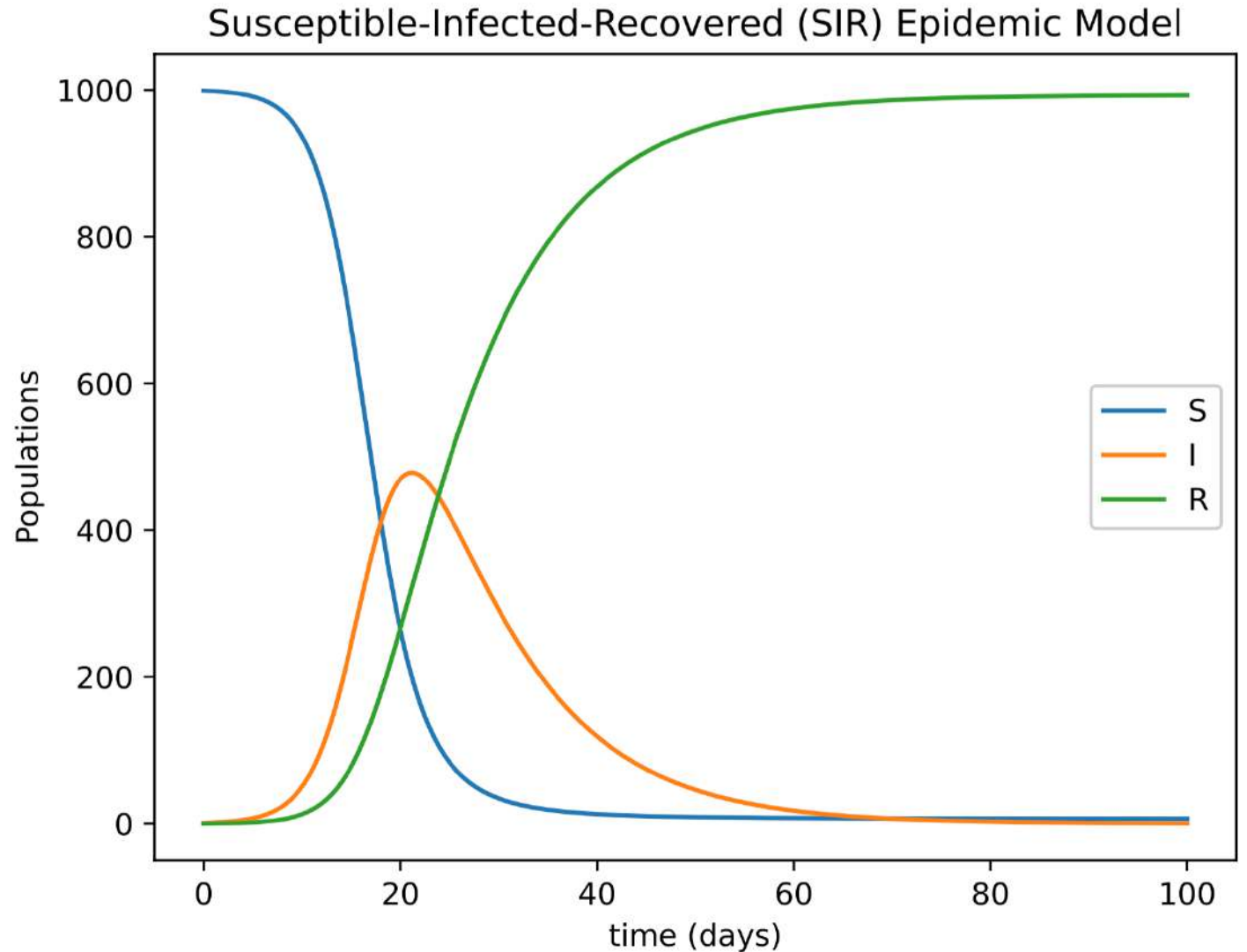
Modelling Epidemics with ODEs



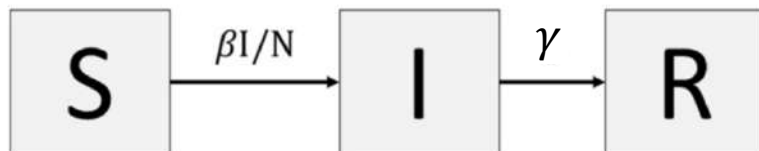
$$\frac{dS}{dt} = -\frac{\beta SI}{N},$$

$$\frac{dI}{dt} = \frac{\beta SI}{N} - \gamma I,$$

$$\frac{dR}{dt} = \gamma I.$$



Modelling Epidemics with ODEs



$$\frac{dS}{dt} = -\frac{\beta SI}{N},$$

$$\frac{dI}{dt} = \frac{\beta SI}{N} - \gamma I,$$

$$\frac{dR}{dt} = \gamma I.$$

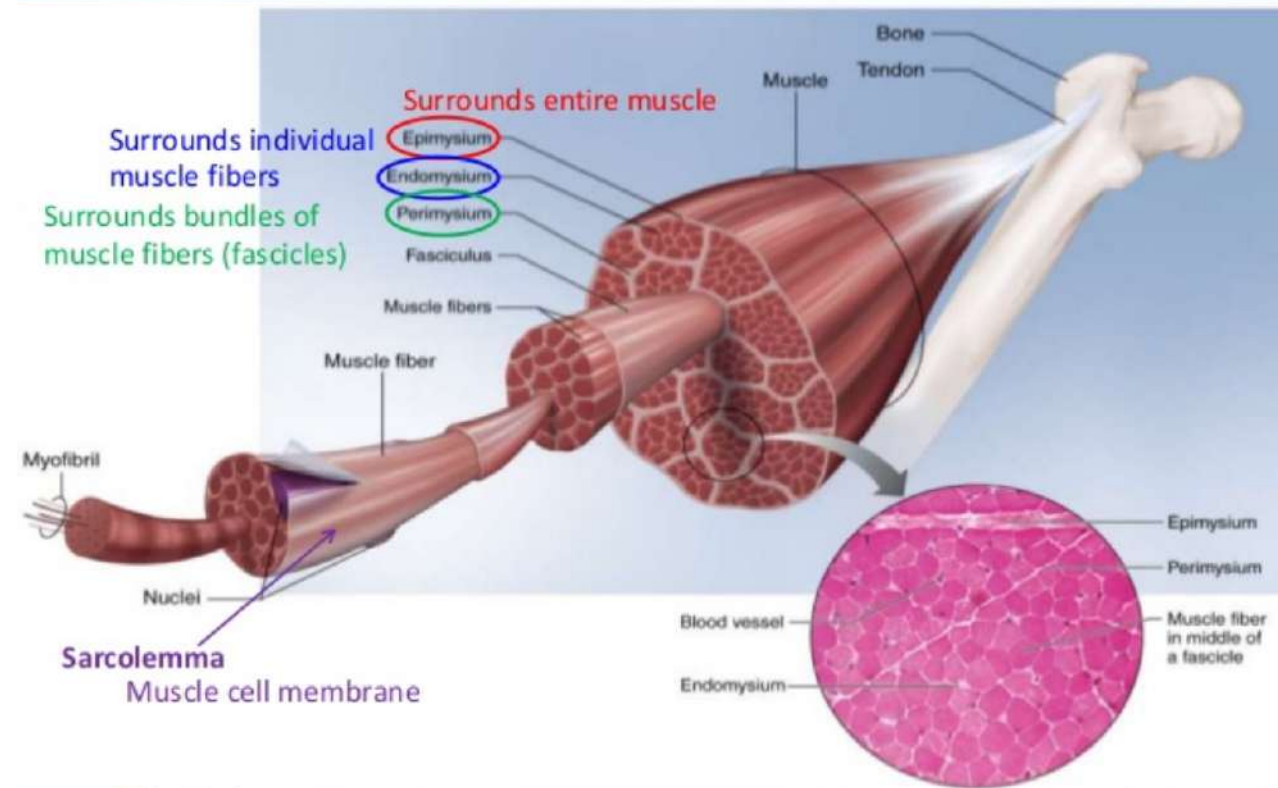
```
# Program_6e.py: SIR Epidemic model.
import numpy as np
import matplotlib.pyplot as plt
from scipy.integrate import odeint
# Set the parameters.
beta, gamma = 0.5, 0.1
S0, I0, R0, N = 999, 1, 0, 1000
tmax, n = 100, 1000
def SIR_Model(X, t, beta, gamma):
    S, I, R = X
    dS = - beta * S * I / N
    dI = beta * S * I / N - gamma * I
    dR = gamma * I
    return(dS, dI, dR)
t = np.linspace(0, tmax, n)
f = odeint(SIR_Model, (S0, I0, R0), t, args = (beta, gamma))
S, I, R = f.T
plt.figure(1)
plt.xlabel("Time (days)")
plt.ylabel("Populations")
plt.title("Susceptible-Infected-Recovered (SIR) Epidemic Model")
plt.plot(t, S, label = "S")
plt.plot(t, I, label = "I")
plt.plot(t, R, label = "R")
legend = plt.legend(loc = "best")
plt.show()
```

Muscle Model

Types of Muscle Contraction

- Concentric contraction: Force is developed while the muscle is shortening
- Isometric contraction: Force is generated but the length of the muscle is unchanged
- Eccentric contraction: Force is generated while the muscle is lengthening

Structure of Muscle



Muscle Model (Modelling with Springs and Dampers)

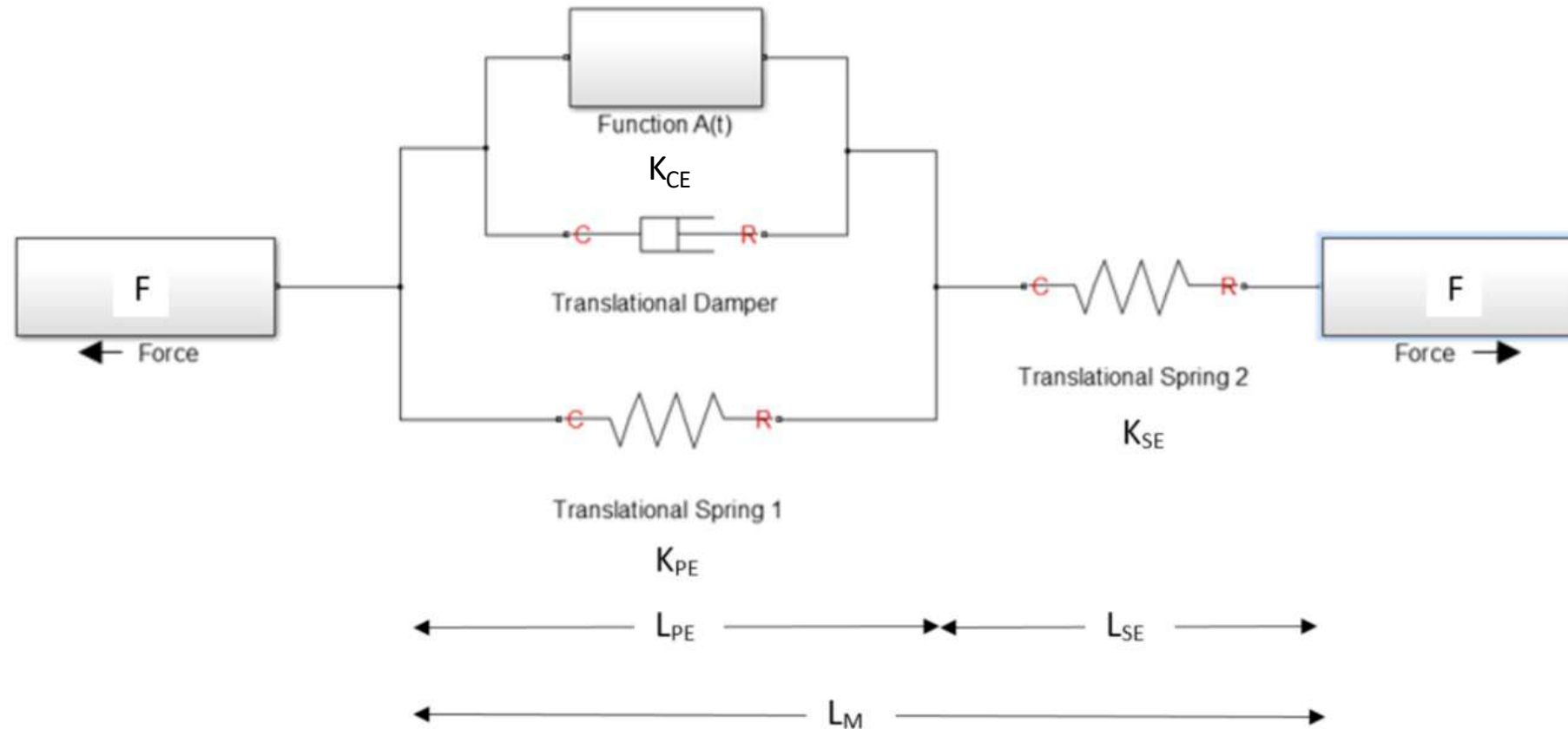
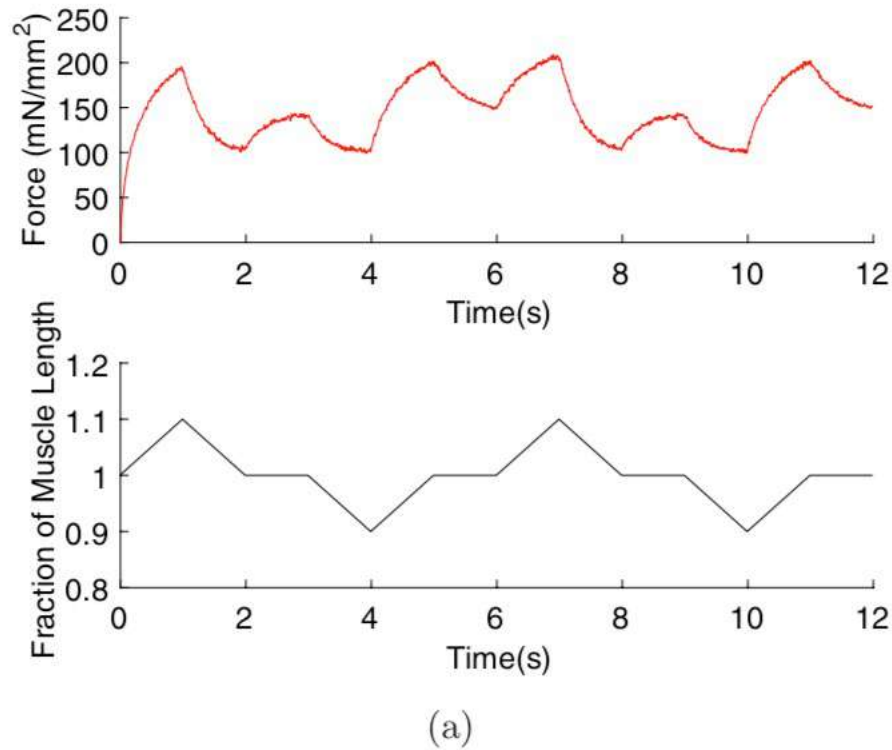


Fig. 18. A Simscape simulation of the Hill muscle model comprising of a series element (SE), a contractile element (CE) and a parallel element (PE).

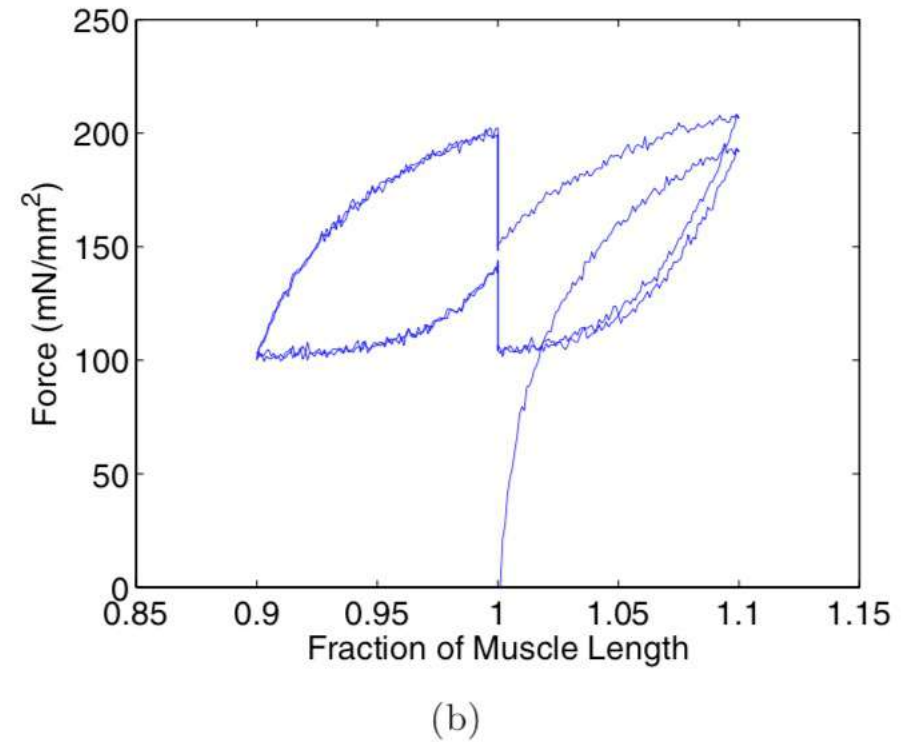
Muscle Model (Python Program of Hill Model)

```
1  # Muscle Hill model.
2  import numpy as np
3  import matplotlib.pyplot as plt
4
5  # From Hill's paper.
6  Length, a, b = 1200, 380 * 0.098, 0.325
7  P0 = a / 0.257
8  vm = P0 * b / a
9  alpha = P0 / 0.1
10 LSE0 = 0.3
11 k = a / 25
12
13 t = [0 + 0.01 * i for i in range(1201)]      # Time
14
15 # Stretching, holding and contracting muscle.
16 A = [1.001 + 0.001 * i for i in range(100)] # Length A.
17 B = [1.099 - 0.001 * i for i in range(100)] # Length B.
18 C = np.ones(100).tolist()                  # Length C.
19 D = [0.999 - 0.001 * i for i in range(100)]
20 E = [0.901 + 0.001 * i for i in range(100)]
21 F = np.ones(100).tolist()
22 G = [1.001 + 0.001 * i for i in range(100)]
23 H = [1.099 - 0.001 * i for i in range(100)]
24 HH = np.ones(100).tolist()
25 J = [0.999 - 0.001 * i for i in range(100)]
26 K = [0.901 + 0.001 * i for i in range(100)]
27 KK = np.ones(101).tolist()
28 L = A+B+C+D+E+F+G+H+HH+J+K+KK
29
30 # Muscle model continued...
31 LSE = np.zeros(1200).tolist()
32 LCE = np.zeros(1200).tolist()
33 P = np.zeros(1201).tolist()
34
35 # Hill's differential equations.
36 for i in range(1200):
37     LSE[i] = 0.3 * P[i] / alpha
38     LCE[i] = L[i] - LSE[i]
39     dt = t[i + 1] - t[i]
40     dL = L[i + 1] - L[i]
41     dP = alpha * ((dL/dt) + b * ((P0 - P[i]) / (a + P[i]))) * dt
42     P[i + 1] = P[i] + dP
43
44 P = np.array(P)
45 PP = (P0 / 100) * np.random.randn(1201) # Add some noise.
46 P = P + PP
47 P = P.tolist()
48
49 plt.figure()
50 plt.plot(L, P) # Plot length v Force.
51 plt.xlabel('Fraction of Muscle Length mm', fontsize = 15)
52 plt.ylabel('Force ($mN / mm^2$)', fontsize = 15)
53 plt.tick_params(labelsize = 15)
```


Muscle Model (Lengthening and Shortening)

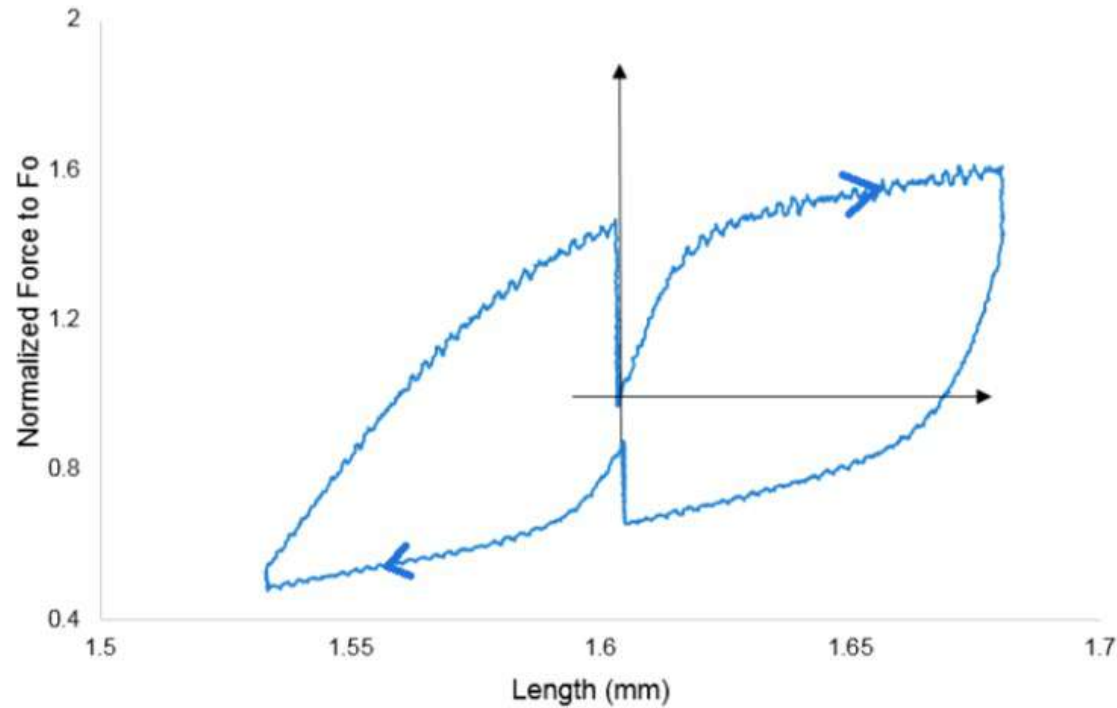


Lengthening and shortening with rests.

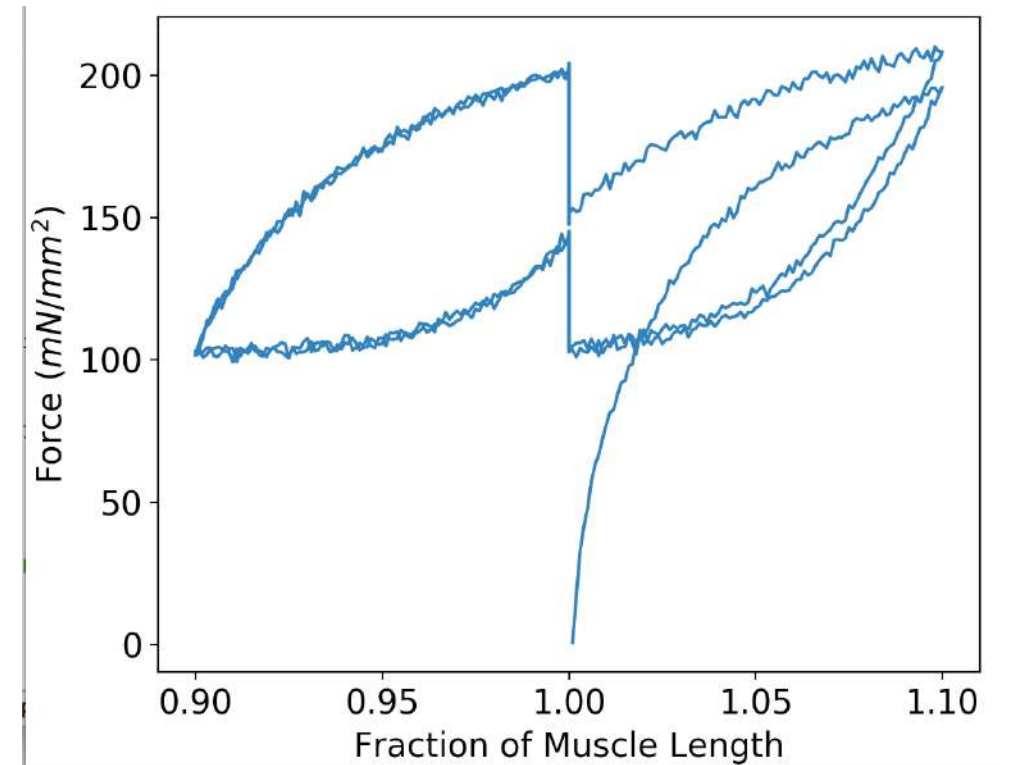


Hysteresis curves from modelling.

Muscle Mode



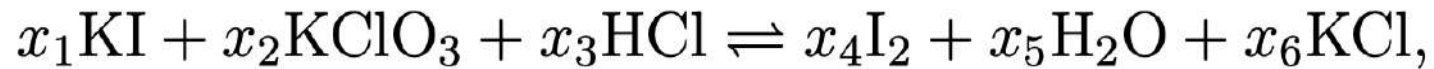
Hysteresis curves from experiment.



Hysteresis curves from modelling.

Ramos J, **Lynch S**, Jones DA & Degens H (2017) Hysteresis in muscle (Feature Article), International Journal of Bifurcation and Chaos 27, 1730003, 1-16.

Chemistry: Balancing Chemical Equations



Chemical Composition Table

Element	KI	KClO ₃	HCl	I ₂	H ₂ O	KCl
K	1	1	0	0	0	1
I	1	0	0	2	0	0
O	0	3	0	0	1	0
H	0	0	1	0	2	0
Cl	0	1	1	0	0	1

Chemistry: Balancing Chemical Equations

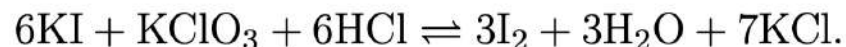
```
# Program_7a.py: Compute the matrix null-space vector.
from sympy import Matrix
# Construct the augmented matrix.
ACCM=Matrix([[1,1,0,0,0,1],\
             [1,0,0,2,0,0],\
             [0,3,0,0,1,0],\
             [0,0,1,0,2,0],\
             [0,1,1,0,0,1],\
             [0,0,0,0,0,1]])

print(ACCM)
invACCM=ACCM.inv() # Find the inverse matrix.
print(invACCM)
Nullv=invACCM.col(5) / min(abs(invACCM.col(5))) # Last column.
print(Nullv) # Scaled null-space vector.
```

The solution is, Nullv=Matrix([[−6], [−1], [−6], [3], [3], [7]]), giving:

$$x_1 = 6, x_2 = 1, x_3 = 6, x_4 = 3, x_5 = 3, x_6 = 7,$$

and the balanced chemical-reaction equation is:



Chemical Kinetics: A Simple Model

```
# Chemical kinetics - conservation of mass.
import numpy as np
from scipy.integrate import odeint
import matplotlib.pyplot as plt
# Set parameters and initial conditions
r1, r2 = 0.01, 0.02
x0, y0, z0 = 1000, 0, 0
# Maximum time point and total number of time points
tmax, n = 500, 10000
def Chemical_Kinetics(X, t, r1, r2):
    #The Differential Equations
    x, y, z = X
    dx = -r1 * x
    dy = r1 * x - r2 * y
    dz = r2 * y
    return (dx, dy, dz)
# Integrate differential equations on the time grid t.
t = np.linspace(0, tmax, n)
f = odeint(Chemical_Kinetics, (x0, y0, z0), t, args=(r1, r2))
x, y, z = f.T
plt.figure(1)
plt.xlabel("Time")
plt.ylabel("Concentrations")
plt.title("Chemical Kinetics")
plt.plot(t, x, label="|A|")
plt.plot(t, y, label="|B|")
plt.plot(t, z, label="|C|")
legend = plt.legend(loc="best")
plt.show()
```

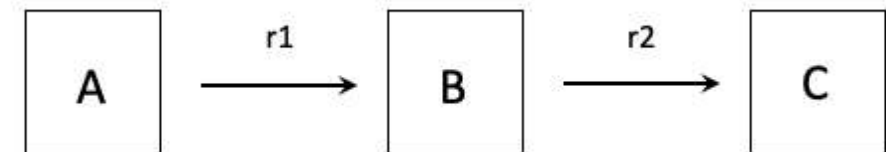
Compartmental Model

$|A| = x, |B| = y, |C| = z$

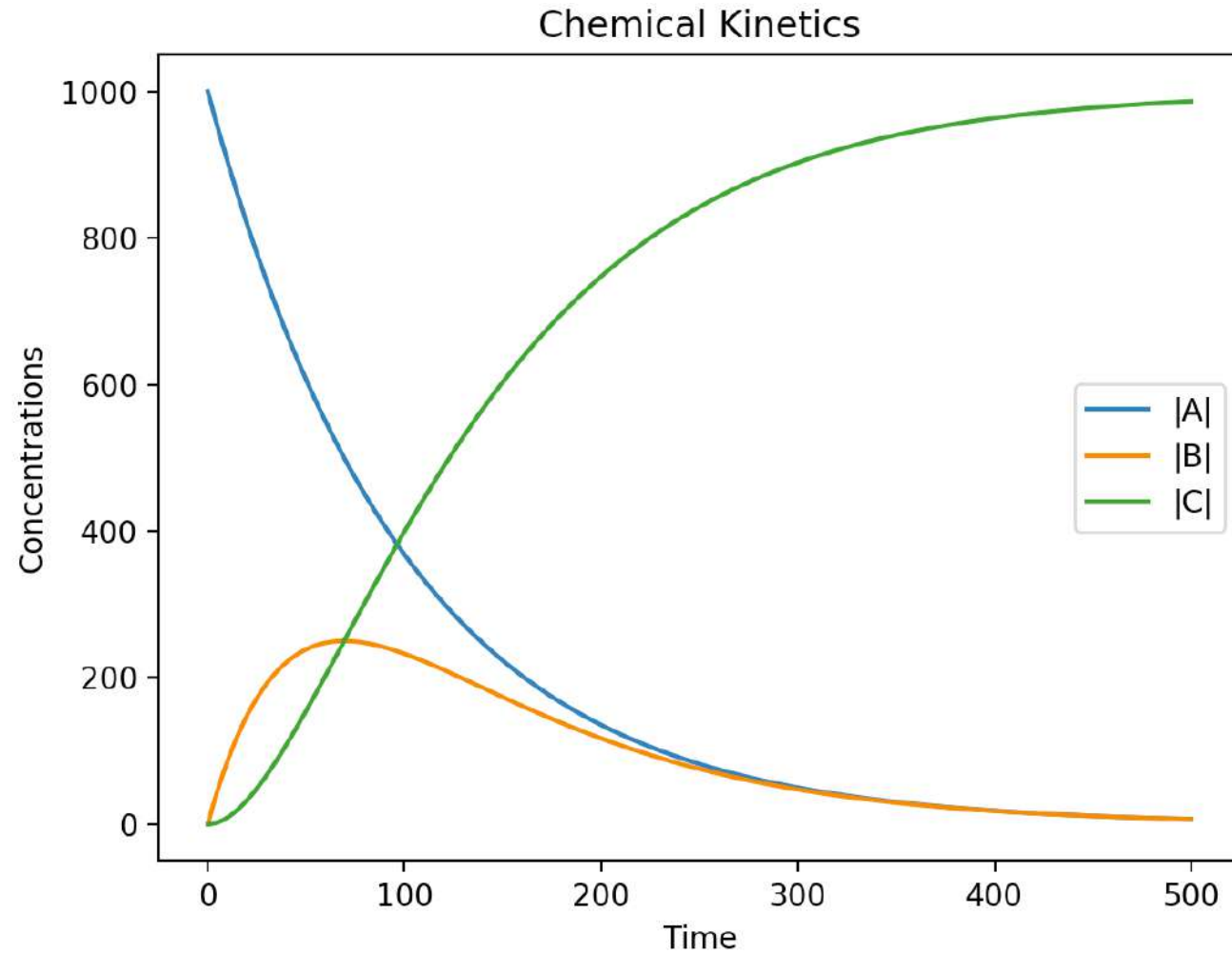
$$\frac{dx}{dt} = -r_1 x$$

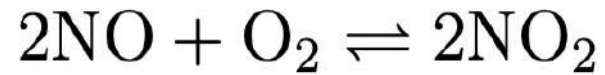
$$\frac{dy}{dt} = r_1 x - r_2 y$$

$$\frac{dz}{dt} = r_2 y$$

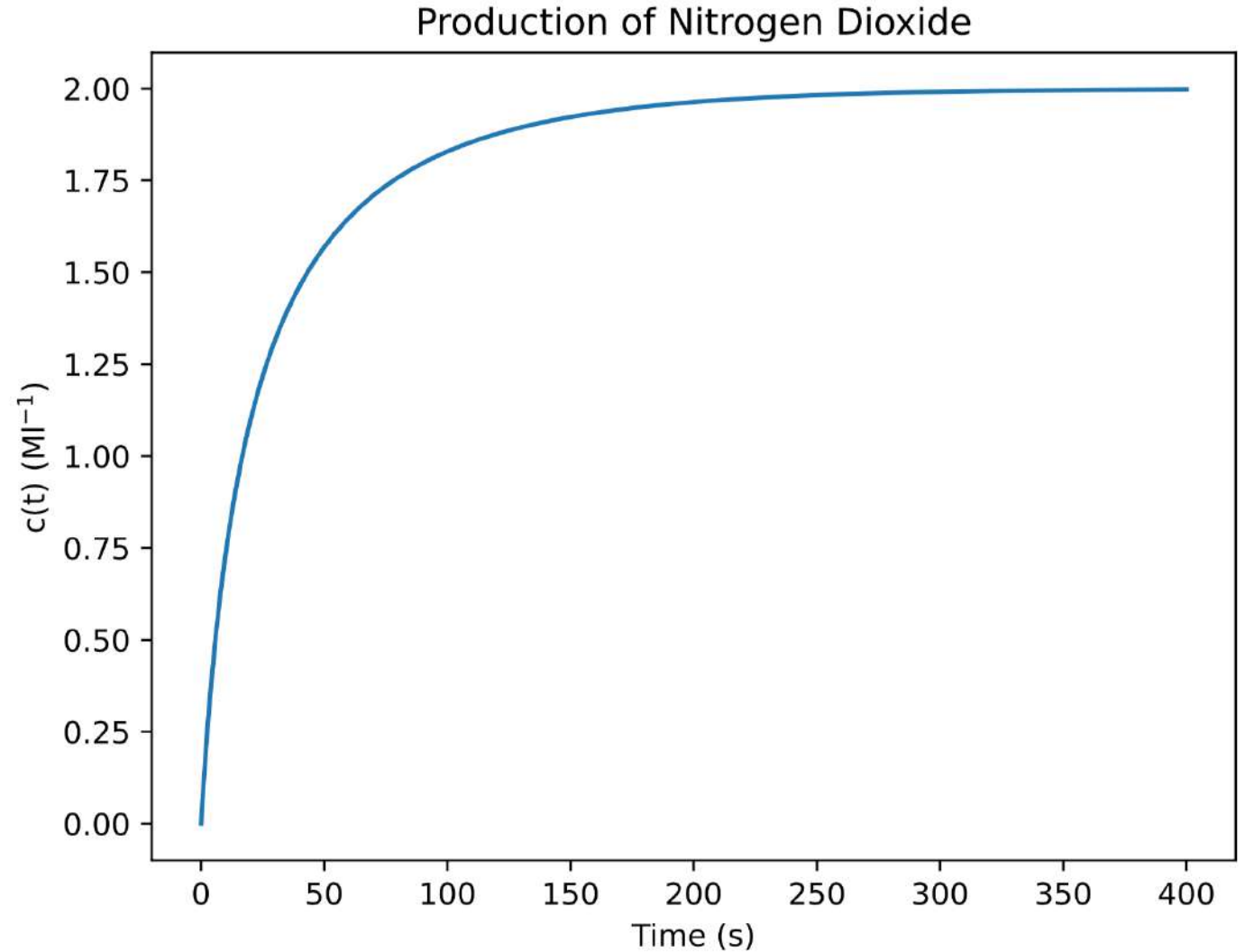


Chemical Kinetics: A Simple Model





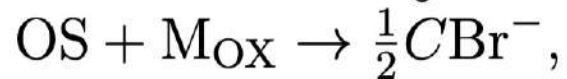
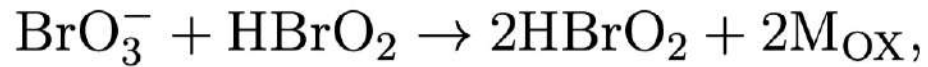
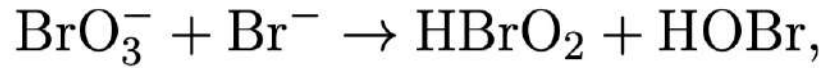
$$\frac{dc}{dt} = k (a_0 - c)^2 \left(b_0 - \frac{c}{2} \right)$$



Chemistry: Chemical Kinetics and ODEs

```
# Program_7b.py: Production of Nitrogen Dioxide.
import numpy as np
import matplotlib.pyplot as plt
from scipy.integrate import odeint
k , a0 , b0 , c0 = 0.00713 , 4 , 1, 0
def ode(c , t):
    dcdt = k * (a0 - c)**2 * (b0 - c / 2)
    return dcdt
t = np.linspace(0 , 400 , 401) # t=[0,1,2,...,400]
c = odeint(ode , c0 , t)
plt.xlabel("Time (s)")
plt.ylabel("c(t) (Ml-1)")
plt.title("Production of Nitrogen Dioxide")
plt.plot(t , c)
print("c(100) = ", c[100], "Moles per litre")
plt.show()
```


Chemistry: Oscillating Chemical Reactions



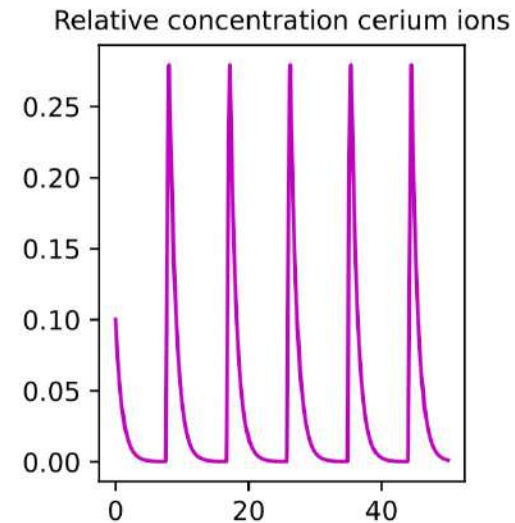
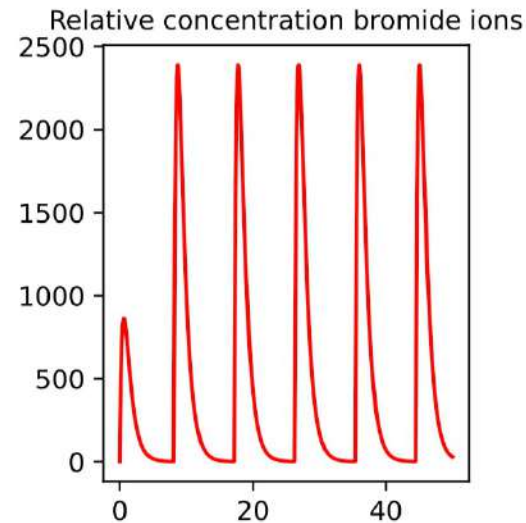
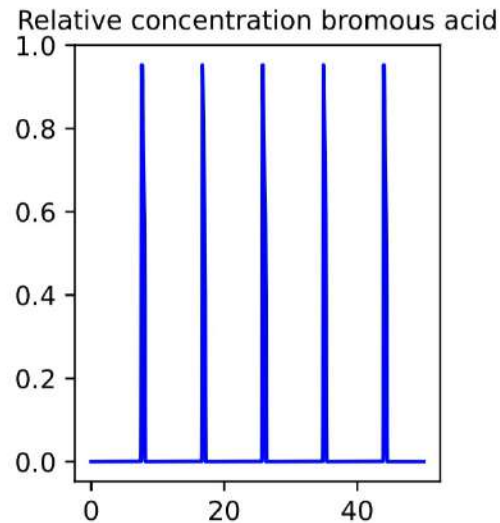
$$\text{Rate} = k_1[\text{BrO}_3^-][\text{Br}^-]$$

$$\text{Rate} = k_2[\text{HBrO}_2][\text{Br}^-]$$

$$\text{Rate} = k_3[\text{BrO}_3^-][\text{HBrO}_2]$$

$$\text{Rate} = k_4[\text{HBrO}_2]^2$$

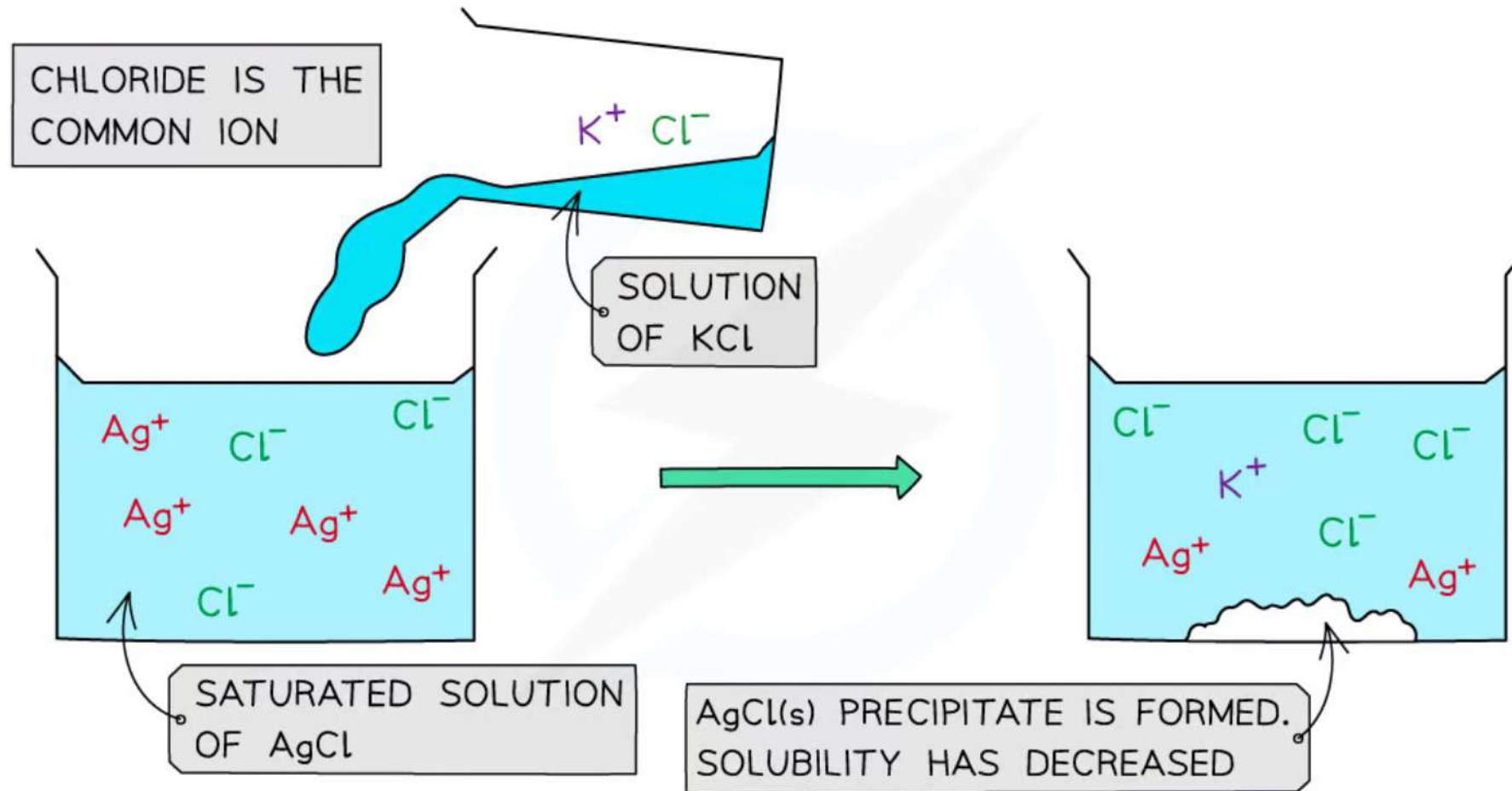
$$\text{Rate} = k_5[\text{OS}][\text{M}_{\text{OX}}]$$



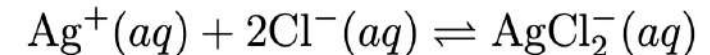
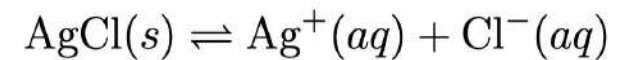
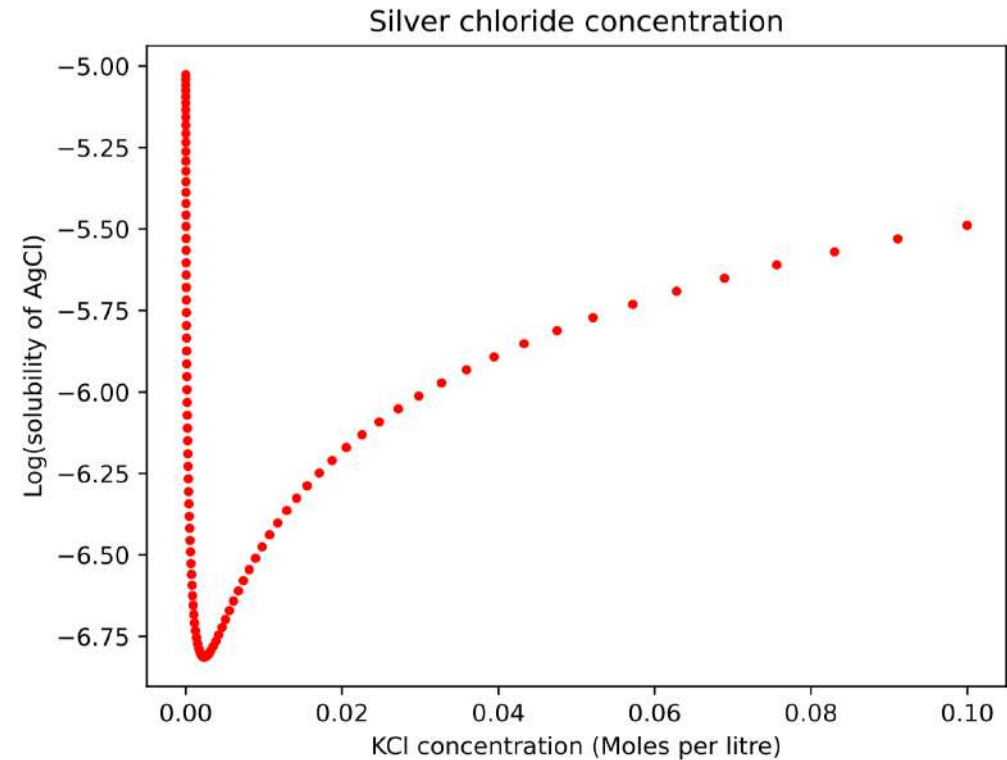
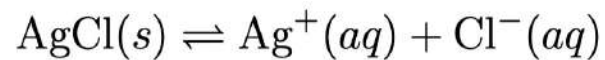
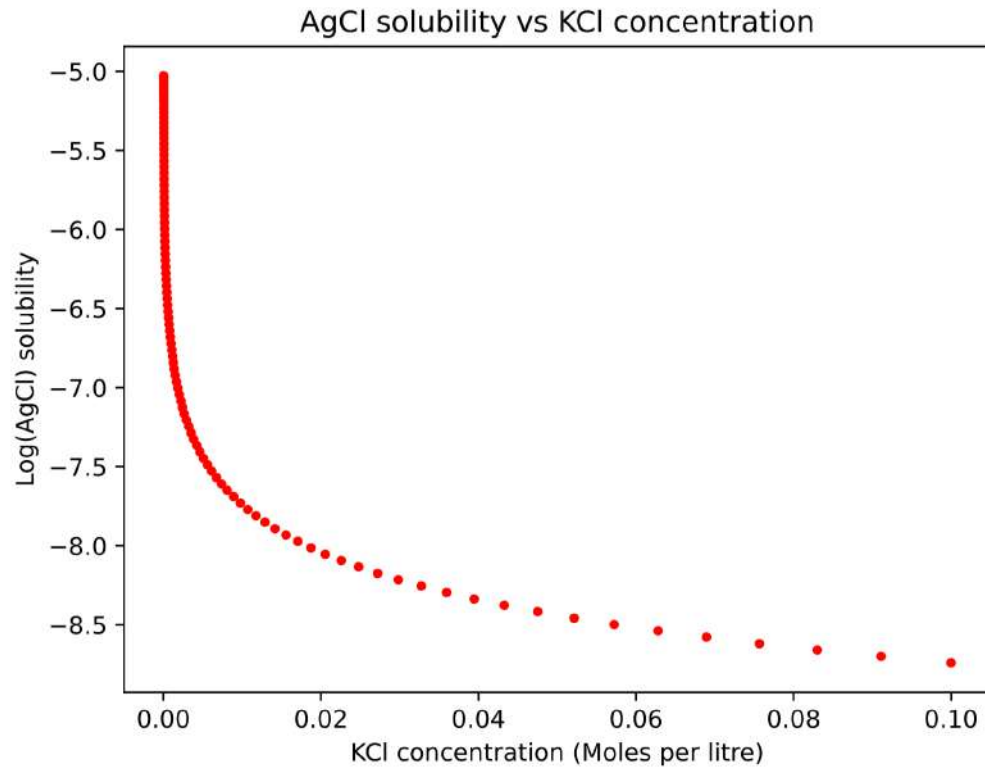


Chemical Oscillation - Belousov-Zhabotinsky reaction

Chemistry: Common Ion Effect in Solubility



Chemistry: Common Ion Effect Silver Chloride: End Session 2



Data Science: Pandas and Drug Efficacy: Start Session 3

```
# Program_8a.py: Create a data frame for drug efficacy.
import numpy as np
import pandas as pd
df1=pd.DataFrame({
    "Date": pd.Timestamp("20220125"),
    "Dosage (mg)": np.array(list(range(2,22,2))),
    "Sex " : pd.Categorical(["F","F","M","F","M",
                           "M","F","F","F","M"]),
    "Weight (Kg)" : pd.Series([52.2,65.8,80.7,53.5,40.9,
                              52.2,64.4,61.7,53.5,61.2],
                              dtype="float32"),
    "Efficacy (%)" : pd.Series([0,0,0,0,5,
                               20,90,100,100,100],dtype="int32")
})
df2=pd.DataFrame({
    "Date": pd.Timestamp("20220126"),
    "Dosage (mg)": np.array(list(range(22,42,2))),
    "Sex " : pd.Categorical(["M","M","F","M","M",
                           "F","M","F","F","M"]),
    "Weight (Kg)" : pd.Series([
        86.2,72.6,59.0,67.1,56.2,
        61.2,78.0,45.3,54.4,88.9],
        dtype="float32"),
    "Efficacy (%)" : pd.Series([
        70,65,55,50,50,
        45,10,0,0,0],dtype="int32")
})
df = pd.concat([df1 , df2] , ignore_index = True)
df
```

	Date	Dosage (mg)	Sex	Weight (Kg)	Efficacy (%)
0	2022-01-25	2	F	52.200001	0
1	2022-01-25	4	F	65.800003	0
2	2022-01-25	6	M	80.699997	0
3	2022-01-25	8	F	53.500000	0
4	2022-01-25	10	M	40.900002	5
5	2022-01-25	12	M	52.200001	20
6	2022-01-25	14	F	64.400002	90
7	2022-01-25	16	F	61.700001	100
8	2022-01-25	18	F	53.500000	100
9	2022-01-25	20	M	61.200001	100
10	2022-01-26	22	M	86.199997	70
11	2022-01-26	24	M	72.599998	65
12	2022-01-26	26	F	59.000000	55
13	2022-01-26	28	M	67.099998	50
14	2022-01-26	30	M	56.200001	50
15	2022-01-26	32	F	61.200001	45
16	2022-01-26	34	M	78.000000	10
17	2022-01-26	36	F	45.299999	0
18	2022-01-26	38	F	54.400002	0
19	2022-01-26	40	M	88.900002	0

Data Science: Pandas

Python Command Lines	Comments
In[1]: df.dtypes	# Lists data types of columns.
In[2]: df.head()	# Lists the first 5 rows of df.
In[3]: df.head(10)	# Lists the first 10 rows of df.
In[4]: df.tail(3)	# Lists the last 3 rows of df.
In[5]: df.index	# Lists the range index.
In[6]: df.columns	# Lists the column headings.
In[7]: df.describe	# Statistics of numerical columns.
In[8]: df["Dosage (mg)"]	# Select a single column.
In[9]: df.sort_values(by="Weight (Kg)")	# Sort data by one column.
In[10]: df.loc[1 : 3]	# Slice rows.
In[11]: df[12 :]	# Slice rows.
In[12]: df.iloc[19]	# Lists data in index 19.
In[13]: df.iloc[1 : 3 , 0 : 2]	# Slice rows and columns using index.
In[14]: df.iat[2 , 2]	# Data in row 3, column 3.
In[15]: df[df["Weight (Kg)"]>60]	# Weights bigger than 60kg.
In[16]: df.to_csv("Drug_Trial.csv")	# Writes to csv file.
In[17]: pd.csv_read("Drug_Trial.csv")	# Loads csv file.
In[18]: df.to_excel("Drug_Trial.xlsx")	# Writes to excel file.
In[19]: df.T	# Transpose the data.
In[20]: df.dropna()	# Drop rows with NaN entries.

Data Science: Linear Programming

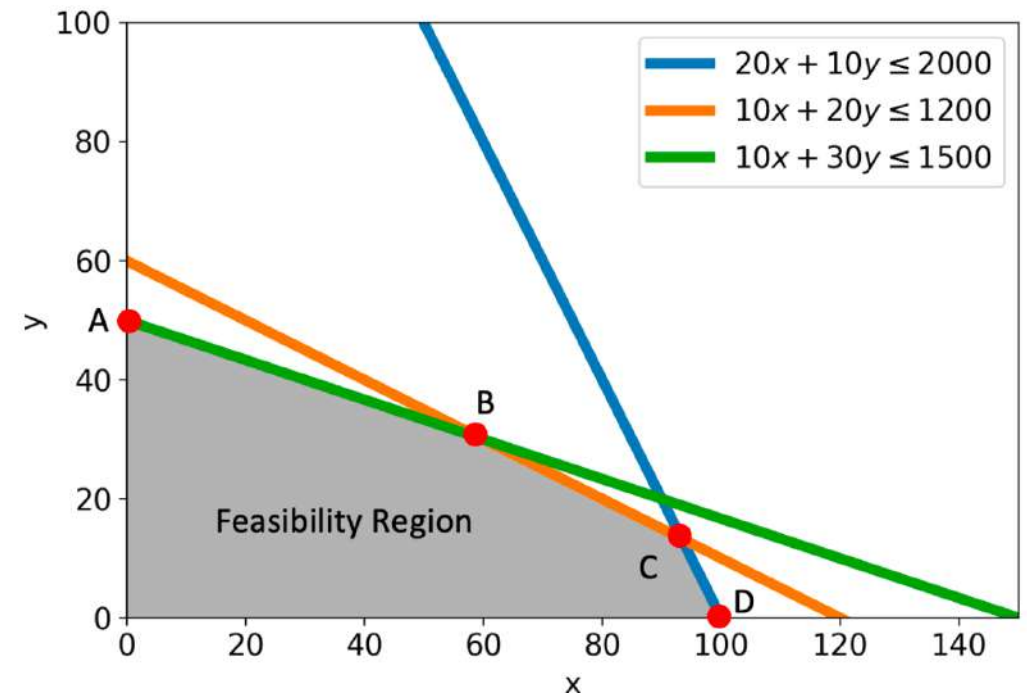
```
# Program_8b.py: Plotting the feasibility region and maximizing profit.
# Maximize P = 5x+12y, given 20x+10y<=2000, 10x+20y<=1200,10x+30y<=1500.
# x,y >= 0.
import numpy as np
import matplotlib.pyplot as plt
m = np.linspace(0,200,200)
x , y = np.meshgrid(m , m)
plt.imshow(((x>=0) & (y>=0) & (20*x+10*y<=2000) & (10*x+20*y<=1200) \
           & (10*x+30*y<=1500)).astype(int) , extent=(x.min(),x.max(), \
           y.min(),y.max()),origin="lower",cmap="Greys",alpha=0.3)
```

```
# Plot the constraint lines.
x = np.linspace(0, 200, 200)
y1 = (-20*x+2000) / 10
y2 = (-10*x+1200) / 20
y3 = (-10*x+1500) / 30
plt.rcParams["font.size"] = "14"
plt.plot(x, y1, label=r"$20x+10y \leq 2000$", linewidth = 4)
plt.plot(x, y2, label=r"$10x+20y \leq 1200$", linewidth = 4)
plt.plot(x, y3, label=r"$10x+30y \leq 1500$", linewidth = 4)
# The maximum profit line.
# plt.plot(x , (-5 * x + 660) / 12 , label = r"$P_{\max}=5x+12y$")
plt.xlim(0,150)
plt.ylim(0,100)
plt.xlabel("x")
plt.ylabel("y")
plt.legend()
plt.show()
```

$$P = 5x + 12y.$$

$$10x + 30y \leq 1500, \quad 20x + 10y \leq 2000, \quad 10x + 20y \leq 1200,$$

$$x \geq 0, \quad y \geq 0.$$



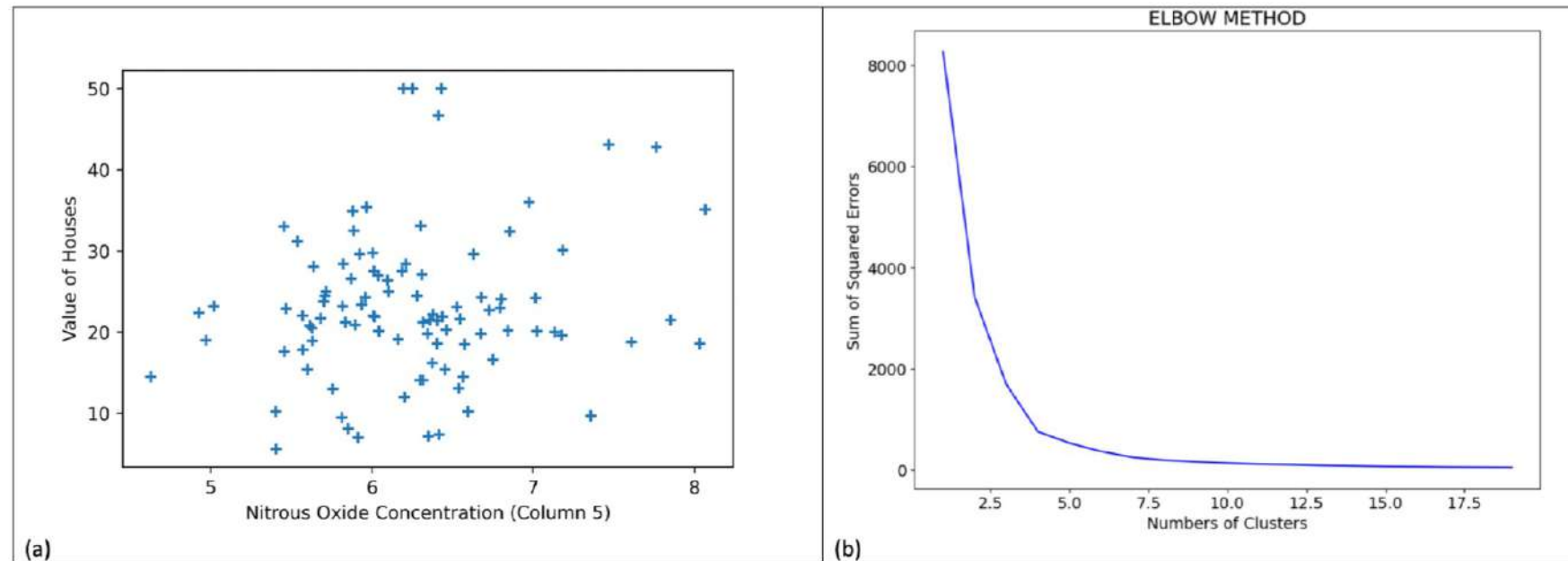


Figure 8.3 (a) Data from column five of the Boston-housing data. (b) The elbow method to determine the number of clusters.

Data Science: Program_8g.py: Clusters and Outliers

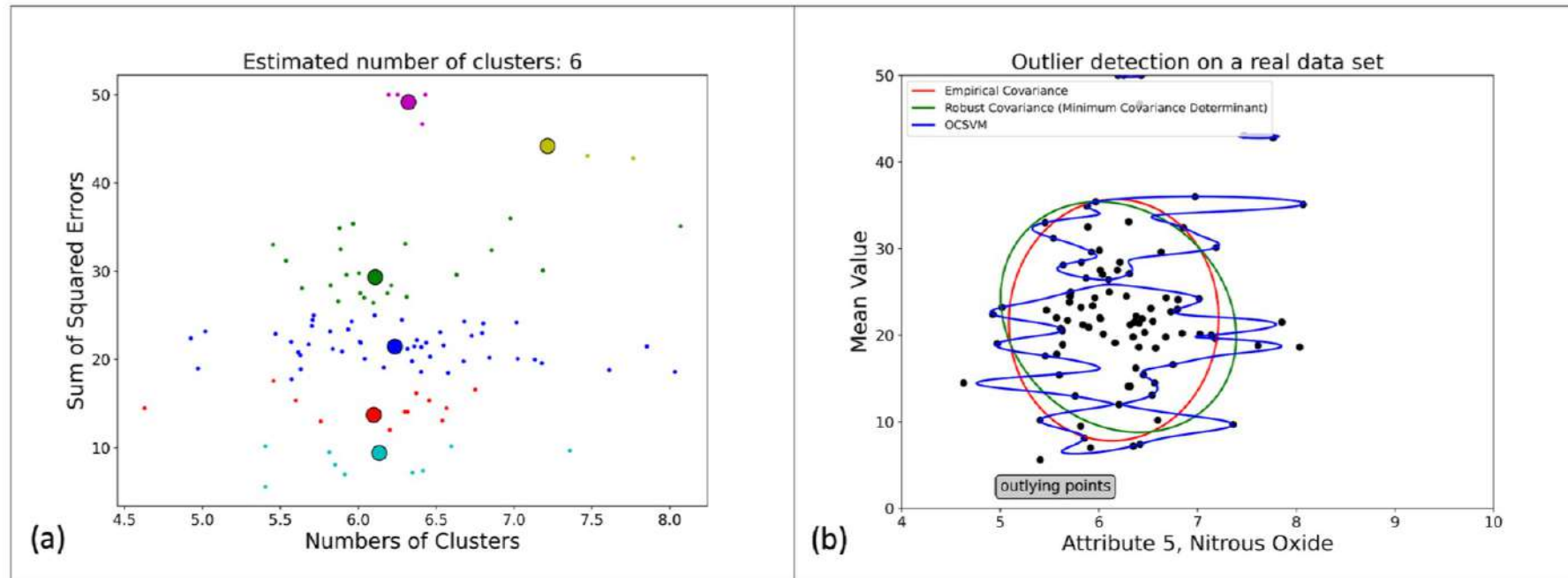
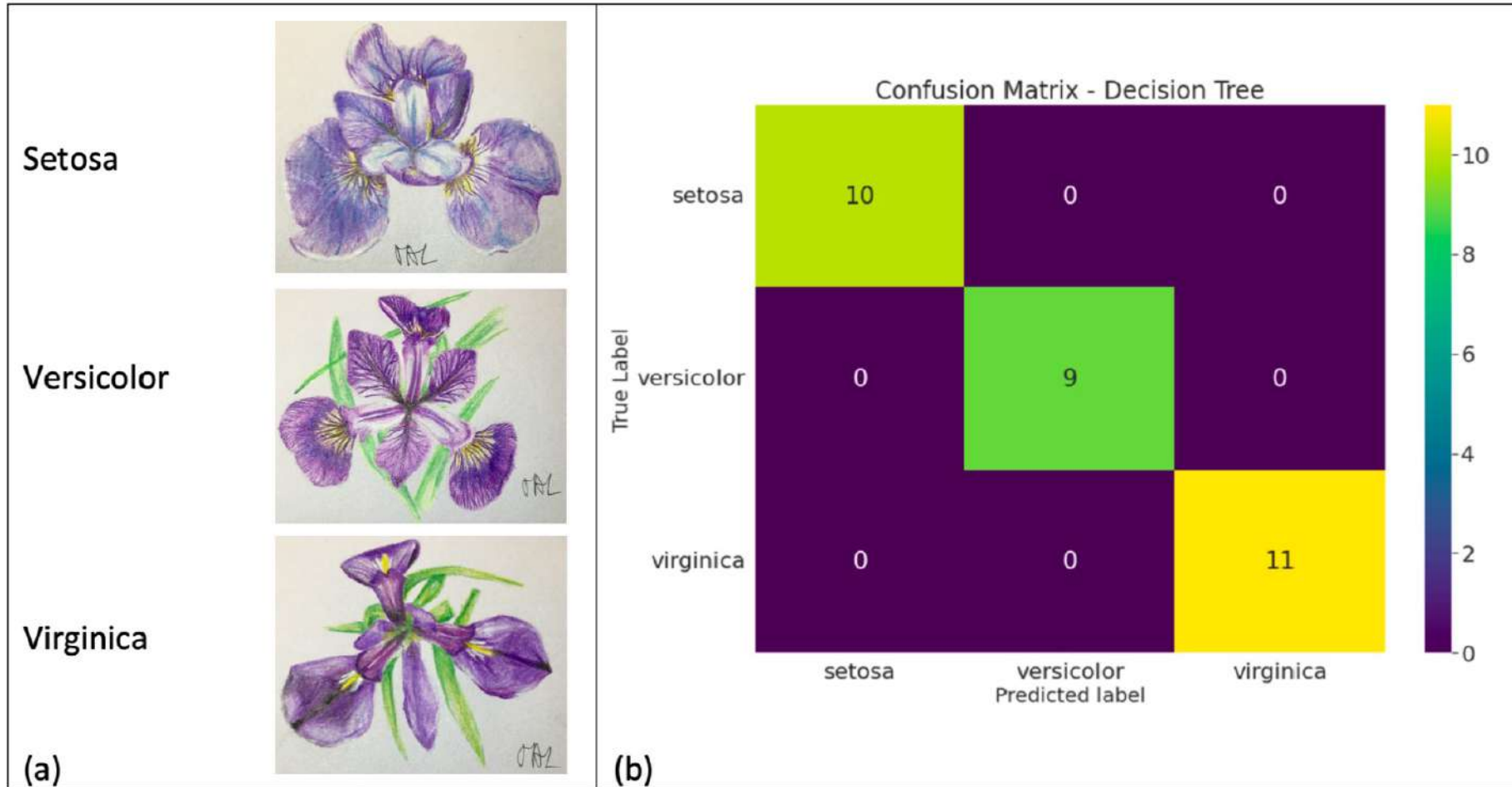
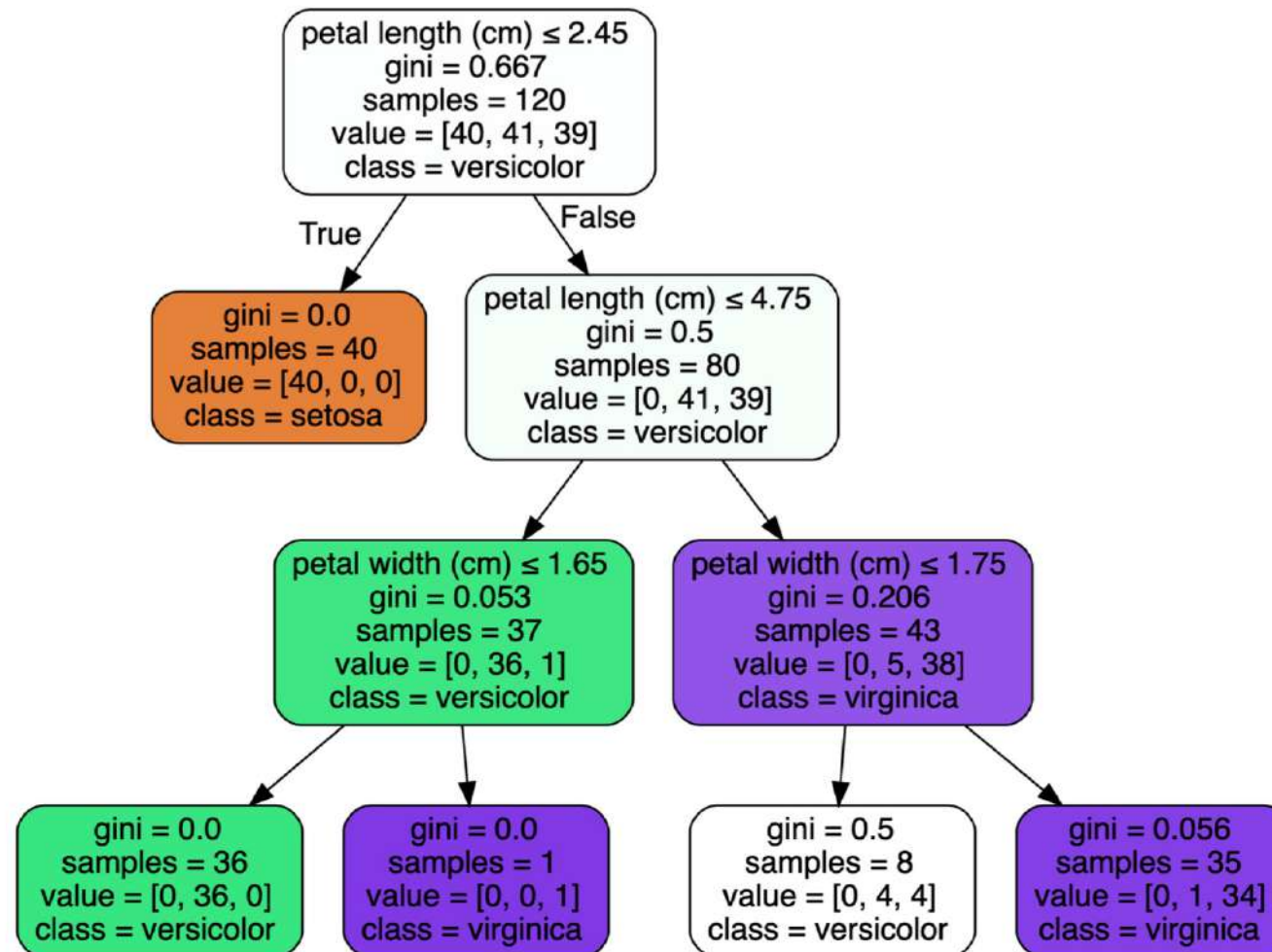


Figure 8.4 (a) Six cluster sets from the mean shift clustering algorithm. (b) Envelope curves for empirical covariance, robust covariance, and OCSVM, to detect rare events.

Data Science: Decision Trees: Predicting Species of Iris



Decision Trees: Predicting Species of Iris: Program_8h.py: End Session 3



Economics: Cobb Douglas Quantity of Production Model: Session 4

Microeconomics: Minimize cost and maximize quantity of product.

Consider a manufacturer of steel cans:

Quantity of product:

$$Q(L, K) = 200L^{\frac{2}{3}}K^{\frac{1}{3}}$$

Cost of construction:

$$C(L, K) = 20L + 750K,$$

where L is labour and K is capital.

Use Lagrange multipliers.

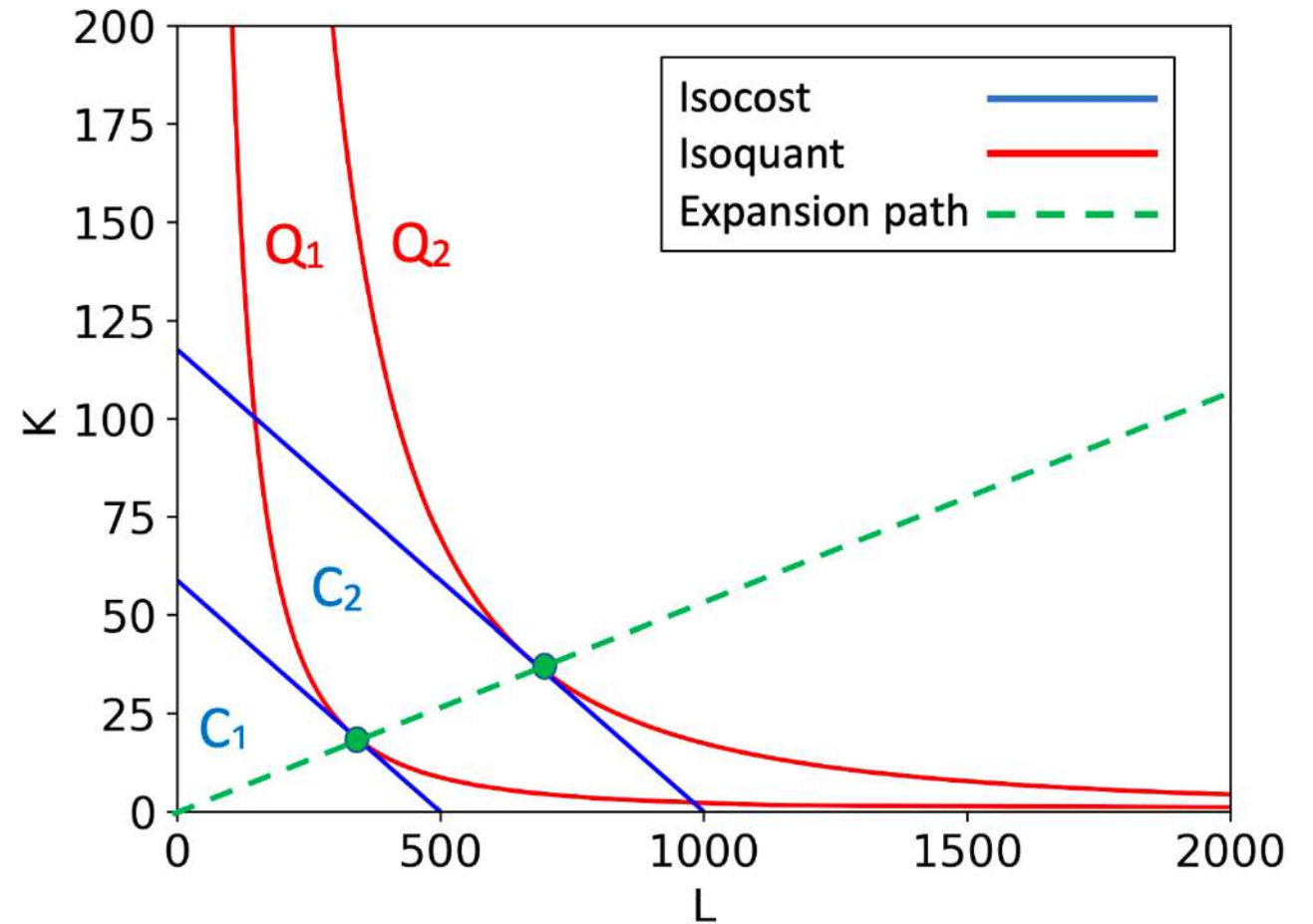


Fig. Isocost-isoquant graph.

Economics: Cobb Douglas Quantity of Production Model

```
# Program_9a.py: Cobb-Douglas Model of Production.
```

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
from sympy import symbols , diff , solve
```

```
L,K,lam=symbols("L K lam")
```

```
Lmax , Kmax = 2000 , 200
```

```
w , r = 20 , 170
```

```
Y = 200*L**(2/3)*K**(1/3)
```

```
C=10000
```

```
Lagrange=Y-lam*(w*L+r*K-C)
```

```
L1 = diff(Lagrange,L)
```

```
L2 = diff(Lagrange,K)
```

```
L3 = w*L+r*K-C
```

```
sol=solve([L1,L2,L3],L,K,lam)
```

```
Y1 = 200*sol[0][0]**(2/3)*sol[0][1]**(1/3)
```

```
C=20000
```

```
Lagrange=Y-lam*(w*L+r*K-C)
```

```
L1 = diff(Lagrange,L)
```

```
L2 = diff(Lagrange,K)
```

```
L3 = w*L+r*K-C
```

```
sol=solve([L1,L2,L3],L,K,lam)
```

```
Y2 = 200*sol[0][0]**(2/3)*sol[0][1]**(1/3)
```

```
Llist = np.linspace(0,Lmax, 1000)
```

```
Klist = np.linspace(0, Kmax, 120)
```

```
L, K = np.meshgrid(Llist, Klist)
```

```
plt.figure()
```

```
Z = 200*L**(2/3)*K**(1/3)
```

```
plt.contour(L,K,Z,[Y1,Y2],colors="red")
```

```
Z = 20*L+170*K
```

```
plt.contour(L,K,Z,[10000,20000],colors="blue")
```

```
plt.xlabel("L",fontsize=15)
```

```
plt.ylabel("K",fontsize=15)
```

```
plt.tick_params(labelsize=15)
```

```
plt.show()
```

Macroeconomics

The ODE is:

$$\frac{dk}{dt} = s(f(k(t))) - (n + \delta + g)k(t),$$

where k is capital intensity, s is the savings rate, n is population growth, δ is depreciation and g is technological progress.

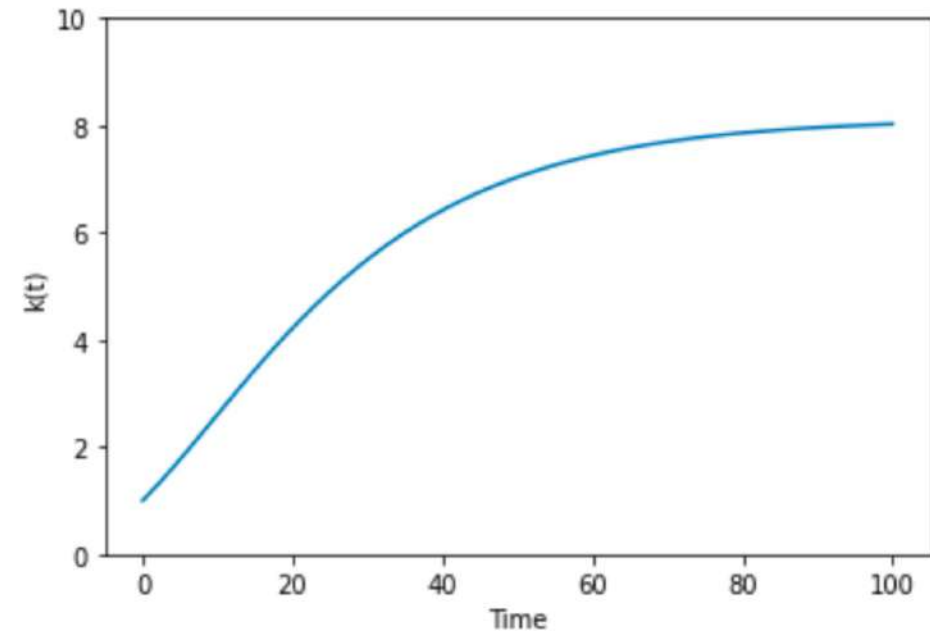
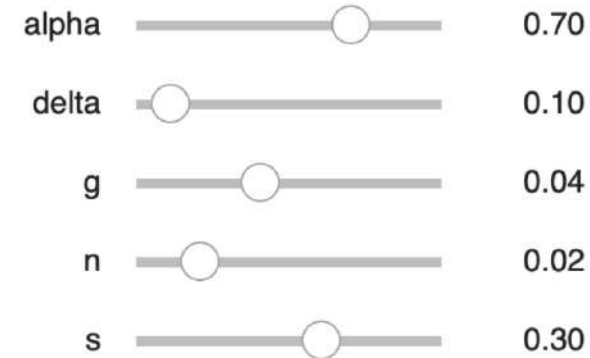
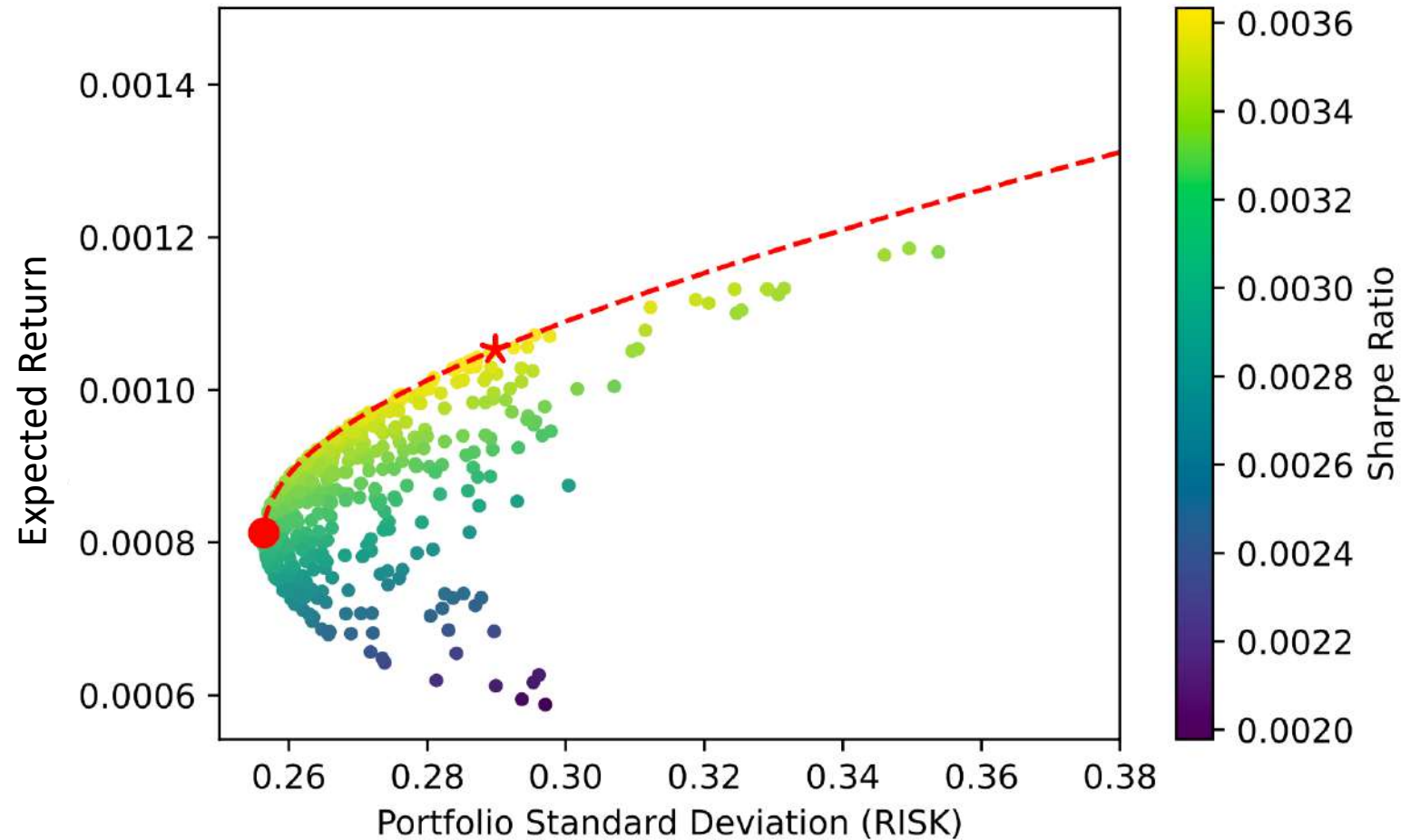


Fig. Interactive plot.

Load financial datasets using Yahoo Finance. The three stocks Apple, Caterpillar and Google are used in this example.

- Pension fund manager – minimize risk
- ★ Hedge fund manager – best risk-reward combination.



Economics: The Black-Scholes Model: Program_9d.py: End of Session 4

```
# Program_9d.py: Black-Scholes Option Prices for Call/Put.
# Computing the Black-Scholes Greeks.
import numpy as np
from scipy.stats import norm
# Parameters: r=interest rate,S=underlying price ($),Strike price ($),
#T=240/365 days, sigma=volatility, C=CALL, P=PUT.
r , S , K , T , sigma = 0.01 , 30 , 40 , 240/365 , 0.3
def Black_Scholes(r,S,K,T,sigma,type="C"):
    d1 = (np.log(S/K)+(r+sigma**2/2)*T)/(sigma*np.sqrt(T))
    d2 = d1 - sigma*np.sqrt(T)
    try:
        if type=="C":
            price=S*norm.cdf(d1,0,1)-K*np.exp(-r*T)*norm.cdf(d2,0,1)
            delta_calc=norm.cdf(d1,0,1)
            gamma_calc=norm.pdf(d1,0,1)/(S*sigma*np.sqrt(T))
            vega_calc=S*norm.pdf(d1,0,1)*np.sqrt(T)*0.01
            theta_calc=(-S*norm.pdf(d1,0,1)*sigma/(2*np.sqrt(T))-\\
                r*K*np.exp(-r*T)*norm.cdf(d2,0,1)) / 365
            rho_calc=K*T*np.exp(-r*T)*norm.cdf(d2,0,1)*0.01
        elif type=="P":
            price=K*np.exp(-r*T)*norm.cdf(-d2,0,1)-S*norm.cdf(-d1,0,1)
            delta_calc=-norm.cdf(-d1,0,1)
            gamma_calc=norm.pdf(d1,0,1)/(S*sigma*np.sqrt(T))
            vega_calc=S*norm.pdf(d1,0,1)*np.sqrt(T) * 0.01
            theta_calc=(-S*norm.pdf(d1,0,1)*sigma/(2*np.sqrt(T))-\\
                r*K*np.exp(-r*T)*norm.cdf(-d2,0,1)) / 365
            rho_calc=-K*T*np.exp(-r*T)*norm.cdf(-d2,0,1) * 0.01
        return [price,delta_calc,gamma_calc,vega_calc,theta_calc,rho_calc]
    except:
        print("Please input correct parameters")
BS_Call=Black_Scholes(r,S,K,T,sigma,type="C")
BS_Put=Black_Scholes(r,S,K,T,sigma,type="P")
print("r=",r,"S=",S,"K=",K,"T=",T,"sigma=",sigma)
print("Option CALL price is: ", round(BS_Call[0],2))
```

```
print("Option PUT price is: ", round(BS_Put[0],2))
print("delta Call is: ", round(BS_Call[1],4))
print("delta Put is: ", round(BS_Put[1],4))
print("gamma Call/Put is: ", round(BS_Call[2],4))
print("vega Call/Put is: ", round(BS_Call[3],4))
print("theta Call is: ", round(BS_Call[4],4))
print("theta Put is: ", round(BS_Put[4],4))
```

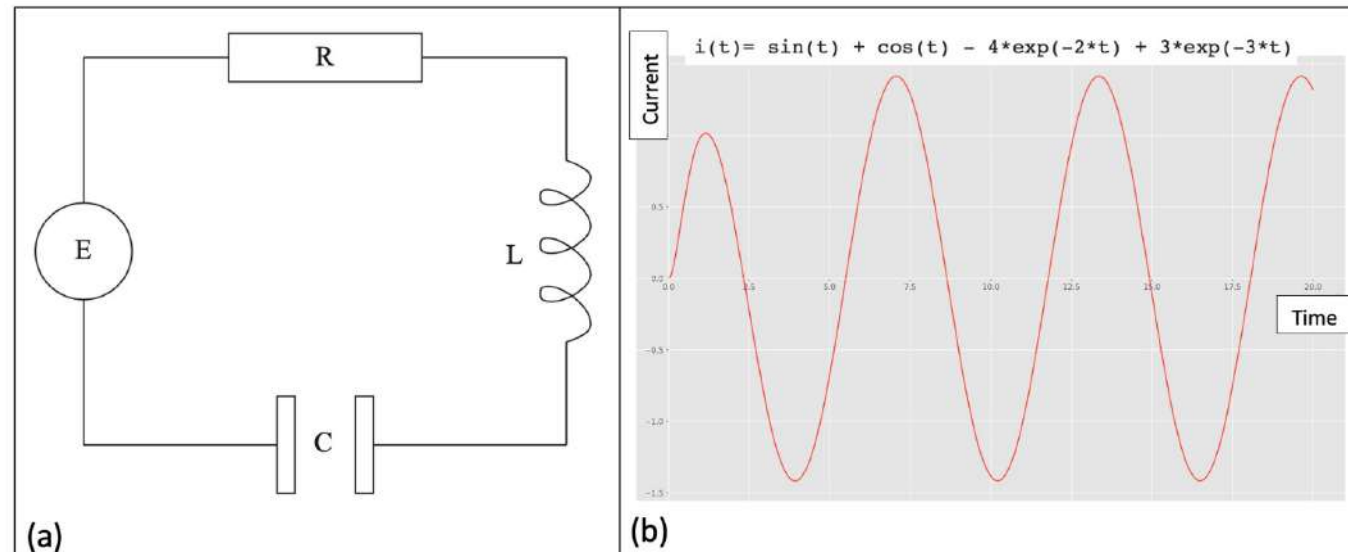
The Black-Scholes partial differential equation describing the price of a European call or put option over time.

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0$$

where V is the price of the option as a function of stock price S and time t , r is risk-free interest rate, and σ is the volatility of the stock.

Engineering: Linear Electric Circuits: Resistor-Inductor-Capacitor: Session 5

```
# Program_10a.py: Current in a Resistor-Inductor-Capacitor circuit.  
from sympy import symbols , diff , Eq , Function , dsolve , cos , plot  
from matplotlib import style  
t=symbols("t")  
i=symbols("i",cls=Function)  
deqn1=Eq(i(t).diff(t,t) + 5*i(t).diff(t) + 6*i(t), 10*cos(t))  
odesol1=dsolve(deqn1, i(t),ics={i(0): 0, diff(i(t), t).subs(t,0): 0})  
print("i(t)=",odesol1.rhs)  
style.use("ggplot")  
plot(odesol1.rhs , (t , 0 , 20),xlabel = "Time", ylabel = "Current")
```



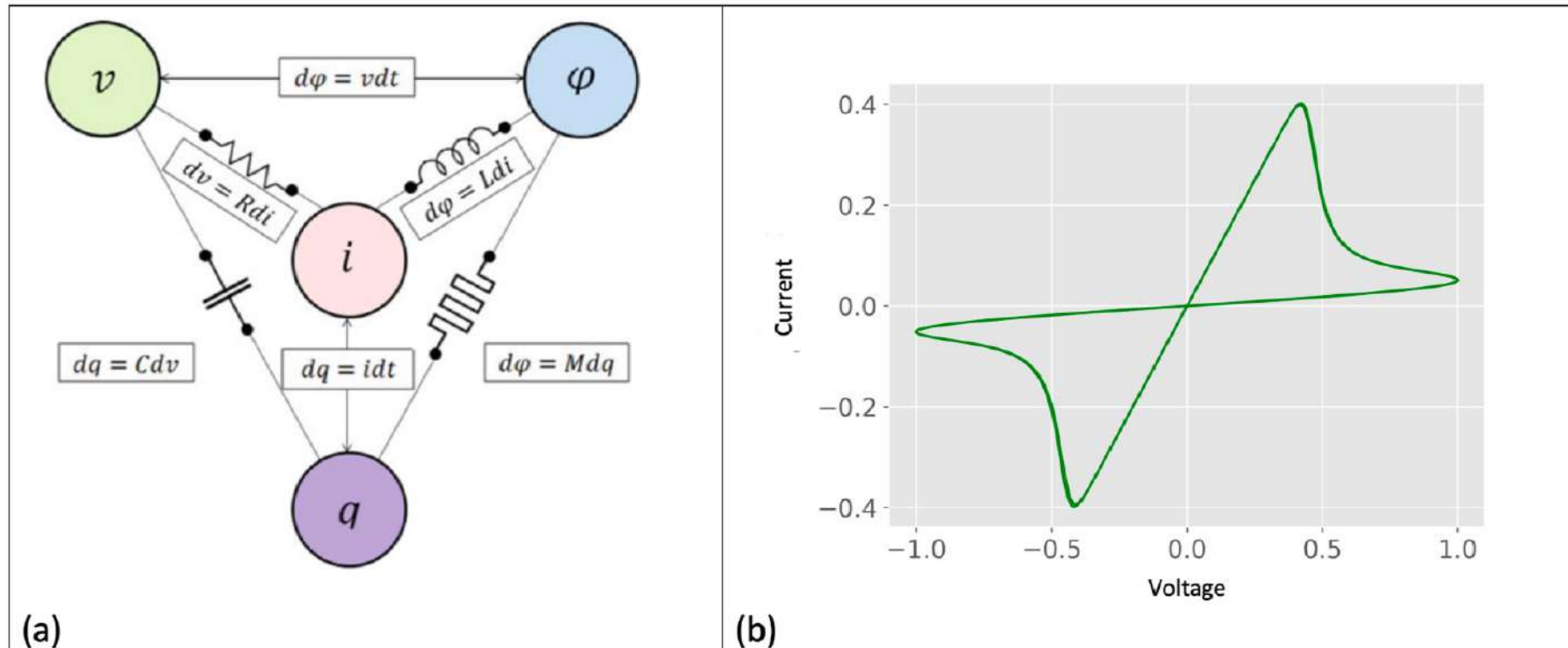


Figure 10.2 (a) Relations between voltage v , flux ϕ , current i , and charge q . (b) Pinched hysteresis curve when $\omega_0 = 0.6$.

Nonlinear Electric Circuits: Chua's Circuit: Program_10c.py

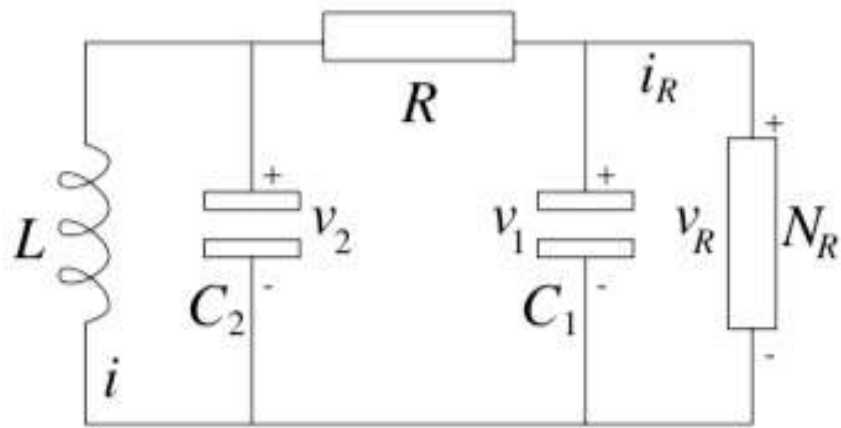


Figure 8.13: Chua's electric circuit.

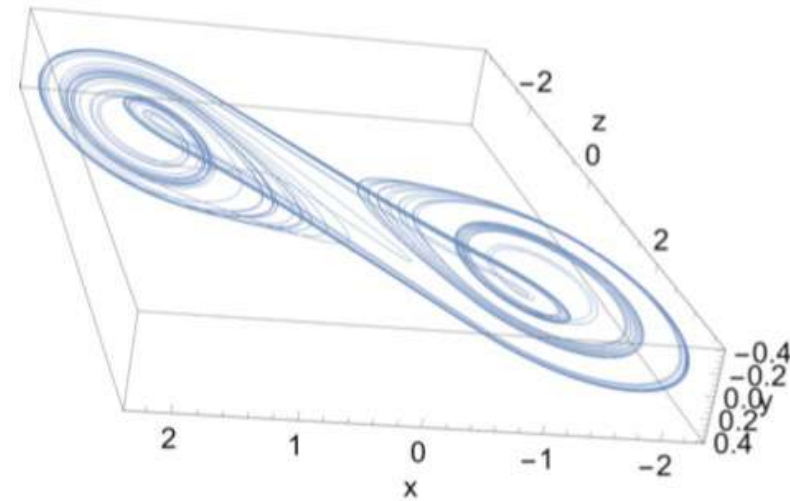
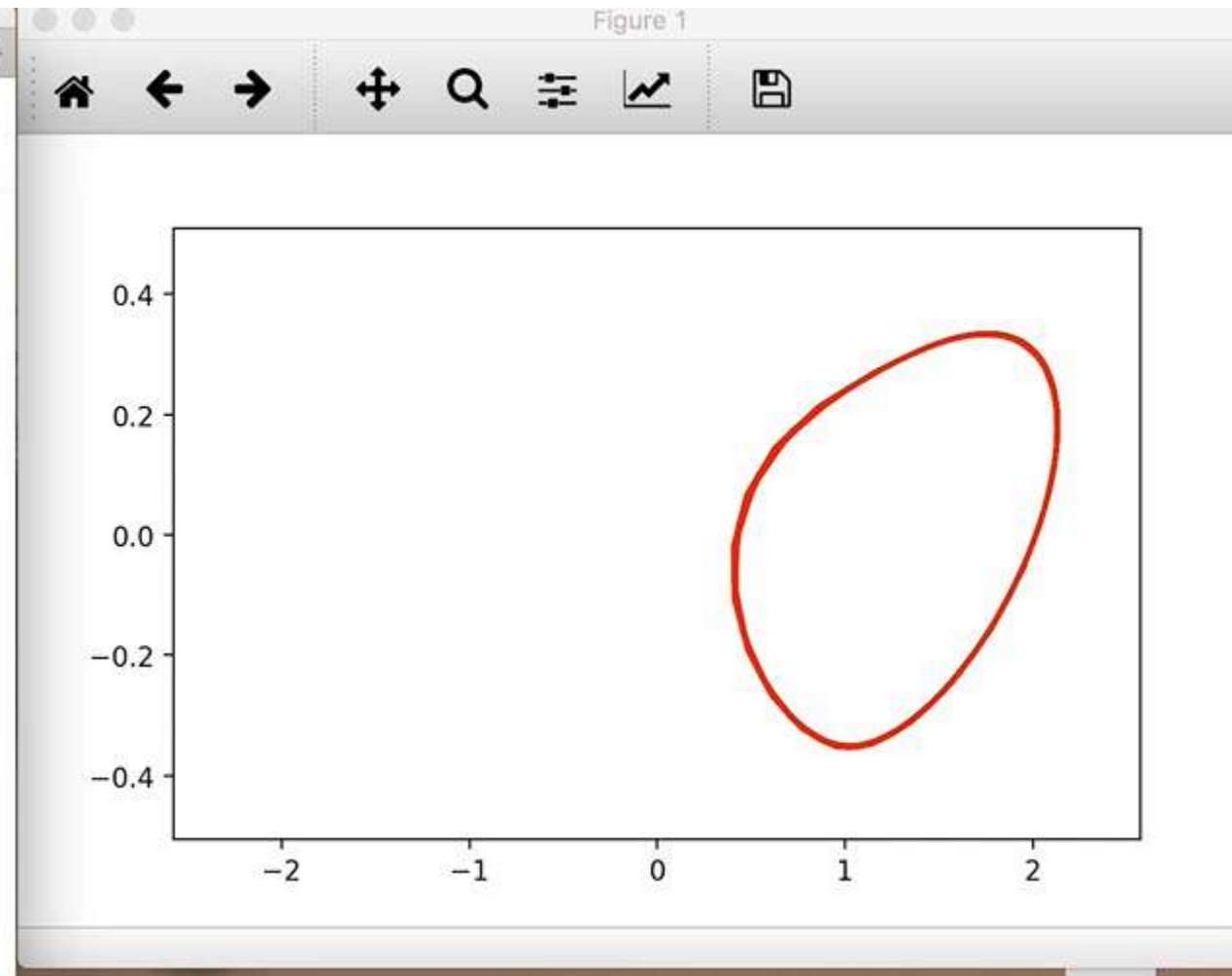
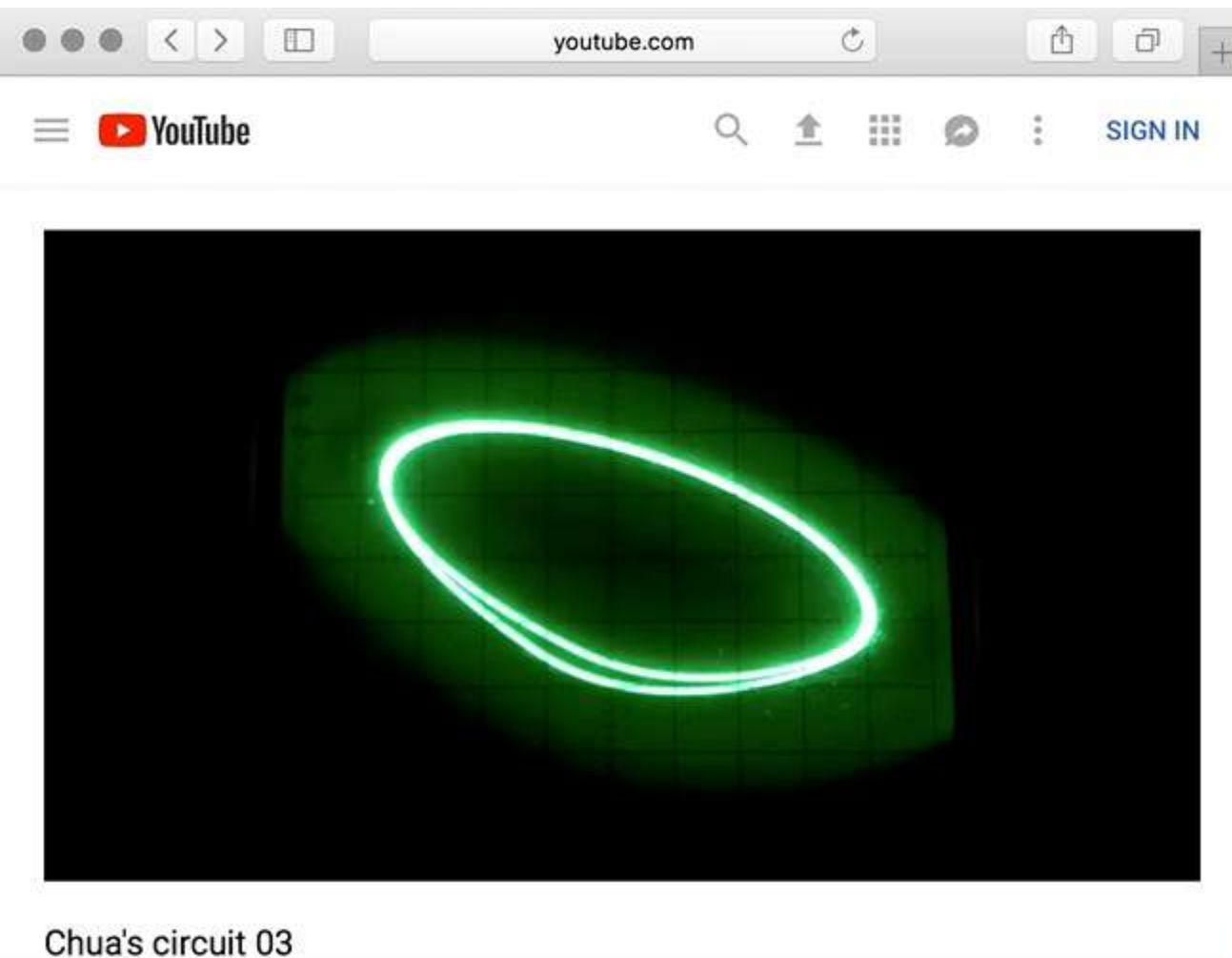


Figure 8.14: [Python animation] Chua's double-scroll attractor: Phase portrait for system (8.9) when $a = 15$, $b = 25.58$, $c = -5/7$, and $d = -8/7$. The initial conditions are $x(0) = -1.6$, $y(0) = 0$, and $z(0) = 1.6$.

Chua Circuit Animation

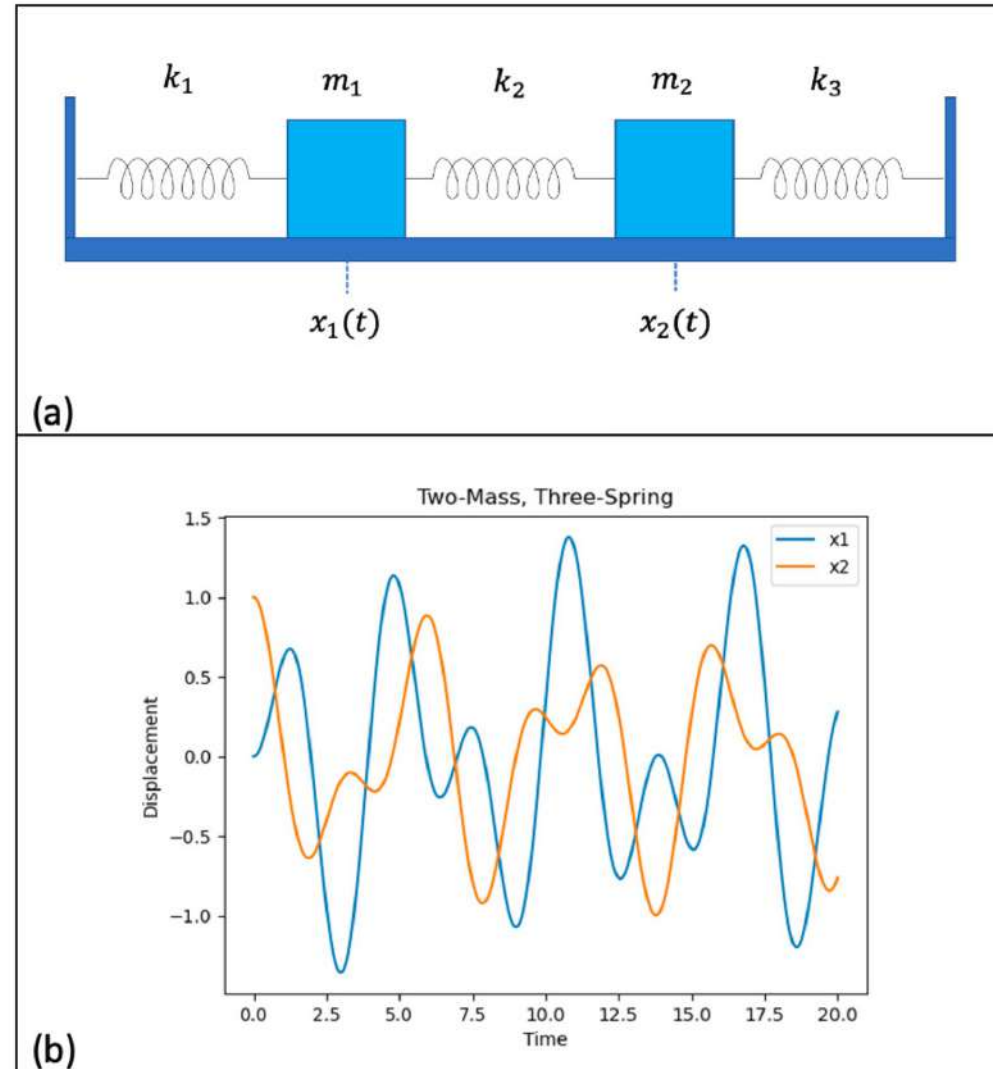


$$\dot{x}_1 = y_1,$$

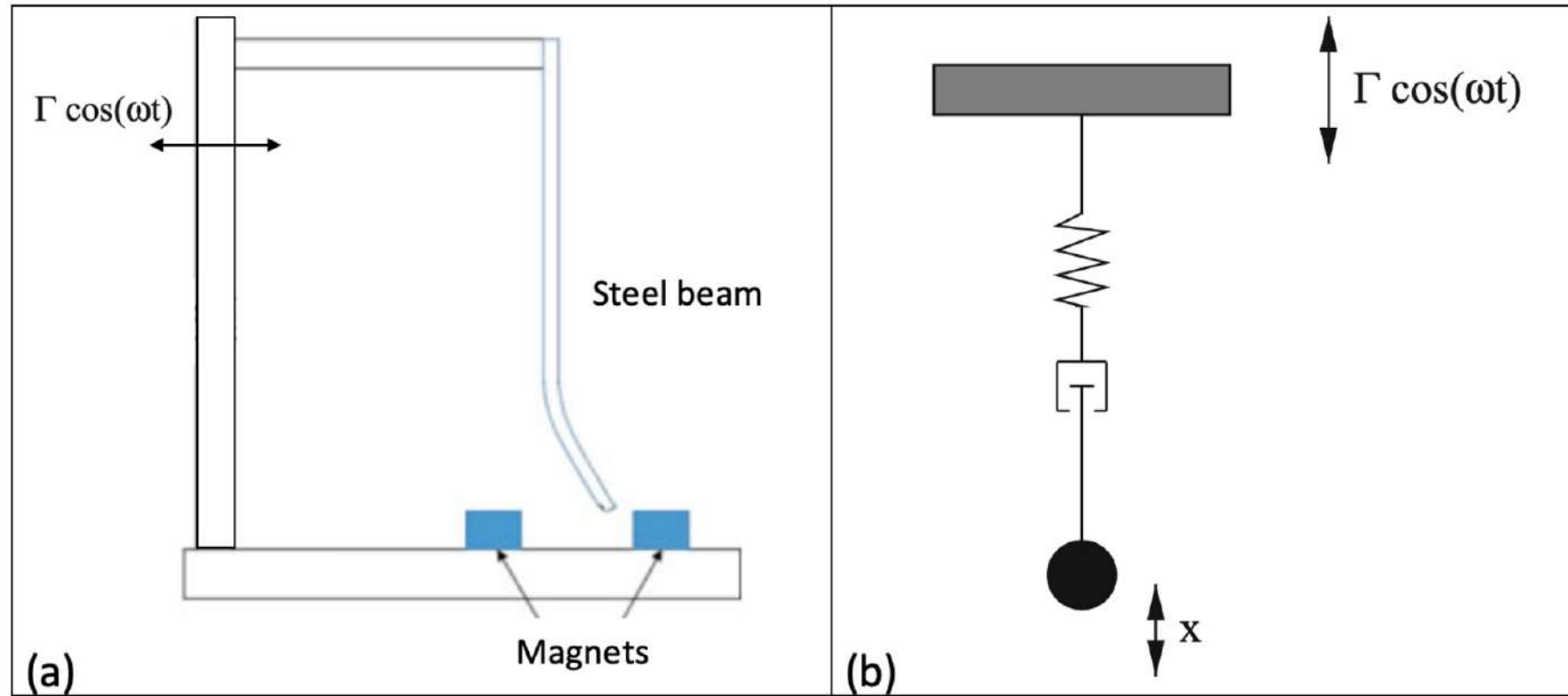
$$\dot{y}_1 = -\frac{1}{m_1} (k_1 x_1 + k_2 (x_1 - x_2)),$$

$$\dot{x}_2 = y_2,$$

$$\dot{y}_2 = \frac{1}{m_2} (k_2 (x_2 - x_1) + k_3 x_2),$$



Engineering: Periodically Forced Systems: Program_10e.py



Engineering: Periodically Forced Systems: Bifurcation Diagram

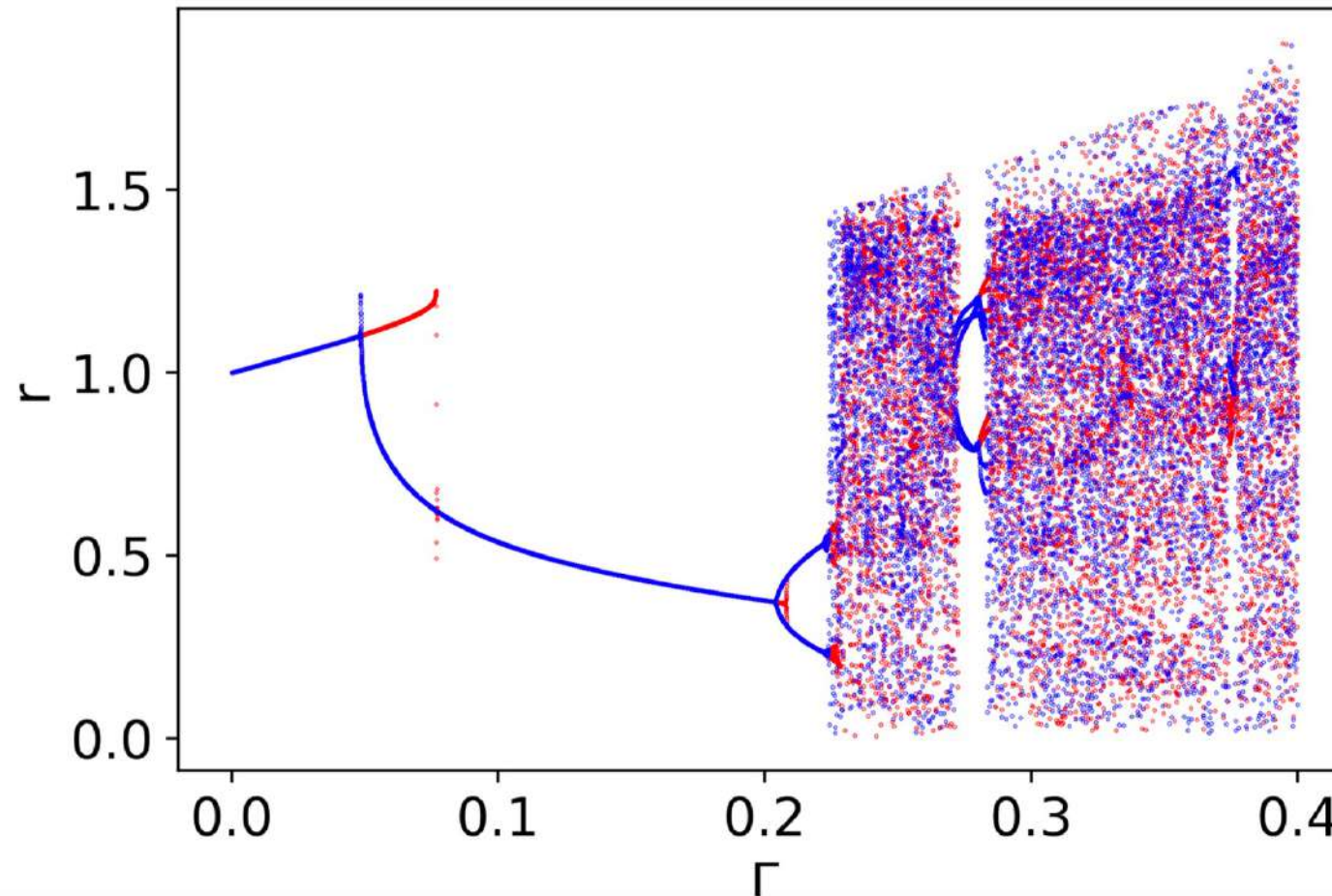


Fig. Bifurcation diagram showing a clockwise hysteresis loop as the amplitude of forcing is increased and decreased.

Hysteresis in the Periodically Driven Two-Bar Linkage

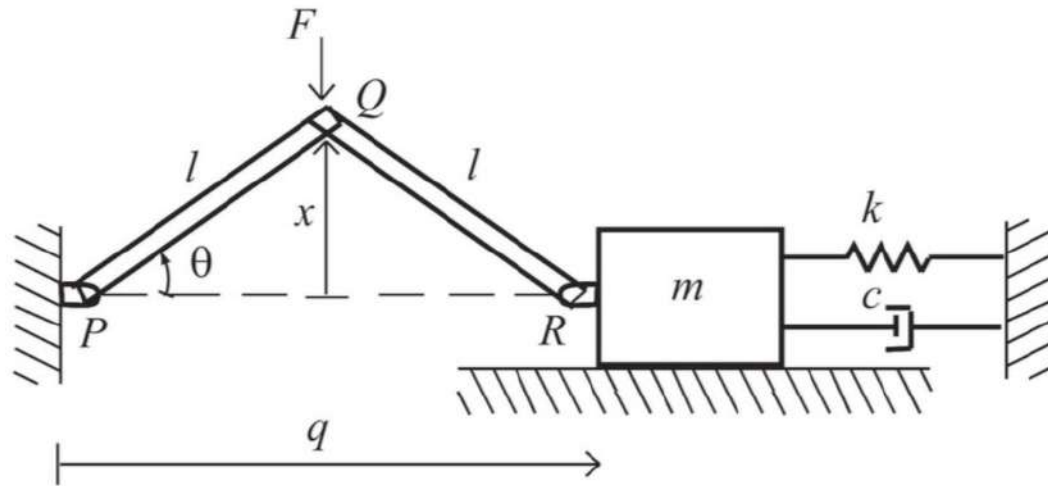
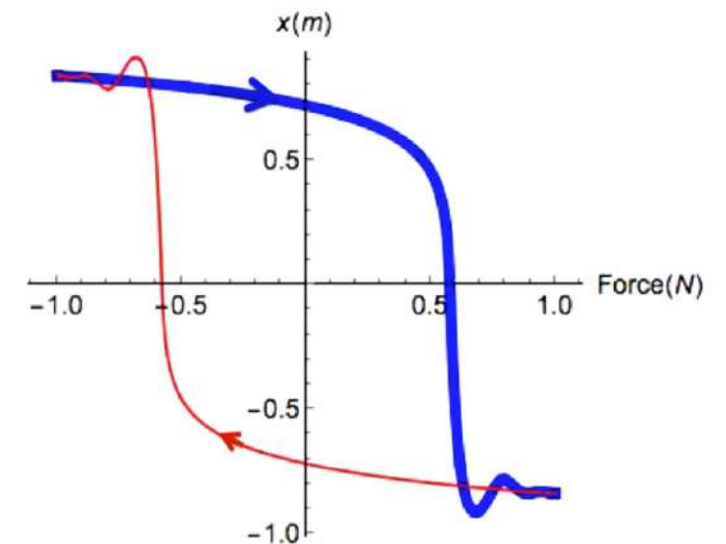
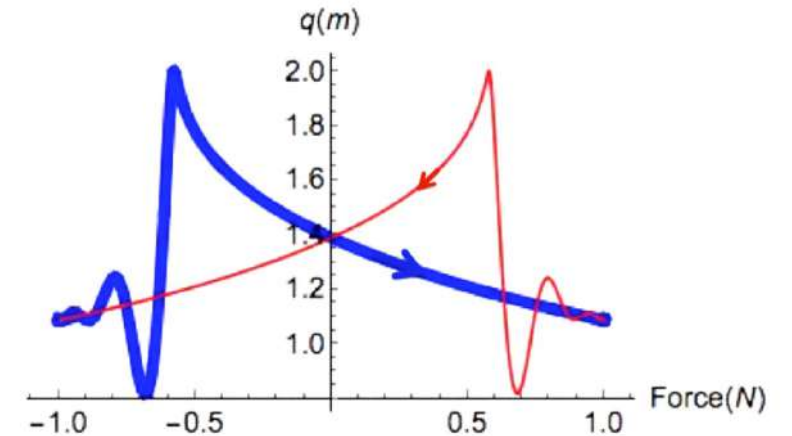
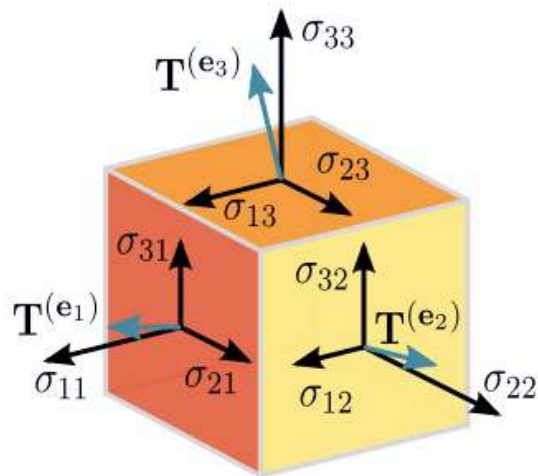


Figure: The preloaded two-bar linkage with a periodic force F acting at the joint Q . As the point Q moves vertically up and down, the mass m moves horizontally left and right.



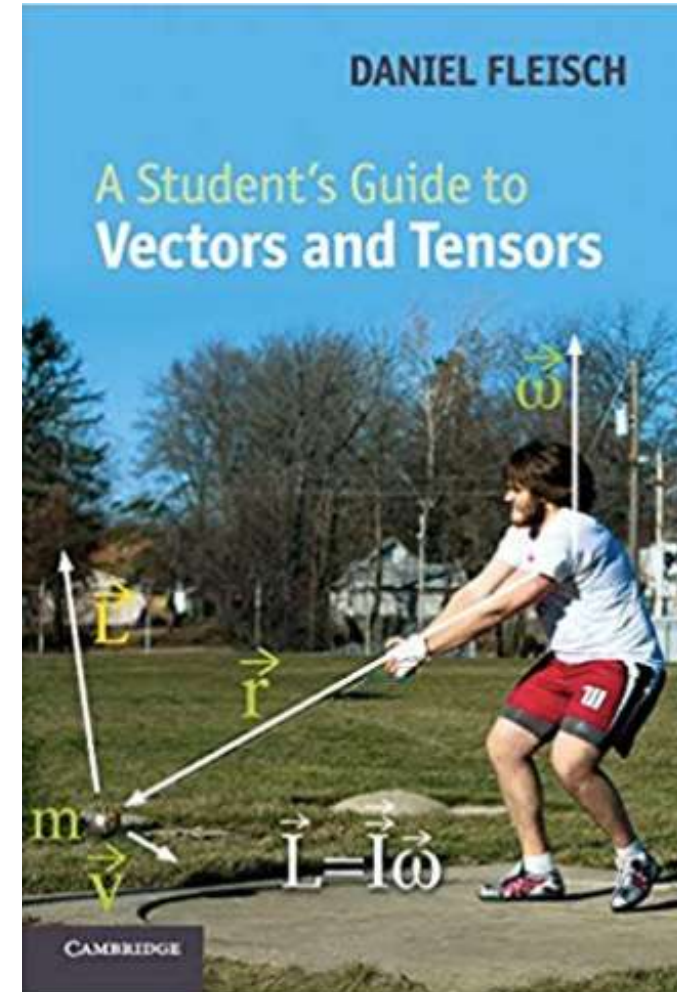
Tensors

Definition: An n 'th rank tensor in m -dimensional space is a mathematical object that has n indices and m^n components and obeys certain transformation rules.



Cauchy stress tensor.

Tensors have applications in Riemannian geometry, mechanics, elasticity, theory of relativity, electromagnetic theory and artificial intelligence, for example.



Tensors in Artificial Intelligence

Definition: An n 'th rank tensor in m -dimensional space is a mathematical object that has n indices and m^n components and obeys certain transformation rules.

3 is a scalar and rank 0 tensor

[1,2,3] is a vector and rank 1 tensor

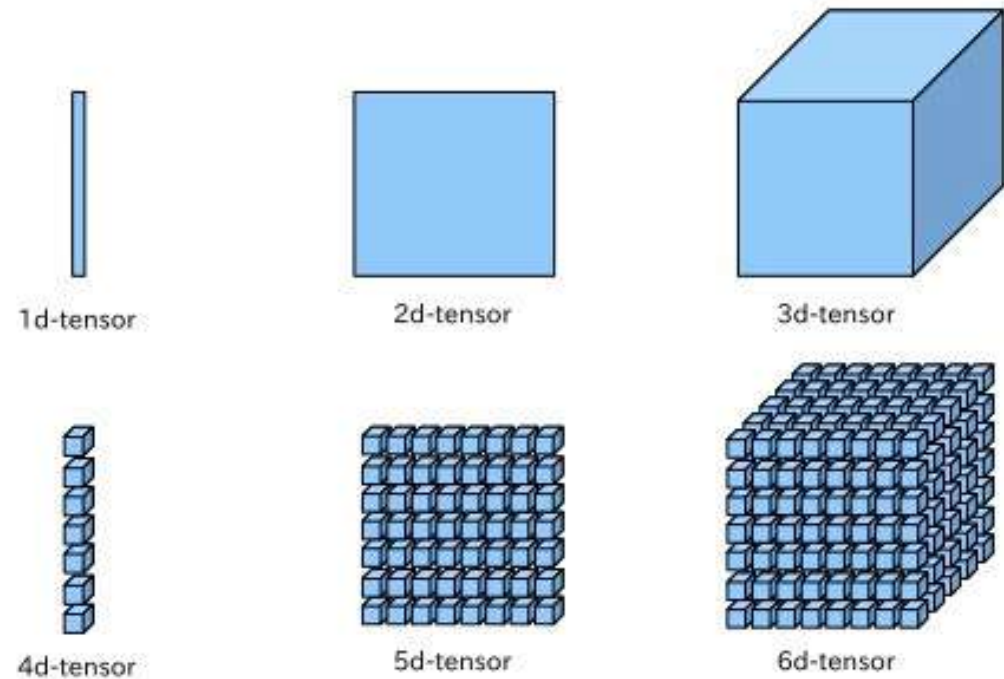
[[1,2,3],[4,5,6],[7,8,9]] is an array and rank 2 tensor

[[[1,2],[3,4]],[[5,6],[7,8]]] is an array and rank 3 tensor

In Deep Learning:

Images are represented by tensors of rank 4

Videos are represented by tensors of rank 5



Tensors and Python

```
In [1]: import numpy as np
```

```
In [2]: A = np.array([1,2,3,4])
```

```
In [3]: A.shape
```

```
Out[3]: (4,)
```

```
In [4]: A.ndim
```

```
Out[4]: 1
```

```
In [1]: import numpy as np
```

```
In [2]: T = np.array([  
...:   [[1,2,3],[4,5,6],[7,8,9]],  
...:   [[11,12,13],[14,15,16],[17,18,19]],  
...:   [[21,22,23],[24,25,26],[27,28,29]],  
...:   ])
```

```
In [3]: T.shape
```

```
Out[3]: (3, 3, 3)
```

```
In [4]: T.ndim
```

```
Out[4]: 3
```

Tensors and Python: End Session 5

There are a number of ways to multiply tensors, for example:

```
In [1]: import numpy as np
```

```
In [2]: A = np.array([[1,2],[3,4]])
```

```
In [3]: B = np.array([[5,6],[7,8]])
```

```
In [4]: A * B
```

```
Out[4]:  
array([[ 5, 12],  
       [21, 32]])
```

```
In [5]: C=np.tensordot(A,B, axes=1)
```

```
In [6]: print(C)
```

```
[[19 22]  
 [43 50]]
```

```
In [7]: C=np.tensordot(A,B, axes=0)
```

```
In [8]: print(C)
```

```
[[[ 5  6]  
  [ 7  8]]
```

```
  [[10 12]  
   [14 16]]]
```

```
  [[[15 18]  
   [21 24]]
```

```
  [[20 24]  
   [28 32]]]]
```

```
In [9]: C.shape
```

```
Out[9]: (2, 2, 2, 2)
```

```
In [10]: C.ndim
```

```
Out[10]: 4
```

Day 2 Summary

Day 2			
Jupyter and Colab Notebooks	10am-11am	Economics	2pm-3pm
Biology and Chemistry	11am-12pm	Engineering	3pm-4pm
Data Science	12pm-1pm		

Download all files from GitHub:

<https://github.com/proflynch/CRC-Press/>

Solutions to the Exercises in Section 2:

https://drstephenlynch.github.io/webpages/Solutions_Section_2.html

